



# Coupled Coincidence Point for Generalized Monotone Operators in Partially Ordered Metric Spaces

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**Abstract :** In this note, we prove the existence and the uniqueness of coupled coincidence points theorem for  $(\varphi - \psi)$  contractive condition for a generalized mapping having the mixed  $g$ -monotone property in complete ordered spaces. These results generalize and extend the existing fixed point results in the literature.

**Keywords :** coupled coincidence point; partially ordered metric space; mixed  $g$ -monotone property.

**2010 Mathematics Subject Classification :** 47H10; 54H25.

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## 1 Introduction

The existence of fixed points in partially ordered metric spaces has been studied recently by several authors: Ran et al [1], Bhaskar and Lakshmikantham [2], Agarwal et al [3], Lakshmikantham and Ćirić [4], Luong Thuan [5] and Alotaibi and Alsulami [6]. The first result appeared in this direction was given by Ran and Reurings [1], who presented its applications to matrix equation. Nieto and Rodríguez-Lopez [7, 8] extended the results of Ran and Reurings [1] for nondecreasing mappings and applied them to obtain a unique solution for a first-order ordinary differential equation with periodic boundary conditions.

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Recently, Alotaibi and Alsulami [6], established the existence and uni-queeness of coupled coincidence point, involving a  $(\varphi, \psi)$ -contraction condition for a mapping having the mixed  $g$ -monotone property. The aim of this paper is to extend the results obtained in [6] by using a more general mapping having the mixed  $g$ -monotone property and generalize the existing fixed point in the literature, [9, 10, 11, 12, 13, 14, 15, 16, 17, 18, 19].

Here are some definitions, and early results we presented in the following.

**Definition 1.1.** ([3]). Let  $(X, \preceq)$  be a partially ordered set and  $F : X \times X \rightarrow X$ . The mapping  $F$  is said to have the *mixed monotone property*, if  $F(x, y)$  is monotone, nondecreasing in  $x$  and it is monotone non-increasing in  $y$ , that is, for any  $x, y \in X$ :

$$x_1, x_2 \in X, \quad x_1 \preceq x_2 \implies F(x_1, y) \preceq F(x_2, y),$$

and

$$y_1, y_2 \in X, \quad y_1 \preceq y_2 \implies F(x, y_1) \succeq F(x, y_2).$$

**Definition 1.2.** ([3]). An element  $(x, y) \in X \times X$  is called a *coupled fixed point* of the mapping  $F : X \times X \rightarrow X$  if

$$x = F(x, y) \quad \text{and} \quad y = F(y, x).$$

**Definition 1.3.** ([4]). (Mixed  $g$ -monotone Property). Let  $F$  and  $g$  be two mappings such that

$$F : X \times X \rightarrow X \quad \text{and} \quad g : X \rightarrow X.$$

The mapping  $F$  is said to have the *mixed  $g$ -monotone property* if  $F(x, y)$  is monotone, nondecreasing in  $x$  and is monotone non-increasing in  $y$ , that is, for any  $x, y \in X$ :

$$x_1, x_2 \in X, \quad gx_1 \preceq gx_2 \implies F(x_1, y) \preceq F(x_2, y), \quad (1.1)$$

and

$$y_1, y_2 \in X, \quad gy_1 \preceq gy_2 \implies F(x, y_1) \succeq F(x, y_2). \quad (1.2)$$

**Definition 1.4.** ([4]). An element  $(x, y) \in X \times X$  is called a *coupled coincidence point* of the mapping  $F : X \times X \rightarrow X$  and  $g : X \rightarrow X$  if

$$gx = F(x, y) \quad \text{and} \quad gy = F(y, x).$$

**Definition 1.5.** ([4]). The mappings  $F$  and  $g$ , where  $F : X \times X \rightarrow X$  and  $g : X \rightarrow X$ , are said to be *compatible* if

$$\lim_{n \rightarrow \infty} d(g(F(x_n, y_n)), F(gx_n, gy_n)) = 0,$$

and

$$\lim_{n \rightarrow \infty} d(g(F(y_n, x_n)), F(gy_n, gx_n)) = 0,$$

whenever  $\{x_n\}$  and  $\{y_n\}$  are sequences in  $X$ , such that:

$$\lim_{n \rightarrow \infty} F(x_n, y_n) = \lim_{n \rightarrow \infty} gx_n = x,$$

and

$$\lim_{n \rightarrow \infty} F(y_n, x_n) = \lim_{n \rightarrow \infty} gy_n = y,$$

are satisfied for all  $x, y \in X$ .

The main theoretical results presented in [2] are the following coupled point theorems.

**Theorem 1.6.** ([2]). *Let  $(X, \preceq)$  be a partially ordered set and suppose there exists a metric  $d$  on  $X$  such that  $(X, d)$  is a complete metric space. Let  $F : X \times X \rightarrow X$  be a continuous mapping, having the mixed monotone property on  $X$ . Assume that there exists a  $k \in [0, 1)$  with*

$$d(F(x, y), F(u, v)) \leq \frac{k}{2}[d(x, u) + d(y, v)]$$

for all  $x \succeq u$  and  $y \preceq v$ .

If there exist two elements  $x_0, y_0 \in X$ , with

$$x_0 \preceq F(x_0, y_0) \text{ and } y_0 \succeq F(y_0, x_0),$$

then there exist  $x, y \in X$  such that

$$x = F(x, y) \text{ and } y = F(y, x).$$

**Theorem 1.7.** [2]. *Let  $(X, \preceq)$  be a partially ordered set and suppose there exists a metric  $d$  on  $X$  such that  $(X, d)$  is a complete metric space. Assume that  $X$  has the following property:*

1. *If a nondecreasing sequence  $\{x_n\} \rightarrow x$ , then  $x_n \preceq x$ , for all  $n \geq 1$ .*
2. *If a non-increasing sequence  $\{y_n\} \rightarrow y$ , then  $y_n \succeq y$ , for all  $n \geq 1$ .*

Let  $F : X \times X \rightarrow X$  be a mapping, having the mixed monotone property on  $X$ . Assume that there exists a  $k \in [0, 1)$  with

$$d(F(x, y), F(u, v)) \leq \frac{k}{2}[d(x, u) + d(y, v)]$$

for all  $x \succeq u$  and  $y \preceq v$ .

