



Coupled Coincidence Points for Monotone Operators in S -Metric Spaces

Somkiat Chaipornjareansri

Department of Mathematics, Faculty of Science
Lampang Rajabhat University, Lampang 52100, Thailand
e-mail : somkiat.chai@gmail.com

Abstract : The aim of this paper is to establish some coupled coincidence point results in S -metric space by using the notion of compatible mappings in the setting of a partially ordered S -metric space. We prove the existence and uniqueness of coupled coincidence points involving a (φ, ψ) -contractive condition for a mappings having the mixed g -monotone property.

Keywords : S -metric space; partially ordered S -metric space; coupled coincidence point; mixed g -monotone property.

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1 Introduction

Metric spaces have very wide applications in mathematics and applied sciences. For this, many authors tried to give definitions of metric spaces in many ways. In 1966, Gahler [1, 2] introduced the notion of 2-metric spaces and Dhage [3] introduced the notion of D -metric spaces. After the introduction of these metric spaces many authors proved some fixed point results related to these metric spaces. In 2006, Mustafa and Sims [4] proved that most of the results of Dhage's D -metric spaces are not valid. So, they introduced the new concept of generalized metric space called G -metric

space and gave some remarkable results in G -metric spaces. In 2012, Sedghi et al. [5] introduced the notion of S -metric spaces as the generalization of G -metric and D^* -metric spaces.

The notion of a coupled fixed point was introduced and studied by Opoitsev [6–8] and then by Guo and Lakshmikantham [9]. Bhashkar and Lakshmikantham in [10] introduced the concept of a coupled fixed point of a mapping $F : X \times X \rightarrow X$ and investigated some coupled fixed point theorems in partially ordered complete metric spaces. They also discussed an application of their result by investigating the existence and uniqueness of solution for a periodic boundary value problem. Choudhury and Kundu [11] obtained coupled coincidence point results in partially ordered metric spaces for compatible mappings.

Lakshmikantham and Ćirić [12] defined a mixed g -monotone mapping and prove coupled coincidence and coupled common fixed point theorems for such nonlinear contractive mappings in partially ordered complete metric spaces. In 2011 Alotaibi and Alsulami [13] proved the existence and uniqueness of coupled coincidence point involving a (φ, ψ) -contractive condition for a mappings having the mixed g -monotone property.

2 Preliminaries

We begin with the following definition:

Definition 2.1. [5] Let X be a nonempty set. An S -metric on X is a function $S : X^3 \rightarrow [0, \infty)$ that satisfies the following conditions, for each $x, y, z, a \in X$.

- (i) $S(x, y, z) \geq 0$;
- (ii) $S(x, y, z) = 0$ if and only if $x = y = z$;
- (iii) $S(x, y, z) \leq S(x, x, a) + S(y, y, a) + S(z, z, a)$.

Then the pair (X, S) is called an S -metric space.

The following is an intuitive geometric example for S -metric spaces.

Example 2.2. [5] Let $X = \mathbb{R}^2$ and d be an ordinary metric on X . Put

$$S(x, y, z) = d(x, y) + d(x, z) + d(y, z)$$

for all $x, y, z \in \mathbb{R}^2$, that is, S is the perimeter of the triangle given by x, y, z . Then S is an S -metric on X .

Lemma 2.3. [5] *Let (X, S) be an S -metric space. Then $S(x, x, y) = S(y, y, x)$ for all $x, y \in X$.*

Lemma 2.4. *Let (X, S) be an S -metric space. Then*

$S(x, x, z) \leq 2S(x, x, y) + S(y, y, z)$ and $S(x, x, z) \leq 2S(x, x, y) + S(z, z, y)$ for all $x, y, z \in X$.

Proof. It is a direct consequence of Definition 2.1 and Lemma 2.4. \square

Definition 2.5. [5] *Let (X, S) be an S -metric space.*

- (i) A sequence $\{x_n\} \subset X$ is said to *converge to* $x \in X$ if $S(x_n, x_n, x) \rightarrow 0$ as $n \rightarrow \infty$. That is, for each $\varepsilon > 0$, there exists $n_0 \in \mathbb{N}$ such that for all $n \geq n_0$ we have $S(x_n, x_n, x) < \varepsilon$. We write $x_n \rightarrow x$ for brevity.
- (ii) A sequence $\{x_n\} \subset X$ is called a *Cauchy sequence* if $S(x_n, x_n, x_m) \rightarrow 0$ as $n, m \rightarrow \infty$. That is, for each $\varepsilon > 0$, there exists $n_0 \in \mathbb{N}$ such that for all $n, m \geq n_0$ we have $S(x_n, x_n, x_m) < \varepsilon$.
- (iii) The S -metric space (X, S) is said to be *complete* if every Cauchy sequence is a convergent sequence.

Lemma 2.6. [5] *Let (X, S) be an S -metric space. If $x_n \rightarrow x$ and $y_n \rightarrow y$, then $S(x_n, x_n, y_n) \rightarrow S(x, x, y)$.*

Definition 2.7 ([12], Mixed g -Monotone Property). Let (X, \leq) be a partially ordered set and $F : X^2 \rightarrow X$. We say that the mapping F has the *mixed g -monotone property* if F is monotone g -non-decreasing in its first argument and is monotone g -non-increasing in its second argument. That is, for any $x, y \in X$,

$$\begin{aligned} x_1, x_2 \in X, gx_1 \leq gx_2 &\Rightarrow F(x_1, y) \leq F(x_2, y) \\ y_1, y_2 \in X, gy_1 \leq gy_2 &\Rightarrow F(x, y_1) \geq F(x, y_2). \end{aligned} \quad (2.1)$$

Definition 2.8 (Coupled Coincidence Point). Let $(x, y) \in X \times X$, $F : X^2 \rightarrow X$ and $g : X \rightarrow X$. We say that (x, y) is a *coupled coincidence point* of F and g if $F(x, y) = gx$ and $F(y, x) = gy$ for $x, y \in X$.

Definition 2.9. The mapping F and g where $F : X^2 \rightarrow X$ and $g : X \rightarrow X$, are said to be *compatible* if

$$\lim_{n \rightarrow \infty} S(g(F(x_n, y_n)), g(F(x_n, y_n)), F(gx_n, gy_n)) = 0$$

and

$$\lim_{n \rightarrow \infty} S(g(F(y_n, x_n)), g(F(y_n, x_n)), F(gy_n, gx_n)) = 0,$$

whenever $\{x_n\}$ and $\{y_n\}$ are sequences in X , such that $\lim_{n \rightarrow \infty} F(x_n, y_n) = \lim_{n \rightarrow \infty} gx_n = x$ and $\lim_{n \rightarrow \infty} F(y_n, x_n) = \lim_{n \rightarrow \infty} gy_n = y$, for all $x, y \in X$ are satisfied.

3 Existence of Coupled Coincidence Points

Let Φ denote all functions $\varphi : [0, \infty) \rightarrow [0, \infty)$ which satisfy

- (1) φ continuous and non-decreasing;
- (2) $\varphi(t) = 0$ if and only if $t = 0$;
- (3) $\varphi(t + s) \leq \varphi(t) + \varphi(s), \forall t, s \in [0, \infty)$

and let Ψ denote all the functions $\psi : [0, \infty) \rightarrow (0, \infty)$ which satisfy $\lim_{t \rightarrow r} \psi(t) > 0$ for all $r > 0$ and $\lim_{t \rightarrow 0^+} \psi(t) = 0$.

Now, let us start proving our main results.

Theorem 3.1. *Let (X, \leq, S) be a partially ordered complete S -metric space. Let $F : X^2 \rightarrow X$ is such that F has the mixed g -monotone property such that there exists $x_0, y_0 \in X$ with*

$$gx_0 \leq F(x_0, y_0) \quad \text{and} \quad gy_0 \geq F(y_0, x_0).$$

Suppose there exist $\varphi \in \Phi$ and $\psi \in \Psi$ such that

$$\begin{aligned} & \varphi\left(S(F(x, y), F(x, y), F(u, v))\right) \\ & \leq \frac{1}{2}\varphi(S(gx, gx, gu) + S(gy, gy, gv)) - \psi\left(\frac{S(gx, gx, gu) + S(gy, gy, gv)}{2}\right), \end{aligned} \tag{3.1}$$

for all $x, y, u, v \in X$ with $gx \geq gu$ and $gy \leq gv$. Suppose $F(X \times X) \subseteq g(X)$, g is continuous and compatible with F and also suppose either

- (a) F is continuous or
- (b) X has the following property:
 - (i) if a non-decreasing sequence $\{x_n\} \rightarrow x$, then $x_n \leq x$, for all n ,

(ii) if a non-increasing sequence $\{y_n\} \rightarrow y$, then $y_n \geq y$, for all n .

Then there exists $x, y \in X$ such that

$$gx = F(x, y) \quad \text{and} \quad gy = F(y, x),$$

i.e., F and g have a coupled coincidence point in X .

Proof. Let $x_0, y_0 \in X$ be such that $gx_0 \leq F(x_0, y_0)$ and $gy_0 \geq F(y_0, x_0)$. Using $F(X \times X) \subseteq g(X)$, we construct sequences $\{x_n\}$ and $\{y_n\}$ in X as

$$gx_{n+1} = F(x_n, y_n) \quad \text{and} \quad gy_{n+1} = F(y_n, x_n) \quad \text{for all } n \geq 0. \quad (3.2)$$

We are going to prove that

$$gx_n \leq gx_{n+1} \quad \text{for all } n \geq 0 \quad (3.3)$$

and

$$gy_n \geq gy_{n+1} \quad \text{for all } n \geq 0. \quad (3.4)$$

To prove these, we are going to use the mathematical induction.

Let $n = 0$. Since $gx_0 \leq F(x_0, y_0)$ and $gy_0 \geq F(y_0, x_0)$ and as $gx_1 = F(x_0, y_0)$ and $gy_1 = F(y_0, x_0)$, we have $gx_0 \leq gx_1$ and $gy_0 \geq gy_1$. Thus (3.3) and (3.4) hold for $n = 0$.

Suppose now that (3.3) and (3.4) hold for some fixed $n \geq 0$. Then, since $gx_n \leq gx_{n+1}$ and $gy_n \geq gy_{n+1}$, and by mixed g -monotone property of F , we have

$$gx_{n+2} = F(x_{n+1}, y_{n+1}) \geq F(x_n, y_{n+1}) \geq F(x_n, y_n) = gx_{n+1} \quad (3.5)$$

and

$$gy_{n+2} = F(y_{n+1}, x_{n+1}) \leq F(y_n, x_{n+1}) \leq F(y_n, x_n) = gy_{n+1}. \quad (3.6)$$

Using (3.5) and (3.6), we get

$$gx_{n+1} \leq gx_{n+2} \quad \text{and} \quad gy_{n+1} \geq gy_{n+2}.$$

Hence by the mathematical induction we conclude that (3.3) and (3.4) hold for all $n \geq 0$.

Therefore,

$$gx_0 \leq gx_1 \leq gx_2 \leq \cdots \leq gx_n \leq gx_{n+1} \leq \cdots \quad (3.7)$$

and

$$gy_0 \geq gy_1 \geq gy_2 \geq \cdots \geq gy_n \geq gy_{n+1} \geq \cdots . \quad (3.8)$$

Since $gx_n \geq gx_{n-1}$ and $gy_n \leq gy_{n-1}$, using (3.1) and (3.2), we have

$$\begin{aligned} \varphi(S(gx_{n+1}, gx_{n+1}, gx_n)) &= \varphi\left(S(F(x_n, y_n), F(x_n, y_n), F(x_{n-1}, y_{n-1}))\right) \\ &\leq \frac{1}{2}\varphi(S(gx_n, gx_n, gx_{n-1}) + S(gy_n, gy_n, gy_{n-1})) \\ &\quad - \psi\left(\frac{S(gx_n, gx_n, gx_{n-1}) + S(gy_n, gy_n, gy_{n-1})}{2}\right). \end{aligned} \quad (3.9)$$