If there exist two elements  $x_0, y_0 \in X$ , with

$$x_0 \preceq F(x_0, y_0) \text{ and } y_0 \succeq F(y_0, x_0),$$

then there exist  $x, y \in X$  such that

$$x = F(x, y) \text{ and } y = F(y, x).$$

In [5], the authors presented some coupled fixed point theorems for a mixed monotone mapping in a partially ordered metric space, which are nondecreasing, of the results of Bhaskar and Lakshmikantham [2].

Let us denote by  $\Phi$  the set of all functions  $\varphi : [0, \infty[ \rightarrow [0, \infty[$  which satisfy

1.  $\varphi$  is continuous and nondecreasing,
2.  $\varphi(t) = 0$  if, and only if  $t = 0$ ,
3.  $\varphi(t + s) \leq \varphi(t) + \varphi(s)$ , for all  $t, s \in [0, \infty[$

and  $\Psi$  denotes the set of all functions  $\psi : [0, \infty[ \rightarrow [0, \infty[$ , which satisfy

$$\lim_{t \rightarrow r} \psi(t) > 0 \text{ for all } r > 0 \text{ and } \lim_{t \rightarrow 0_+} \psi(t) = 0.$$

(For more details about  $\Phi$  and  $\Psi$ , see [5]).

**Theorem 1.8.** ([2]). *Let  $(X, \preceq)$  be a partially ordered set and suppose there exists a metric  $d$  on  $X$  such that  $(X, d)$  is a complete metric space. Let  $F : X \times X \rightarrow X$  be a continuous mapping, having the mixed monotone property on  $X$ , such that there exist two elements  $x_0, y_0 \in X$ , with  $x_0 \preceq F(x_0, y_0)$  and  $y_0 \succeq F(y_0, x_0)$ . Suppose there exist  $\varphi \in \Phi$  and  $\psi \in \Psi$  such that*

$$\varphi(d(F(x, y), F(u, v))) \leq \frac{1}{2}\varphi(d(x, u) + d(y, v)) - \psi\left(\frac{d(x, u) + d(y, v)}{2}\right)$$

for all  $x \succeq u$  and  $y \preceq v$ .

Suppose either

(a)  $F$  is continuous or

(b)  $X$  has the following properties:

- (i) If a nondecreasing sequence  $\{x_n\} \rightarrow x$ , then  $x_n \preceq x$ , for all  $n \geq 1$ ,
- (ii) If a non-increasing sequence  $\{y_n\} \rightarrow y$ , then  $y_n \succeq y$ , for all  $n \geq 1$ ,

then there exist  $x, y \in X$  such that  $x = F(x, y)$  and  $y = F(y, x)$ . That is  $F$  has a fixed point.

A. Alotaibi and S. Alsulami [6] established the existence and uniqueness of coupled coincidence point involving a  $(\varphi, \psi)$ -contractive condition for mappings having the mixed  $g$ -monotone property. The main theoretical result in A. Alotaibi and S. Alsulami [6], is given by the following theorem:

**Theorem 1.9.** [6]. *Let  $(X, \preceq)$  be a partially ordered set and suppose there exists a metric  $d$  on  $X$  such that  $(X, d)$  is a complete metric space. Let  $F : X \times X \rightarrow X$  be a continuous mapping, having the mixed monotone property on  $X$  such that there*

exist two elements  $x_0, y_0 \in X$  with  $gx_0 \preceq F(x_0, y_0)$  and  $gy_0 \succeq F(y_0, x_0)$ . Suppose there exist  $\varphi \in \Phi$  and  $\psi \in \Psi$  such that

$$\varphi(d(F(x, y), F(u, v))) \leq \frac{1}{2}\varphi(d(gx, gu) + d(gy, gv)) - \psi\left(\frac{d(gx, gu) + d(gy, gv)}{2}\right)$$

for all  $gx \succeq gu$  and  $gy \preceq gv$ .

Suppose  $F(X \times X) \subset g(X)$ ,  $g$  continuous and compatible with  $F$ , also suppose either

(a)  $F$  is continuous or

(b)  $X$  has the following property:

- (i)  $f$  a nondecreasing sequence  $\{x_n\} \rightarrow x$ , then  $x_n \preceq x$ , for all  $n \geq 1$ ,
- (ii)  $f$  a non-increasing sequence  $\{y_n\} \rightarrow y$ , then  $y_n \succeq y$ , for all  $n \geq 1$

then there exist  $x, y \in X$  such that  $gx = F(x, y)$  and  $gy = F(y, x)$ . That is  $F$  and  $g$  have a coupled coincidence point in  $X$ .