Similarly, since $gy_{n-1} \geq gy_n$ and $gx_{n-1} \leq gx_n$, using (3.1) and (3.2), we have

$$\begin{aligned} \varphi(S(gy_n, gy_n, gy_{n+1})) &= \varphi\left(S(F(y_{n-1}, x_{n-1}), F(y_{n-1}, x_{n-1}), F(y_n, x_n))\right) \\ &\leq \frac{1}{2}\varphi(S(gy_{n-1}, gy_{n-1}, gy_n) + S(gx_{n-1}, gx_{n-1}, gx_n)) \\ &\quad - \psi\left(\frac{S(gy_{n-1}, gy_{n-1}, gy_n) + S(gx_{n-1}, gx_{n-1}, gx_n)}{2}\right). \end{aligned} \quad (3.10)$$

Using Lemma 2.3, we have

$$\begin{aligned} \varphi(S(gy_{n+1}, gy_{n+1}, gy_n)) &\leq \frac{1}{2}\varphi(S(gy_n, gy_n, gy_{n-1}) + S(gx_n, gx_n, gx_{n-1})) \\ &\quad - \psi\left(\frac{S(gy_n, gy_n, gy_{n-1}) + S(gx_n, gx_n, gx_{n-1})}{2}\right). \end{aligned} \quad (3.11)$$

Using (3.9) and (3.11), we have

$$\begin{aligned} &\varphi(S(gx_{n+1}, gx_{n+1}, gx_n)) + \varphi(S(gy_{n+1}, gy_{n+1}, gy_n)) \\ &\leq \varphi(S(gx_n, gx_n, gx_{n-1}) + S(gy_n, gy_n, gy_{n-1})) \\ &\quad - 2\psi\left(\frac{S(gx_n, gx_n, gx_{n-1}) + S(gy_n, gy_n, gy_{n-1})}{2}\right). \end{aligned} \quad (3.12)$$

By property (3) of φ , we have

$$\begin{aligned} &\varphi(S(gx_{n+1}, gx_{n+1}, gx_n) + S(gy_{n+1}, gy_{n+1}, gy_n)) \\ &\leq \varphi(S(gx_{n+1}, gx_{n+1}, gx_n)) + \varphi(S(gy_{n+1}, gy_{n+1}, gy_n)). \end{aligned} \quad (3.13)$$

Using (3.12) and (3.13), we have

$$\begin{aligned} & \varphi(S(gx_{n+1}, gx_{n+1}, gx_n) + S(gy_{n+1}, gy_{n+1}, gy_n)) \\ & \leq \varphi(S(gx_n, gx_n, gx_{n-1}) + S(gy_n, gy_n, gy_{n-1})) \\ & \quad - 2\psi\left(\frac{S(gx_n, gx_n, gx_{n-1}) + S(gy_n, gy_n, gy_{n-1})}{2}\right), \end{aligned} \quad (3.14)$$

which implies, since ψ is a non-negative function,

$$\begin{aligned} & \varphi(S(gx_{n+1}, gx_{n+1}, gx_n) + S(gy_{n+1}, gy_{n+1}, gy_n)) \\ & \leq \varphi(S(gx_n, gx_n, gx_{n-1}) + S(gy_n, gy_n, gy_{n-1})). \end{aligned}$$

Using the fact that φ is non-decreasing, we get

$$\begin{aligned} & S(gx_{n+1}, gx_{n+1}, gx_n) + S(gy_{n+1}, gy_{n+1}, gy_n) \\ & \leq S(gx_n, gx_n, gx_{n-1}) + S(gy_n, gy_n, gy_{n-1}). \end{aligned}$$

Set

$$\delta_n = S(gx_{n+1}, gx_{n+1}, gx_n) + S(gy_{n+1}, gy_{n+1}, gy_n).$$

Now we would like to show that $\delta_n \rightarrow 0$ as $n \rightarrow \infty$. It is clear that the sequence $\{\delta_n\}$ is decreasing. Therefore, there is some $\delta \geq 0$ such that

$$\lim_{n \rightarrow \infty} \delta_n = \lim_{n \rightarrow \infty} [S(gx_{n+1}, gx_{n+1}, gx_n) + S(gy_{n+1}, gy_{n+1}, gy_n)] = \delta. \quad (3.15)$$

We shall show that $\delta = 0$. Suppose, to the contrary, that $\delta > 0$. Then taking the limit as $n \rightarrow \infty$ (equivalently, $\delta_n \rightarrow \delta$) of both sides of (3.14) and remembering $\lim_{t \rightarrow r} \psi(t) > 0$ for all $r > 0$ and φ is continuous, we have

$$\begin{aligned} \varphi(\delta) &= \lim_{n \rightarrow \infty} \varphi(\delta_n) \leq \lim_{n \rightarrow \infty} \left[\varphi(\delta_{n-1}) - 2\psi\left(\frac{\delta_{n-1}}{2}\right) \right] \\ &= \varphi(\delta) - 2 \lim_{\delta_{n-1} \rightarrow \delta} \psi\left(\frac{\delta_{n-1}}{2}\right) < \varphi(\delta), \end{aligned}$$

this is a contradiction. Thus $\delta = 0$, that is

$$\lim_{n \rightarrow \infty} \delta_n = \lim_{n \rightarrow \infty} [S(gx_{n+1}, gx_{n+1}, gx_n) + S(gy_{n+1}, gy_{n+1}, gy_n)] = 0. \quad (3.16)$$

Now, we will prove that $\{gx_n\}$ and $\{gy_n\}$ are Cauchy sequences. Suppose, to the contrary, that at least one of $\{gx_n\}$ or $\{gy_n\}$ is not Cauchy sequence. Then there exists an $\varepsilon > 0$ for which we can find subsequences

$\{gx_{n(k)}\}, \{gx_{m(k)}\}$ of $\{gx_n\}$ and $\{gy_{n(k)}\}, \{gy_{m(k)}\}$ of $\{gy_n\}$ with $n(k) > m(k) \geq k$ such that

$$S(gx_{n(k)}, gx_{n(k)}, gx_{m(k)}) + S(gy_{n(k)}, gy_{n(k)}, gy_{m(k)}) \geq \varepsilon. \quad (3.17)$$

Further, corresponding to $m(k)$, we can choose $n(k)$ in such a way that it is the smallest integer with $n(k) > m(k)$ and satisfying (3.17). Then

$$S(gx_{n(k)-1}, gx_{n(k)-1}, gx_{m(k)}) + S(gy_{n(k)-1}, gy_{n(k)-1}, gy_{m(k)}) < \varepsilon. \quad (3.18)$$

Using (3.17), (3.18), Lemma 2.3 and Lemma 2.4, we have

$$\begin{aligned} \varepsilon &\leq r_k := S(gx_{n(k)}, gx_{n(k)}, gx_{m(k)}) + S(gy_{n(k)}, gy_{n(k)}, gy_{m(k)}) \\ &\leq 2S(gx_{n(k)}, gx_{n(k)}, gx_{n(k)-1}) + S(gx_{m(k)}, gx_{m(k)}, gx_{n(k)-1}) \\ &\quad + 2S(gy_{n(k)}, gy_{n(k)}, gy_{n(k)-1}) + S(gy_{m(k)}, gy_{m(k)}, gy_{n(k)-1}) \\ &\leq 2S(gx_{n(k)}, gx_{n(k)}, gx_{n(k)-1}) + 2S(gy_{n(k)}, gy_{n(k)}, gy_{n(k)-1}) + \varepsilon. \end{aligned}$$

Letting $k \rightarrow \infty$ and using (3.16), we get

$$\lim_{k \rightarrow \infty} r_k = \lim_{k \rightarrow \infty} \left[S(gx_{n(k)}, gx_{n(k)}, gx_{m(k)}) + S(gy_{n(k)}, gy_{n(k)}, gy_{m(k)}) \right] = \varepsilon. \quad (3.19)$$

By Lemma 2.4, we have

$$\begin{aligned} r_k &= S(gx_{n(k)}, gx_{n(k)}, gx_{m(k)}) + S(gy_{n(k)}, gy_{n(k)}, gy_{m(k)}) \\ &\leq 2S(gx_{n(k)}, gx_{n(k)}, gx_{n(k)+1}) + S(gx_{m(k)}, gx_{m(k)}, gx_{n(k)+1}) \\ &\quad + 2S(gy_{n(k)}, gy_{n(k)}, gy_{n(k)+1}) + S(gy_{m(k)}, gy_{m(k)}, gy_{n(k)+1}) \\ &\leq 2S(gx_{n(k)}, gx_{n(k)}, gx_{n(k)+1}) + S(gx_{n(k)+1}, gx_{n(k)+1}, gx_{m(k)}) \\ &\quad + 2S(gy_{n(k)}, gy_{n(k)}, gy_{n(k)+1}) + S(gy_{n(k)+1}, gy_{n(k)+1}, gy_{m(k)}) \\ &\leq 2S(gx_{n(k)}, gx_{n(k)}, gx_{n(k)+1}) + \left[2S(gx_{n(k)+1}, gx_{n(k)+1}, gx_{m(k)+1}) \right. \\ &\quad \left. + S(gx_{m(k)+1}, gx_{m(k)+1}, gx_{m(k)+1}) \right] + 2S(gy_{n(k)}, gy_{n(k)}, gy_{n(k)+1}) \\ &\quad + \left[2S(gy_{n(k)+1}, gy_{n(k)+1}, gy_{m(k)+1}) + S(gy_{m(k)+1}, gy_{m(k)+1}, gy_{m(k)+1}) \right] \\ &\leq 2\delta_{n(k)} + \delta_{m(k)} + S(gx_{n(k)+1}, gx_{n(k)+1}, gx_{m(k)+1}) \\ &\quad + S(gy_{n(k)+1}, gy_{n(k)+1}, gy_{m(k)+1}). \end{aligned}$$

Using the property of φ , we have

$$\begin{aligned} \varphi(r_k) &= \varphi\left(\delta_{n(k)} + \delta_{m(k)} + S(gx_{n(k)+1}, gx_{n(k)+1}, gx_{m(k)+1})\right. \\ &\quad \left.+ S(gy_{n(k)+1}, gy_{n(k)+1}, gy_{m(k)+1})\right) \\ &\leq \varphi(\delta_{n(k)} + \delta_{m(k)}) + \varphi\left(S(gx_{n(k)+1}, gx_{n(k)+1}, gx_{m(k)+1})\right) \\ &\quad + \varphi\left(S(gy_{n(k)+1}, gy_{n(k)+1}, gy_{m(k)+1})\right). \end{aligned} \quad (3.20)$$

Since $n(k) > m(k)$, hence $gx_{n(k)} \geq gx_{m(k)}$ and $gy_{n(k)} \geq gy_{m(k)}$. Using (3.1) and (3.2), we get

$$\begin{aligned} &\varphi\left(S(gx_{n(k)+1}, gx_{n(k)+1}, gx_{m(k)+1})\right) \\ &= \varphi\left(S(F(x_{n(k)}, y_{n(k)}), F(x_{n(k)}, y_{n(k)}), F(x_{m(k)}, y_{m(k)}))\right) \\ &\leq \frac{1}{2}\varphi\left(S(gx_{n(k)}, gx_{n(k)}, gx_{m(k)}) + S(gy_{n(k)}, gy_{n(k)}, gy_{m(k)})\right) \\ &\quad - \psi\left(\frac{S(gx_{n(k)}, gx_{n(k)}, gx_{m(k)}) + S(gy_{n(k)}, gy_{n(k)}, gy_{m(k)})}{2}\right) \\ &= \frac{1}{2}\varphi(r_k) - \psi\left(\frac{r_k}{2}\right). \end{aligned} \quad (3.21)$$