## 2 Existence of Coupled Coincidence Points.

The set  $\Psi_1$  of all lower semi-continuous functions  $\psi : [0, \infty[ \rightarrow [0, \infty[$ , is considered, instead of  $\Psi$ , the function,  $\psi$  satisfies:  $\psi(t) = 0$  if, and only if  $t = 0$ . We prove our main result:

**Theorem 2.1** (Main Theorem). *Let  $(X, \preceq)$  be a partially ordered set and suppose there exists a metric  $d$  on  $X$  such that  $(X, d)$  is a complete metric space. Let  $F : X \times X \rightarrow X$  be a continuous mapping, having the mixed monotone property on  $X$ , such that there exist two elements  $x_0, y_0 \in X$  with*

$$gx_0 \preceq F(x_0, y_0) \text{ and } gy_0 \succeq F(y_0, x_0). \tag{2.1}$$

Suppose that there exist  $\varphi \in \Phi$  and  $\psi \in \Psi_1$  such that

$$\left. \begin{aligned} \varphi(d(F(x, y), F(u, v))) &\leq \frac{1}{2}\varphi(\Theta(gx, gy, gu, gv)) \\ &\quad - \psi(\Theta(gx, gy, gu, gv)) \end{aligned} \right\} \tag{2.2}$$

for all  $gx \succeq gu$  and  $gy \preceq gv$

$$\left. \begin{aligned} \Theta(gx, gy, gu, gv) &= \frac{\alpha}{2} [d(gx, gu) + d(gy, gv)] \\ &\quad + \frac{\beta}{2} [d(gx, F(x, y)) + d(gy, F(y, x)) \\ &\quad \quad + d(gu, F(u, v)) + d(gv, F(v, u))] \\ &\quad + \frac{\gamma}{2} [d(gx, F(u, v)) + d(gy, F(v, u)) \\ &\quad \quad + d(gu, F(x, y)) + d(gv, F(y, x))] \end{aligned} \right\} \tag{2.3}$$

where  $\alpha > 0$ , and  $\beta, \gamma \geq 0$  such that  $\alpha + 2\beta + 2\gamma < 2$ . Suppose  $F(X \times X) \subset g(X)$ ,  $g$  continuous and compatible with  $F$ , also suppose either

(a)  $F$  is continuous or

(b)  $X$  has the following properties:

(i) If a nondecreasing sequence  $\{x_n\} \rightarrow x$ , then  $x_n \preceq x$ , for all  $n \geq 1$ ,

(ii) If a non-increasing sequence  $\{y_n\} \rightarrow y$ , then  $y_n \succeq y$ , for all  $n \geq 1$ ,

then there exist  $x, y \in X$  such that  $gx = F(x, y)$  and  $gy = F(y, x)$ . That is  $F$  and  $g$  have a coupled coincidence point in  $X$ .

*Proof.* Let  $x_0, y_0 \in X$  be such that  $gx_0 \preceq F(x_0, y_0)$  and  $gy_0 \succeq F(y_0, x_0)$ . Using the fact that  $F(X \times X) \subset g(X)$ , we construct sequences  $\{x_n\}$  and  $\{y_n\}$  in  $X$  as follows:

$$gx_{n+1} = F(gx_n, gy_n) \text{ and } gy_{n+1} = F(gy_n, gx_n) \text{ for all } n \geq 0. \quad (2.4)$$

We shall show that the sequence  $\{gx_n\}$  is increasing and  $\{gy_n\}$  is decreasing, that is:

$$gx_n \preceq gx_{n+1} \text{ for all } n \geq 0 \quad (2.5)$$

and

$$gy_n \succeq gy_{n+1} \text{ for all } n \geq 0. \quad (2.6)$$

To prove (2.5) and (2.6), we use the mathematical induction.

Let  $n = 0$ . Since  $gx_0 \preceq F(x_0, y_0)$  and  $gy_0 \succeq F(y_0, x_0)$  and as  $gx_1 = F(x_0, y_0)$  and  $gy_1 = F(y_0, x_0)$ , we have  $gx_0 \preceq gx_1$  and  $gy_0 \succeq gy_1$ . Thus (2.5) and (2.6) hold for  $n = 0$ .

Suppose now that (2.5) and (2.6) hold for some  $n \geq 0$ . Then, since  $gx_n \preceq gx_{n+1}$  and  $gy_n \succeq gy_{n+1}$ , and by the mixed  $g$ -monotone property of  $F$ , we have

$$gx_{n+2} = F(x_{n+1}, y_{n+1}) \succeq F(x_n, y_{n+1}) \succeq F(x_n, y_n) = gx_{n+1} \quad (2.7)$$

and

$$gy_{n+2} = F(y_{n+1}, x_{n+1}) \preceq F(y_n, y_{n+1}) \preceq F(y_n, x_n) = gy_{n+1}. \quad (2.8)$$

Now, from (2.7) and (2.8), we obtain

$$gx_{n+2} \preceq gx_{n+1} \quad \text{and} \quad gy_{n+1} \succeq gy_{n+2}, \quad (2.9)$$

thus, by mathematical induction, we conclude that (2.5) and (2.6) hold for all  $n \geq 0$ . Therefore:

$$gx_0 \preceq gx_1 \preceq gx_2 \preceq \cdots \preceq gx_n \preceq gx_{n+1} \preceq \cdots \quad (2.10)$$

$$gy_0 \succeq gy_1 \succeq gy_2 \succeq \cdots \succeq gy_n \succeq gy_{n+1} \succeq \cdots \quad (2.11)$$

since  $gx_n \succeq gx_{n-1}$  and  $gy_n \preceq gy_{n-1}$ . Then, from (2.3) and (2.4), we have:

$$\Theta(gx_n, gy_n, gx_{n-1}, gy_{n-1}) = \left. \begin{aligned} & \frac{\alpha}{2} [d(gx_n, gx_{n-1}) + d(gy_n, gy_{n-1})] \\ & + \frac{\beta}{2} [d(gx_n, gx_{n+1}) + d(gy_n, gy_{n+1})] \\ & + d(gx_{n-1}, gx_n) + d(gy_{n-1}, gy_n) \\ & \frac{\gamma}{2} [d(gx_{n-1}, gx_{n+1}) + d(gy_{n-1}, gy_{n+1})] \end{aligned} \right\} \quad (2.12)$$

Similarly, since  $gx_n \succeq gx_{n-1}$  and  $gy_n \preceq gy_{n-1}$ , then, from (2.3) and (2.4), we have also:

$$\left. \begin{aligned} \varphi(d(gy_{n+1}, gy_n)) &= \varphi(d(F(y_n, x_n), F(y_{n-1}, x_{n-1}))) \\ &\leq \frac{1}{2} \varphi(\Theta(gy_n, gx_n, gy_{n-1}, gx_{n-1})) \\ &\quad - \psi(\Theta(gy_n, gx_n, gy_{n-1}, gx_{n-1})) \end{aligned} \right\} \quad (2.13)$$

$$\begin{aligned} \varphi(d(gx_{n+1}, gx_n)) &= \varphi(d(F(x_n, y_n), F(x_{n-1}, y_{n-1}))) \\ &\leq \frac{1}{2} \varphi(\Theta(gx_n, gy_n, gx_{n-1}, gy_{n-1})) \\ &\quad - \psi(\Theta(gx_n, gy_n, gx_{n-1}, gy_{n-1})) \end{aligned}$$

where

$$\Theta(gy_n, gx_n, gy_{n-1}, gx_{n-1}) = \left. \begin{aligned} & \frac{\alpha}{2} [d(gy_n, gy_{n-1}) + d(gx_n, gx_{n-1})] \\ & + \frac{\beta}{2} [d(gy_n, gy_{n+1}) + d(gx_n, gx_{n+1})] \\ & + d(gy_{n-1}, gy_n) + d(gx_{n-1}, gx_n) \\ & + \frac{\gamma}{2} [d(gy_{n-1}, gy_{n+1}) + d(gx_{n-1}, gx_{n+1})] \end{aligned} \right\} \quad (2.14)$$

$$\Theta(gx_n, gy_n, gx_{n-1}, gy_{n-1}) = \left. \begin{aligned} & \frac{\alpha}{2} [d(gx_n, gx_{n-1}) + d(gy_n, gy_{n-1})] \\ & + \frac{\beta}{2} [d(gx_n, gx_{n+1}) + d(gy_n, gy_{n+1})] \\ & + d(gx_{n-1}, gx_n) + d(gy_{n-1}, gy_n) \\ & + \frac{\gamma}{2} [d(gx_{n-1}, gx_{n+1}) + d(gy_{n-1}, gy_{n+1})] \end{aligned} \right\} \quad (2.15)$$

From (2.15) and (2.14), we remark that, for all  $n \geq 1$  :

$$\Theta(gx_n, gy_n, gx_{n-1}, gy_{n-1}) = \Theta(gy_n, gx_n, gy_{n-1}, gx_{n-1}). \quad (2.16)$$

Now, let us set

$$\delta_{n-1} = d(gx_n, gx_{n-1}) + d(gy_n, gy_{n-1}). \quad (2.17)$$

From (2.16), (2.17) and triangular inequality, we get

$$\left. \begin{aligned} \frac{\alpha}{2} \delta_{n-1} \leq \Theta(gx_n, gy_n, gx_{n-1}, gy_{n-1}) &\leq \frac{\alpha}{2} \delta_{n-1} + \frac{\beta}{2} [\delta_n + \delta_{n-1}] \\ &\quad + \frac{\gamma}{2} [\delta_{n-1} + \delta_n] \end{aligned} \right\} \quad (2.18)$$

Now, from (2.18), we have

$$\Theta(gx_n, gy_n, gx_{n-1}, gy_{n-1}) \leq \frac{\alpha + \beta + \gamma}{2} \delta_{n-1} + \frac{\beta + \gamma}{2} \delta_n. \quad (2.19)$$

If there exists  $n_0 \in \mathbb{N}$  such that  $\Theta(gx_{n_0}, gy_{n_0}, gx_{n_0-1}, gy_{n_0-1}) = 0$ , then  $\delta_{n_0-1} = 0$ . Therefore:

$$gx_{n_0} = gx_{n_0-1} = F(x_{n_0-1}, y_{n_0-1})$$

and

$$gy_{n_0} = gy_{n_0-1} = F(y_{n_0-1}, x_{n_0-1}),$$

so, the proof is finished.

From now on, we suppose that

$$\Theta(gx_n, gy_n, gx_{n-1}, gy_{n-1}) > 0 \text{ for all } n \geq 1. \quad (2.20)$$

From (2.12), we obtain

$$\left. \begin{aligned} \varphi(d(gx_{n+1}, gx_n)) + \varphi(d(gy_{n+1}, gy_n)) &\leq \\ \varphi(\Theta(gx_n, gy_n, gx_{n-1}, gy_{n-1})) - 2\psi(\Theta(gx_n, gy_n, gx_{n-1}, gy_{n-1})) &\end{aligned} \right\} \quad (2.21)$$

Using the property of  $\varphi$ , we have

$$\left. \begin{aligned} \varphi(d(gx_{n+1}, gx_n) + d(gy_{n+1}, gy_n)) &\leq \\ \varphi(d(gx_{n+1}, gx_n)) + \varphi(d(gy_{n+1}, gy_n)) &\end{aligned} \right\} \quad (2.22)$$

From (2.21) and (2.22), we have

$$\left. \begin{aligned} \varphi(\delta_n) &\leq \\ \varphi(\Theta(gx_n, gy_n, gx_{n-1}, gy_{n-1})) - 2\psi(\Theta(gx_n, gy_n, gx_{n-1}, gy_{n-1})) &\end{aligned} \right\} \quad (2.23)$$

Therefore, from (2.19) and (2.23) and by the property of  $\varphi$ , we obtain

$$\left. \begin{aligned} \varphi(\delta_n) &\leq \\ \varphi\left(\frac{\alpha + \beta + \gamma}{2} \delta_{n-1} + \frac{\beta + \gamma}{2} \delta_n\right) - 2\psi(\Theta(gx_n, gy_n, gx_{n-1}, gy_{n-1})) &\end{aligned} \right\} \quad (2.24)$$