By the same way, we also have

$$\begin{aligned} &\varphi\left(S(gy_{m(k)+1}, gy_{m(k)+1}, gy_{n(k)+1})\right) \\ &= \varphi\left(S(F(y_{m(k)}, x_{m(k)}), F(y_{m(k)}, x_{m(k)}), F(y_{n(k)}, x_{n(k)}))\right) \\ &\leq \frac{1}{2}\varphi\left(S(gy_{m(k)}, gy_{m(k)}, gy_{n(k)}) + S(gx_{m(k)}, gx_{m(k)}, gx_{n(k)})\right) \\ &\quad - \psi\left(\frac{S(gy_{m(k)}, gy_{m(k)}, gy_{n(k)}) + S(gx_{m(k)}, gx_{m(k)}, gx_{n(k)})}{2}\right) \\ &= \frac{1}{2}\varphi(r_k) - \psi\left(\frac{r_k}{2}\right). \end{aligned} \quad (3.22)$$

Inserting (3.21) and (3.22) in (3.20), we have

$$\varphi(r_k) \leq \varphi(\delta_{n(k)} + \delta_{m(k)}) + \varphi(r_k) - 2\psi\left(\frac{r_k}{2}\right).$$

Letting $k \rightarrow \infty$ and using (3.16) and (3.19), we get

$$\varphi(\varepsilon) \leq \varphi(0) + \varphi(\varepsilon) - 2 \lim_{k \rightarrow \infty} \psi\left(\frac{r_k}{2}\right) = \varphi(\varepsilon) - 2 \lim_{r_k \rightarrow \infty} \psi\left(\frac{r_k}{2}\right) < \varphi(\varepsilon),$$

this is a contradiction. This shows that $\{gx_n\}$ and $\{gy_n\}$ are Cauchy sequences.

Since X is a complete metric space, there exist $x, y \in X$ such that

$$\lim_{n \rightarrow \infty} F(x_n, y_n) = \lim_{n \rightarrow \infty} gx_n = x \quad \text{and} \quad \lim_{n \rightarrow \infty} F(y_n, x_n) = \lim_{n \rightarrow \infty} gy_n = y. \quad (3.23)$$

Since F and g are compatible mappings, we have

$$\lim_{n \rightarrow \infty} S\left(g(F(x_n, y_n)), g(F(x_n, y_n)), F(gx_n, gy_n)\right) = 0 \quad (3.24)$$

and

$$\lim_{n \rightarrow \infty} S\left(g(F(y_n, x_n)), g(F(y_n, x_n)), F(gy_n, gx_n)\right) = 0. \quad (3.25)$$

We now show that $gx = F(x, y)$ and $gy = F(y, x)$. Suppose that the assumption (a) holds. For all $n \geq 0$, we have

$$\begin{aligned} S(gx, gx, F(gx_n, gy_n)) &\leq S(gx, gx, g(F(x_n, y_n))) \\ &\quad + S(g(F(x_n, y_n)), g(F(x_n, y_n)), F(gx_n, gy_n)). \end{aligned}$$

Taking the limit as $n \rightarrow \infty$, using (3.2), (3.23), (3.24) and the fact that F and g are continuous, we have $S(gx, gx, F(x, y)) = 0$.

Similarly, using (3.2), (3.23), (3.25) and the fact that F and g are continuous, we have $S(gy, gy, F(y, x)) = 0$.

Combining the above two results, we get

$$gx = F(x, y) \quad \text{and} \quad gy = F(y, x).$$

Finally, suppose that (b) holds. By (3.3), (3.4) and (3.23), we have $\{gx_n\}$ is a non-decreasing sequence, $gx_n \rightarrow x$ and $\{gy_n\}$ is a non-increasing sequence, $gy_n \rightarrow y$ as $n \rightarrow \infty$. Hence, by assumption (b), we have for all $n \geq 0$,

$$gx_n \leq x \quad \text{and} \quad gy_n \leq y. \quad (3.26)$$

Since F and g are compatible mappings and g is continuous, by (3.24) and (3.25), we have

$$\lim_{n \rightarrow \infty} g(gx_n) = gx = \lim_{n \rightarrow \infty} g(F(x_n, y_n)) = \lim_{n \rightarrow \infty} F(gx_n, gy_n) \quad (3.27)$$

and

$$\lim_{n \rightarrow \infty} g(gy_n) = gy = \lim_{n \rightarrow \infty} g(F(y_n, x_n)) = \lim_{n \rightarrow \infty} F(gy_n, gx_n). \quad (3.28)$$

Now we have

$$S(gx, gx, F(x, y)) \leq S(gx, gx, g(gx_{n+1})) + S(g(gx_{n+1}), g(gx_{n+1}), F(x, y)).$$

Taking $n \rightarrow \infty$ in the above inequality, using (3.2) and (3.20) we have,

$$\begin{aligned} S(gx, gx, F(x, y)) &\leq \lim_{n \rightarrow \infty} S(gx, gx, g(gx_{n+1})) \\ &\quad + \lim_{n \rightarrow \infty} S(g(F(x_n, y_n)), g(F(x_n, y_n)), F(x, y)) \quad (3.29) \\ &\leq \lim_{n \rightarrow \infty} S(F(gx_n, gy_n), F(gx_n, gy_n), F(x, y)). \end{aligned}$$

Using the property of φ , we get

$$\varphi\left(S(gx, gx, F(x, y))\right) \leq \lim_{n \rightarrow \infty} \varphi\left(S(F(gx_n, gy_n), F(gx_n, gy_n), F(x, y))\right).$$

Since the mapping g is monotone increasing, using (3.1), (3.26) and (3.29), we have for all $n \geq 0$,

$$\begin{aligned} \varphi\left(S(gx, gx, F(x, y))\right) &\leq \lim_{n \rightarrow \infty} \frac{1}{2} \varphi\left(S(ggx_n, ggx_n, gx) + S(gy_n, gy_n, ggy)\right) \\ &\quad - \lim_{n \rightarrow \infty} \left(\frac{S(ggx_n, ggx_n, gx) + S(gy_n, gy_n, ggy)}{2}\right). \end{aligned}$$

Using the above inequality, using (3.23) and the property of ψ , we get $\psi\left(S(gx, gx, F(x, y))\right) = 0$, thus $S(gx, gx, F(x, y)) = 0$. Hence $gx = F(x, y)$.