Now, we claim that

$$\delta_n \leq \delta_{n-1} \text{ for all } n \geq 1. \quad (2.25)$$

Suppose that (2.25) is not true, in this case, there exists  $n_0 \geq 1$  such that

$$\delta_{n_0} > \delta_{n_0-1}, \quad (2.26)$$

then from (2.24) and (2.26) we have

$$\left. \begin{aligned} \varphi(\delta_{n_0}) &\leq \\ \varphi\left(\frac{\alpha + 2\beta + 2\gamma}{2} \delta_{n_0}\right) - 2\psi(\Theta(gx_{n_0}, gy_{n_0}, gx_{n_0-1}, gy_{n_0-1})) &\end{aligned} \right\} \quad (2.27)$$



since  $\frac{\alpha + 2\beta + 2\gamma}{2} < 1$  and since  $\varphi$  is nondecreasing, we get

$$\varphi(\delta_{n_0}) \leq \varphi(\delta_{n_0}) - 2\psi(\Theta(gx_{n_0}, gy_{n_0}, gx_{n_0-1}, gy_{n_0-1})), \tag{2.28}$$

which implies:

$$\psi(\Theta(gx_{n_0}, gy_{n_0}, gx_{n_0-1}, gy_{n_0-1})) = 0,$$

and by the property of  $\psi$ , we have

$$\Theta(gx_{n_0}, gy_{n_0}, gx_{n_0-1}, gy_{n_0-1}) = 0,$$

which is a contradiction to (2.20). Therefore, (2.25) is true.

Now we shall prove that

$$\lim_{n \rightarrow \infty} \delta_{n-1} = 0. \tag{2.29}$$

From (2.25), the sequence  $\{\delta_n\}$  is non-increasing, with 0 as lower bound, thus, there exists  $\delta \geq 0$  such that  $\delta_n \rightarrow \delta$ . We shall show that  $\delta = 0$ . We suppose that  $\delta > 0$ , then from (2.25), (2.21) and (2.27), we have:

$$\left. \begin{aligned} \lim_{n \rightarrow \infty} \frac{\alpha}{2} \delta_n &\leq \limsup_{n \rightarrow \infty} \Theta(gx_n, gy_n, gx_{n-1}, gy_{n-1}) \\ &\leq \limsup_{n \rightarrow \infty} \left[ \frac{\alpha + 2\beta + 2\gamma}{2} \delta_{n-1} \right]. \end{aligned} \right\} \tag{2.30}$$

Since  $\frac{\alpha + 2\beta + 2\gamma}{2} < 1$ , (2.30) implies that

$$\frac{\alpha}{2} \delta \leq \limsup_{n \rightarrow \infty} \Theta(gx_n, gy_n, gx_{n-1}, gy_{n-1}) < \delta. \tag{2.31}$$

So, there exists  $\delta_1 > 0$  and a subsequence  $\{\delta_{n_k}\}$  of  $\{\delta_n\}$  such that

$$\lim_{k \rightarrow \infty} \Theta(gx_{n_k}, gy_{n_k}, gx_{n_k-1}, gy_{n_k-1}) = \delta_1 \leq \delta. \tag{2.32}$$

By the lower semicontinuity of  $\psi$ , we have

$$\psi(\delta_1) \leq \liminf_{k \rightarrow \infty} \psi(\Theta(gx_{n_k}, gy_{n_k}, gx_{n_k-1}, gy_{n_k-1})). \tag{2.33}$$

From (2.23), we have

$$\left. \begin{aligned} \varphi(\delta_{n_k}) &\leq \varphi(\Theta(gx_{n_k}, gy_{n_k}, gx_{n_k-1}, gy_{n_k-1})) \\ &\quad - 2\psi(\Theta(gx_{n_k}, gy_{n_k}, gx_{n_k-1}, gy_{n_k-1})) \end{aligned} \right\} \tag{2.34}$$

thus

$$\left. \begin{aligned} \limsup_{k \rightarrow \infty} \varphi(\delta_{n_k}) &\leq \limsup_{k \rightarrow \infty} \varphi(\Theta(gx_{n_k}, gy_{n_k}, gx_{n_k-1}, gy_{n_k-1})) \\ &\quad - 2 \liminf_{k \rightarrow \infty} \psi(\Theta(gx_{n_k}, gy_{n_k}, gx_{n_k-1}, gy_{n_k-1})), \end{aligned} \right\} \tag{2.35}$$

which implies

$$\varphi(\delta) \leq \varphi(\delta) - 2\psi(\delta_1). \quad (2.36)$$

From (2.36) we obtain  $\psi(\delta_1) = 0$ , thus, by the property of  $\psi$ , we get  $\delta_1 = 0$ , which is a contradiction with the fact that  $\delta > 0$ , therefore  $\delta = 0$ . Now we will prove that  $\{gx_n\}$  and  $\{gy_n\}$  are Cauchy sequences. Suppose to the contrary, that at least one of  $\{gx_n\}$  or  $\{gy_n\}$  is not Cauchy sequence. Then there exists an  $\varepsilon > 0$  for which we can find subsequences  $\{gx_{n(k)}\}$ ,  $\{gx_{m(k)}\}$  of  $\{gx_n\}$  and  $\{gy_{n(k)}\}$ ,  $\{gy_{m(k)}\}$  of  $\{gy_n\}$ , with  $n(k) > m(k) \geq k$ , such that

$$d(gx_{n(k)}, gx_{m(k)}) + d(gy_{n(k)}, gy_{m(k)}) \geq \varepsilon. \quad (2.37)$$

Furthermore, corresponding to  $m(k)$ , we can choose  $n(k)$  as the smallest integer with  $n(k) > m(k) \geq k$  and satisfying (2.37). Then

$$d(gx_{n(k)-1}, gx_{m(k)}) + d(gy_{n(k)-1}, gy_{m(k)}) \leq \varepsilon. \quad (2.38)$$

Using (2.37), (2.38) and the triangular inequality, we have

$$\begin{aligned} \varepsilon &\leq r_k := d(gx_{n(k)}, gx_{m(k)}) + d(gy_{n(k)}, gy_{m(k)}) \\ &\leq d(gx_{n(k)}, gx_{n(k)-1}) + d(gx_{n(k)-1}, gx_{m(k)}) \\ &\quad + d(gy_{n(k)}, gy_{n(k)-1}) + d(gy_{n(k)-1}, gy_{m(k)}) \\ &\leq d(gx_{n(k)}, gx_{n(k)-1}) + d(gy_{n(k)}, gy_{n(k)-1}) + \varepsilon. \end{aligned}$$

Letting  $k \rightarrow \infty$  and using (2.17), we get

$$\lim_{k \rightarrow \infty} r_k = \lim_{k \rightarrow \infty} [d(gx_{n(k)}, gx_{m(k)}) + d(gy_{n(k)}, gy_{m(k)})] = \varepsilon. \quad (2.39)$$

From (2.3) we have

$$\begin{aligned} &\frac{\alpha}{2} [d(gx_{n(k)}, gx_{m(k)}) + d(gy_{n(k)}, gy_{m(k)})] \\ &\leq \Theta(gx_{n(k)}, gy_{n(k)}, gx_{n(k)-1}, gy_{n(k)-1}) \\ &= \frac{\alpha}{2} [d(gx_{n(k)}, gx_{m(k)}) + d(gy_{n(k)}, gy_{m(k)})] \\ &\quad + \frac{\beta}{2} [d(gx_{n(k)}, F(x_{n(k)}, gy_{n(k)})) + d(gy_{n(k)}, F(y_{n(k)}, gx_{n(k)}))] \\ &\quad + d(gx_{m(k)}, F(x_{m(k)}, y_{m(k)})) + d(gy_{m(k)}, F(y_{m(k)}, x_{m(k)}))] \\ &\quad + \frac{\gamma}{2} [d(gx_{m(k)}, F(x_{m(k)}, y_{m(k)})) + d(gy_{n(k)}, F(y_{m(k)}, x_{m(k)}))] \\ &\quad + d(gx_{n(k)}, F(x_{n(k)}, y_{n(k)})) + d(gy_{n(k)}, F(y_{n(k)}, x_{n(k)}))] \end{aligned}$$

Then

$$\left. \begin{aligned}
 & \frac{\alpha}{2} [d(gx_{n(k)}, gx_{m(k)}) + d(gy_{n(k)}, gy_{m(k)})] \\
 & \leq \Theta(gx_{n_k}, gy_{n_k}, gx_{n_k-1}, gy_{n_k-1}) \\
 & = \frac{\alpha}{2} [d(gx_{n(k)}, gx_{m(k)}) + d(gy_{n(k)}, gy_{m(k)})] \\
 & \quad + \frac{\beta}{2} [d(gx_{n(k)}, gx_{n(k)+1}) + d(gy_{n(k)}, gy_{n(k)+1}) \\
 & \quad d(gx_{m(k)}, gx_{m(k)+1}) + d(gy_{m(k)}, gy_{m(k)+1})] \\
 & \quad + \frac{\gamma}{2} [d(gx_{m(k)}, gx_{m(k)+1}) + d(gy_{m(k)}, gy_{m(k)+1}) \\
 & \quad + d(gx_{m(k)}, gx_{n(k)+1}) + d(gy_{m(k)}, gy_{n(k)+1})]
 \end{aligned} \right\} \quad (2.40)$$

From triangular inequality, we obtain

$$\left. \begin{aligned}
 d(gx_{m(k)}, gx_{n(k)+1}) & \leq d(gx_{m(k)}, gx_{m(k)+1}) + d(gx_{m(k)+1}, gx_{n(k)+1}) \\
 d(gy_{m(k)}, gx_{n(k)+1}) & \leq d(gy_{m(k)}, gy_{m(k)+1}) + d(gy_{m(k)+1}, gy_{n(k)+1})
 \end{aligned} \right\} \quad (2.41)$$

From (2.40) and (2.41) we get

$$\left. \begin{aligned}
 \frac{\alpha}{2} r_{n_k} \leq \Theta(gx_{n_k}, gy_{n_k}, gx_{n_k-1}, gy_{n_k-1}) & \leq \frac{\alpha}{2} r_{n_k} + \frac{\beta}{2} (\delta_{n_k} + \delta_{m_k}) \\
 & \quad + \frac{\gamma}{2} (\delta_{m_k} + \delta_{m_k} + r_{n_{k+1}})
 \end{aligned} \right\} \quad (2.42)$$

Taking upper limit when  $k \rightarrow \infty$  and using (2.29), (2.39) and the fact that  $\frac{\alpha}{2} + \frac{\gamma}{2} < 1$ , we get

$$0 < \frac{\alpha}{2} \varepsilon \leq \limsup_{k \rightarrow \infty} \Theta(gx_{n_k}, gy_{n_k}, gx_{n_k-1}, gy_{n_k-1}) \leq \frac{\alpha}{2} \varepsilon + \frac{\gamma}{2} \varepsilon < \varepsilon,$$

this implies that there exist  $\varepsilon_1 > 0$  and two subsequences  $gx_{n_{k_p}}$  and  $gy_{n_{k_p}}$  such that

$$\lim_{p \rightarrow \infty} \Theta(gx_{n_{k_p}}, gy_{n_{k_p}}, gx_{n_{k_p}-1}, gy_{n_{k_p}-1}) = \varepsilon_1 < \varepsilon. \quad (2.43)$$