Similarly, we can show that $gy = F(y, x)$. Thus we proved that F and g have a coupled coincidence point. \square

Corollary 3.2. *Let (X, \leq, S) be a partially ordered complete S -metric space. Let $F : X^2 \rightarrow X$ is such that F has the mixed monotone property such that there exists $x_0, y_0 \in X$ with*

$$x_0 \leq F(x_0, y_0) \quad \text{and} \quad y_0 \geq F(y_0, x_0).$$

Suppose there exist $\varphi \in \Phi$ and $\psi \in \Psi$ such that

$$\begin{aligned} &\varphi\left(S(F(x, y), F(x, y), F(u, v))\right) \\ &\leq \frac{1}{2} \varphi(S(x, x, u) + S(y, y, v)) - \psi\left(\frac{S(x, x, u) + S(y, y, v)}{2}\right), \quad (3.30) \end{aligned}$$

for all $x, y, u, v \in X$ with $x \geq u$ and $y \leq v$. Suppose either

- (a) F is continuous or
- (b) X has the following property:
- (i) if a non-decreasing sequence $\{x_n\} \rightarrow x$, then $x_n \leq x$, for all n ,
 - (ii) if a non-increasing sequence $\{y_n\} \rightarrow y$, then $y_n \geq y$, for all n .

Then there exists $x, y \in X$ such that

$$x = F(x, y) \quad \text{and} \quad y = F(y, x),$$

that is, F has a coupled fixed point in X .

Corollary 3.3. Let (X, \leq, S) be a partially ordered complete S -metric space. Let $F : X^2 \rightarrow X$ is such that F has the mixed monotone property such that there exists $x_0, y_0 \in X$ with

$$x_0 \leq F(x_0, y_0) \quad \text{and} \quad y_0 \geq F(y_0, x_0).$$

Suppose there exist $\psi \in \Psi$ such that

$$\begin{aligned} & S(F(x, y), F(x, y), F(u, v)) \\ & \leq \frac{S(x, x, u) + S(y, y, v)}{2} - \psi \left(\frac{S(x, x, u) + S(y, y, v)}{2} \right), \end{aligned} \tag{3.31}$$

for all $x, y, u, v \in X$ with $x \geq u$ and $y \leq v$. Suppose either

- (a) F is continuous or
- (b) X has the following property:
- (i) if a non-decreasing sequence $\{x_n\} \rightarrow x$, then $x_n \leq x$, for all n ,
 - (ii) if a non-increasing sequence $\{y_n\} \rightarrow y$, then $y_n \geq y$, for all n .

Then there exists $x, y \in X$ such that

$$x = F(x, y) \quad \text{and} \quad y = F(y, x),$$

that is, F has a coupled fixed point in X .

Proof. Take $\varphi(t) = t$ in Corollary 3.2. □

Corollary 3.4. *Let (X, \leq, S) be a partially ordered complete S -metric space. Let $F : X^2 \rightarrow X$ is such that F has the mixed monotone property such that there exists $x_0, y_0 \in X$ with*

$$x_0 \leq F(x_0, y_0) \quad \text{and} \quad y_0 \geq F(y_0, x_0).$$

Suppose there exists a real number $k \in [0, 1)$ such that

$$S(F(x, y), F(x, y), F(u, v)) \leq \frac{k}{2} (S(x, x, u) + S(y, y, v)), \quad (3.32)$$

for all $x, y, u, v \in X$ with $x \geq u$ and $y \leq v$. Suppose either

- (a) *F is continuous or*
- (b) *X has the following property:*
 - (i) *if a non-decreasing sequence $\{x_n\} \rightarrow x$, then $x_n \leq x$, for all n ,*
 - (ii) *if a non-increasing sequence $\{y_n\} \rightarrow y$, then $y_n \geq y$, for all n .*

Then there exists $x, y \in X$ such that

$$x = F(x, y) \quad \text{and} \quad y = F(y, x),$$

that is, F has a coupled fixed point in X .

Proof. Take $\psi(t) = (1 - k)t$ in Corollary 3.3. □

4 Uniqueness of Coupled Coincidence Point

In this section, we will prove the uniqueness of the coupled coincidence point. Note that if $(X; \leq)$ is a partially ordered set, then we endow the product X^2 with the following partial order relation, for all $(x, y), (u, v) \in X^2$,

$$(x, y) \leq (u, v) \quad \Leftrightarrow \quad x \leq u, \quad y \geq v.$$

Theorem 4.1. *In addition to hypotheses of Theorem 3.1, suppose that for every $(x, y), (z, t)$ in X^2 , if there exists a (u, v) in X^2 that is comparable to (x, y) and (z, t) , then F has a unique coupled coincidence point.*

Proof. From Theorem 3.1, the set of coupled coincidence points of F and g is nonempty. Suppose (x, y) and (z, t) are coupled coincidence points of F and g , that is $gx = F(x, y)$, $gy = F(y, x)$, $gz = F(z, t)$ and $gt = F(t, z)$. We are going to show that $gx = gz$ and $gy = gt$. By assumption, there exists

$(u, v) \subset X^2$ that is comparable to (x, y) and (z, t) . We define sequences $\{gu_n\}, \{gv_n\}$ as follows,

$$u_0 = u, \quad v_0 = v. \quad gu_{n+1} = F(u_n, v_n) \quad \text{and} \quad gv_{n+1} = F(v_n, u_n) \quad \text{for all } n.$$

Since (u, v) is comparable with (x, y) , we may assume that $(x, y) \geq (u, v) = (u_0, v_0)$. Using the mathematical induction, it is easy to prove that

$$(x, y) \geq (u_n, v_n) \quad \text{for all } n. \tag{4.1}$$

Using (3.1) and (4.1), we have

$$\begin{aligned} \varphi\left(S(gx, gx, gu_{n+1})\right) &= \varphi\left(S(F(x, y), F(x, y), F(u_n, v_n))\right) \\ &\leq \frac{1}{2}\varphi\left(S(gx, gx, gu_n) + S(gy, gy, gv_n)\right) \\ &\quad - \psi\left(\frac{S(gx, gx, gu_n) + S(gy, gy, gv_n)}{2}\right). \end{aligned} \tag{4.2}$$