By the lower semicontinuity of  $\psi$  :

$$\psi(\varepsilon) \leq \liminf_{p \rightarrow \infty} \psi \left( \Theta(gx_{n_{k_p}}, gy_{n_{k_p}}, gx_{n_{k_p}-1}, gy_{n_{k_p}-1}) \right). \quad (2.44)$$

By the triangular inequality

$$\begin{aligned}
 r_k & = d(gx_{n(k)}, gx_{m(k)}) + d(gx_{n(k)}, gx_{m(k)}) \\
 & \leq d(gx_{n(k)}, gx_{n(k)+1}) + d(gx_{n(k)+1}, gx_{m(k)+1}) \\
 & \quad + d(gx_{m(k)}, gx_{m(k)+1}) + d(gy_{n(k)}, gy_{n(k)+1}) \\
 & \quad + d(gy_{n(k)+1}, gy_{m(k)+1}) + d(gy_{m(k)}, gy_{m(k)+1}) \\
 & = \delta_{n_k} + \delta_{m_k} + d(gx_{n(k)+1}, gx_{m(k)+1}) \\
 & \quad + d(gy_{n(k)+1}, gy_{m(k)+1}).
 \end{aligned}$$

Using the property of  $\varphi$ , we have

$$\left. \begin{aligned} \varphi(r_k) &= \varphi[\delta_{n_k} + \delta_{m_k} + d(gx_{n(k)+1}, gx_{m(k)+1}) \\ &\quad + d(gy_{n(k)+1}, gy_{m(k)+1})] \\ &\leq \varphi(\delta_{n_k} + \delta_{m_k}) + \varphi(d(gx_{n(k)+1}, gx_{m(k)+1})) \\ &\quad + \varphi(d(gy_{n(k)+1}, gy_{m(k)+1})). \end{aligned} \right\} \quad (2.45)$$

Since  $n(k) > m(k)$ , hence  $gx_{n(k)} \succeq gx_{m(k)}$  and  $gy_{n(k)} \preceq gy_{m(k)}$ , using (2.2) and (2.4), we obtain

$$\left. \begin{aligned} \varphi(d(gx_{n(k)+1}, gx_{m(k)+1})) &= \varphi(d(F(x_{n(k)}, y_{n(k)}), F(x_{m(k)}, y_{m(k)}))) \\ &\leq \frac{1}{2}\varphi(\theta(x_{n(k)}, y_{n(k)}, x_{m(k)}, y_{m(k)})) \\ &\quad - \psi(\theta(x_{n(k)}, y_{n(k)}, x_{m(k)}, y_{m(k)})). \end{aligned} \right\} \quad (2.46)$$

By the same way, we also have

$$\left. \begin{aligned} \varphi(d(gy_{n(k)+1}, gy_{m(k)+1})) &= \varphi(d(F(y_{n(k)}, x_{n(k)}), F(y_{m(k)}, x_{m(k)}))) \\ &\leq \frac{1}{2}\varphi(\theta(y_{n(k)}, x_{n(k)}, y_{m(k)}, x_{m(k)})) \\ &\quad - \psi(\theta(y_{n(k)}, x_{n(k)}, y_{m(k)}, x_{m(k)})). \end{aligned} \right\} \quad (2.47)$$

From (2.45), (2.46) and (2.47), we obtain

$$\left. \begin{aligned} \varphi(r_{k_p}) &\leq \varphi(\delta_{n_{k_p}} + \delta_{m_{k_p}}) \\ &\quad + \varphi(\theta(y_{n(k)}, x_{n(k)}, y_{m(k)}, x_{m(k)})) \\ &\quad - 2\psi(\theta(y_{n(k)}, x_{n(k)}, y_{m(k)}, x_{m(k)})) \end{aligned} \right\} \quad (2.48)$$

then

$$\begin{aligned} \limsup_{p \rightarrow \infty} \varphi(r_{k_p}) &\leq \limsup_{p \rightarrow \infty} \varphi(\delta_{n_{k_p}} + \delta_{m_{k_p}}) \\ &\quad + \limsup_{p \rightarrow \infty} \varphi(\theta(y_{n(k)}, x_{n(k)}, y_{m(k)}, x_{m(k)})) \\ &\quad - \liminf_{p \rightarrow \infty} 2\psi(\theta(y_{n(k)}, x_{n(k)}, y_{m(k)}, x_{m(k)})), \end{aligned}$$

hence

$$\varphi(\varepsilon) \leq \varphi(0) + \varphi(\varepsilon_1) - 2\psi(\varepsilon_1) \leq \varphi(\varepsilon) - 2\psi(\varepsilon_1).$$

This implies that  $\psi(\varepsilon_1) = 0$  and so  $\varepsilon_1 = 0$ , which is a contradiction. This shows that  $\{gx_n\}$  and  $\{gy_n\}$  are Cauchy sequences. Since  $X$  is a complete metric space, there exist  $x, y \in X$  such that

$$\lim_{n \rightarrow \infty} F(x_n, y_n) = \lim_{n \rightarrow \infty} gx_n = x \quad (2.49)$$

and

$$\lim_{n \rightarrow \infty} F(y_n, x_n) = \lim_{n \rightarrow \infty} gy_n = y. \quad (2.50)$$

Since  $F$  and  $g$  are compatible mappings, we have

$$\lim_{n \rightarrow \infty} d(g(F(x_n, y_n)), F(gx_n, gy_n)) = 0 \tag{2.51}$$

$$\lim_{n \rightarrow \infty} d(g(F(y_n, x_n)), F(gy_n, gx_n)) = 0. \tag{2.52}$$

Now, we show that  $gx = F(x, y)$  and  $gy = F(y, x)$ . Suppose that the assumption (a) holds. For all  $n \geq 0$ , we have

$$d(gx, F(gx_n, gy_n)) \leq d(gx, g(F(x_n, y_n))) + d(g(F(x_n, y_n)), F(gx_n, gy_n)).$$