Similarly,

$$\begin{aligned} \varphi\left(S(gv_{n+1}, gy, gy)\right) &= \varphi\left(S(F(v_n, u_n), F(y, x), F(y, x))\right) \\ &\leq \frac{1}{2}\varphi\left(S(gv_n, gy, gy) + S(gu_n, gx, gx)\right) \\ &\quad - \psi\left(\frac{S(gv_n, gy, gy) + S(gu_n, gx, gx)}{2}\right). \end{aligned} \tag{4.3}$$

Using (4.2), (4.3) and the property of φ , we have

$$\begin{aligned} &\varphi\left(S(gx, gx, gu_{n+1}) + S(gv_{n+1}, gy, gy)\right) \\ &\leq \varphi\left(S(gx, gx, gu_{n+1})\right) + \varphi\left(S(gv_{n+1}, gy, gy)\right) \\ &\leq \varphi\left(S(gx, gx, gu_n) + S(gy, gy, gv_n)\right) \\ &\quad - 2\psi\left(\frac{S(gv_n, gy, gy) + S(gu_n, gx, gx)}{2}\right), \end{aligned} \tag{4.4}$$

which implies, using the definition of ψ ,

$$\begin{aligned} &\varphi\left(S(gx, gx, gu_{n+1}) + S(gv_{n+1}, gy, gy)\right) \\ &\leq \varphi\left(S(gx, gx, gu_n)\right) + \varphi\left(S(gv_n, gy, gy)\right). \end{aligned}$$

Thus, using the definition of φ ,

$$S(gx, gx, gu_{n+1}) + S(gv_{n+1}, gy, gy) \leq S(gx, gx, gu_n) + S(gv_n, gy, gy).$$

That is the sequence $\{S(gx, gx, gu_n) + S(gy, gy, gv_n)\}$ is decreasing. Therefore, there exists $\alpha \geq 0$ such that

$$\lim_{n \rightarrow \infty} \left(S(gx, gx, gu_n) + S(gy, gy, gv_n) \right) = \alpha. \quad (4.5)$$

We will show that $\alpha = 0$. Suppose to the contrary that $\alpha > 0$. Taking the limit as $n \rightarrow \infty$ in (4.4), we have, using the property of ψ ,

$$\varphi(\alpha) \leq \varphi(\alpha) - 2 \lim_{n \rightarrow \infty} \psi \left(\frac{S(gx, gx, gu_n) + S(gy, gy, gv_n)}{2} \right) < \varphi(\alpha),$$

this is a contradiction. Thus $\alpha = 0$, that is,

$$\lim_{n \rightarrow \infty} \left(S(gx, gx, gu_n) + S(gy, gy, gv_n) \right) = 0.$$

It implies

$$\lim_{n \rightarrow \infty} S(gx, gx, gu_n) = \lim_{n \rightarrow \infty} S(gy, gy, gv_n) = 0. \quad (4.6)$$

Similarly, we show that

$$\lim_{n \rightarrow \infty} S(gz, gz, gu_n) = \lim_{n \rightarrow \infty} S(gt, gt, gv_n) = 0. \quad (4.7)$$

Using (4.6) and (4.7), we have $gx = gz$ and $gy = gt$. \square

Corollary 4.2. *In addition to hypotheses of Corollary 3.2, suppose that for every $(x, y), (z, t)$ in X^2 , if there exists a (u, v) in X^2 that is comparable to (x, y) and (z, t) , then F has a unique coupled fixed point.*

5 Example

Example 5.1. Let $X = [0, 1]$. Then (X, \leq) is a partially ordered set with the natural ordering of real numbers. Let

$$S(x, y, z) = \frac{|x - y| + |x - z| + |y - z|}{2} \quad \text{for } x, y, z \in [0, 1].$$

Then $S(x, x, y) = |x - y|$ and (X, S) is a complete S -metric space.

Let $g : X \rightarrow X$ be defined as:

$$gx = x^2, \quad \text{for all } x \in X,$$

and let $F : X^2 \rightarrow X$ be defined as:

$$F(x, y) = \begin{cases} \frac{x^2 - y^2}{3}, & \text{if } x \geq y; \\ 0, & \text{if } x < y. \end{cases}$$

F obeys the mixed g -monotone property. Let $\varphi : [0, \infty) \rightarrow [0, \infty)$ be defined as:

$$\varphi(t) = \frac{3}{4}t, \quad \text{for } t \in [0, \infty),$$

and let $\psi : [0, \infty) \rightarrow [0, \infty)$ be defined as:

$$\psi(t) = \frac{1}{4}t, \quad \text{for } t \in [0, \infty).$$

Let $\{x_n\}$ and $\{y_n\}$ be two sequences in X such that $\lim_{n \rightarrow \infty} F(x_n, y_n) = a$, $\lim_{n \rightarrow \infty} gx_n = a$, $\lim_{n \rightarrow \infty} F(y_n, x_n) = b$ and $\lim_{n \rightarrow \infty} gy_n = b$. Then obviously, $a = 0$ and $b = 0$. Now, for all $n \geq 0$,

$$gx_n = x_n^2, \quad gy_n = y_n^2, \quad F(x_n, y_n) = \begin{cases} \frac{x_n^2 - y_n^2}{3}, & \text{if } x_n \geq y_n; \\ 0, & \text{if } x_n < y_n, \end{cases}$$

and

$$F(y_n, x_n) = \begin{cases} \frac{y_n^2 - x_n^2}{3}, & \text{if } y_n \geq x_n; \\ 0, & \text{if } y_n < x_n. \end{cases}$$

Then it follows that,

$$\lim_{n \rightarrow \infty} S\left(g(F(x_n, y_n)), g(F(x_n, y_n)), F(gx_n, gy_n)\right) = 0$$

and

$$\lim_{n \rightarrow \infty} S\left(g(F(y_n, x_n)), g(F(y_n, x_n)), F(gy_n, gx_n)\right) = 0.$$

Hence, the mappings F and g are compatible in X . Also, $x_0 = 0$ and $y_0 = c (> 0)$ are two points in X such that

$$gx_0 = g(0) = 0 = F(0, c) = F(x_0, y_0) \quad \text{and}$$

$$gy_0 = g(c) = c^2 \geq \frac{c^2}{3} = F(c, 0) = F(y_0, x_0).$$

We next verify the contraction (3.1). We take $x, y, u, v \in X$ such that $gx \geq gu$ and $gy \leq gv$, that is, $x^2 \geq u^2$ and $y^2 \leq v^2$.

We consider the following cases:

Case 1. $x \geq y, u \geq v$. Then

$$\begin{aligned} & \varphi\left(S(F(x, y), F(x, y), F(u, v))\right) \\ &= \frac{3}{4}\left(S(F(x, y), F(x, y), F(u, v))\right) \\ &= \frac{3}{4}\left(S\left(\frac{x^2 - y^2}{3}, \frac{x^2 - y^2}{3}, \frac{u^2 - v^2}{3}\right)\right) \\ &= \frac{3}{4}\left|\frac{(x^2 - y^2) - (u^2 - v^2)}{3}\right| \\ &= \frac{3}{4}\left(\frac{|x^2 - u^2| - |y^2 - v^2|}{3}\right) \\ &= \frac{1}{2}\left(\frac{S(gx, gx, gu) + S(gy, gy, gv)}{2}\right) \\ &= \frac{3}{4}\left(\frac{S(gx, gx, gu) + S(gy, gy, gv)}{2}\right) - \frac{1}{4}\left(\frac{S(gx, gx, gu) + S(gy, gy, gv)}{2}\right) \\ &= \frac{3}{8}\left(S(gx, gx, gu) + S(gy, gy, gv)\right) - \frac{1}{4}\left(\frac{S(gx, gx, gu) + S(gy, gy, gv)}{2}\right) \\ &= \frac{1}{2}\varphi\left(S(gx, gx, gu) + S(gy, gy, gv)\right) - \psi\left(\frac{S(gx, gx, gu) + S(gy, gy, gv)}{2}\right). \end{aligned}$$

Case 2. $x \geq y, u < v$. Then

$$\begin{aligned} \varphi\left(S(F(x, y), F(x, y), F(u, v))\right) &= \frac{3}{4}\left(S(F(x, y), F(x, y), F(u, v))\right) \\ &= \frac{3}{4}\left(S\left(\frac{x^2 - y^2}{3}, \frac{x^2 - y^2}{3}, 0\right)\right) \\ &= \frac{3}{4}\frac{|x^2 - y^2|}{3} = \frac{3}{4}\left(\frac{|u^2 + x^2 - y^2 - u^2|}{3}\right) \\ &< \frac{3}{4}\left(\frac{|v^2 + x^2 - y^2 - u^2|}{3}\right) \\ &= \frac{3}{4}\left(\frac{|(v^2 - y^2) - (u^2 - x^2)|}{3}\right) \end{aligned}$$

$$\begin{aligned}
&\leq \frac{3}{4} \left(\frac{|u^2 - x^2| + |y^2 - v^2|}{3} \right) \\
&= \frac{1}{2} \left(\frac{S(gx, gx, gu) + S(gy, gy, gv)}{2} \right) \\
&= \frac{3}{4} \left(\frac{S(gx, gx, gu) + S(gy, gy, gv)}{2} \right) - \frac{1}{4} \left(\frac{S(gx, gx, gu) + S(gy, gy, gv)}{2} \right) \\
&= \frac{3}{8} (S(gx, gx, gu) + S(gy, gy, gv)) - \frac{1}{4} \left(\frac{S(gx, gx, gu) + S(gy, gy, gv)}{2} \right) \\
&= \frac{1}{2} \varphi (S(gx, gx, gu) + S(gy, gy, gv)) - \psi \left(\frac{S(gx, gx, gu) + S(gy, gy, gv)}{2} \right).
\end{aligned}$$

Case 3. $x < y, u \geq v$. Then,

$$\begin{aligned}
&\varphi \left(S(F(x, y), F(x, y), F(u, v)) \right) \\
&= \frac{3}{4} \left(S \left(0, 0, \frac{u^2 - v^2}{3} \right) \right) \\
&= \frac{3}{4} \frac{|u^2 - v^2|}{3} = \frac{3}{4} \left(\frac{|u^2 + x^2 - v^2 - x^2|}{3} \right) \\
&< \frac{3}{4} \left(\frac{|u^2 + y^2 - v^2 - x^2|}{3} \right) \\
&\leq \frac{3}{4} \left(\frac{|u^2 - x^2| + |y^2 - v^2|}{3} \right) \\
&= \frac{1}{2} \left(\frac{S(gx, gx, gu) + S(gy, gy, gv)}{2} \right) \\
&= \frac{3}{4} \left(\frac{S(gx, gx, gu) + S(gy, gy, gv)}{2} \right) - \frac{1}{4} \left(\frac{S(gx, gx, gu) + S(gy, gy, gv)}{2} \right) \\
&= \frac{3}{8} (S(gx, gx, gu) + S(gy, gy, gv)) - \frac{1}{4} \left(\frac{S(gx, gx, gu) + S(gy, gy, gv)}{2} \right) \\
&= \frac{1}{2} \varphi (S(gx, gx, gu) + S(gy, gy, gv)) - \psi \left(\frac{S(gx, gx, gu) + S(gy, gy, gv)}{2} \right).
\end{aligned}$$

Case 4. $x < y$ and $u < v$ with $x^2 \leq u^2$ and $y^2 \geq v^2$. Then, $F(x, y) = 0$ and $F(u, v) = 0$, that is,

$$\varphi \left(S(F(x, y), F(x, y), F(u, v)) \right) = \varphi(S(0, 0, 0)) = \varphi(0) = 0.$$

Therefore all conditions of Theorem 3.1 are satisfied. Thus the conclusion follows. \square

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