Taking the limit as  $n \rightarrow \infty$  and using (2.4), (2.49), (2.51) and by using the fact that  $F$  and  $g$  are continuous, we obtain  $d(gx, F(x, y)) = 0$ , hence  $gx = F(x, y)$ . With the same way, we obtain  $d(gy, F(y, x)) = 0$ , hence  $gy = F(y, x)$ . Combining the two results above, we get

$$gx = F(x, y) \text{ and } gy = F(y, x).$$

Finally, we suppose (b) holds. By (2.9) and from (2.49), (2.50), we have  $\{gx_n\}$  is a nondecreasing sequence,  $gx_n \rightarrow x$  and  $\{gy_n\}$  is a nondecreasing sequence,  $gy_n \rightarrow y$  as  $n \rightarrow \infty$ . Hence, by assumption (b), we have for all  $n \geq 0$  :

$$gx_n \preceq x \text{ and } gy_n \succeq y. \tag{2.53}$$

Since  $F$  and  $g$  are compatible mappings and  $g$  is continuous, by (2.51) and (2.52), we have

$$\lim_{n \rightarrow \infty} g(gx_n) = gx = \lim_{n \rightarrow \infty} g(F(x_n, y_n)) = \lim_{n \rightarrow \infty} F(gx_n, gy_n) \tag{2.54}$$

and

$$\lim_{n \rightarrow \infty} g(gy_n) = gy = \lim_{n \rightarrow \infty} g(F(y_n, x_n)) = \lim_{n \rightarrow \infty} F(gy_n, gx_n). \tag{2.55}$$

Now, by triangular inequality, we have

$$d(gx, F(x, y)) \leq d(gx, g(gx_{n+1})) + d(g(gx_{n+1}), F(x, y)),$$

taking  $n \rightarrow \infty$  in the above inequality, using (2.4) and (2.48) we have

$$\left. \begin{aligned} d(gx, F(x, y)) &\leq \lim_{n \rightarrow \infty} d(gx, g(gx_{n+1})) + \lim_{n \rightarrow \infty} d(g(gx_{n+1}), F(x, y)) \\ &\leq \lim_{n \rightarrow \infty} d(F(gx_n, gy_n), F(x, y)) \end{aligned} \right\} \tag{2.56}$$

Using the property of  $\varphi$ , we get

$$\varphi(d(gx, F(x, y))) \leq \lim_{n \rightarrow \infty} \varphi(d(F(gx_n, gy_n), F(x, y))).$$

Since the mapping  $g$  is monotone and increasing, using (2.2), (2.53) and (2.56), we have, for all  $n \geq 0$  :

$$\begin{aligned} \varphi(d(gx, F(x, y))) &\leq \limsup_{n \rightarrow \infty} \frac{1}{2} \varphi(\Theta(g(gx_n), g(gy_n), gx, gy)) \\ &\quad - \liminf_{n \rightarrow \infty} \psi(\Theta(g(gx_n), g(gy_n), gx, gy)), \end{aligned}$$

$$\limsup_{n \rightarrow \infty} \frac{1}{2} \varphi (\Theta(g(gx_n), g(gy_n), gx, gy)) = \frac{1}{2} \varphi (\Theta(gx, gy, gx, gy))$$

and

$$\psi (\Theta(gx, gy, gx, gy)) \leq \liminf_{n \rightarrow \infty} \psi (\Theta(g(gx_n), g(gy_n), gx, gy)),$$

then

$$\left. \begin{aligned} \varphi (d(gx, F(x, y))) &\leq \frac{1}{2} \varphi (\Theta(gx, gy, gx, gy)) \\ &- \psi (\Theta(gx, gy, gx, gy)) \end{aligned} \right\} \quad (2.57)$$

With the same way and by using (2.16), we prove that

$$\left. \begin{aligned} \varphi (d(gy, F(y, x))) &\leq \frac{1}{2} \varphi (\Theta(gx, gy, gx, gy)) \\ &- \psi (\Theta(gx, gy, gx, gy)) \end{aligned} \right\} \quad (2.58)$$

$$\left. \begin{aligned} \Theta(gx, gy, gx, gy) &= (\beta + \gamma) (d(gx, F(x, y)) + d(gy, F(y, x))) \\ &\leq d(gx, F(x, y)) + d(gy, F(y, x)) \end{aligned} \right\} \quad (2.59)$$

and  $\varphi$  is nondecreasing, then from (2.57), (2.58), (2.59) and the property of  $\varphi$ , we get

$$\begin{aligned} \varphi (d(gx, F(x, y)) + d(gy, F(y, x))) &\leq \varphi (d(gx, F(x, y)) + d(gy, F(y, x))) \\ &- 2\psi (\Theta(gx, gy, gx, gy)) \end{aligned}$$

Then

$$\Theta(gx, gy, gx, gy) = 0 = (\beta + \gamma) (d(gx, F(x, y)) + d(gy, F(y, x))).$$

This implies that

$$d(gx, F(x, y)) = 0 \quad \text{and} \quad d(gy, F(y, x)) = 0.$$

Hence  $gx = F(x, y)$  and  $gy = F(y, x)$ . Thus we proved that  $F$  and  $g$  have a coupled coincidence point.  $\square$

### 3 Uniqueness of Coupled Coincidence Point.

In this section, we will prove the uniqueness of the coupled coincidence point. Note that if  $(X, \preceq)$  is a partially ordered set, then we endow the product  $X \times X$ , with the following partial order relation, for all  $(x, y), (u, v) \in X \times X$  :

$$(x, y) \preceq (u, v) \text{ if, and only if } x \preceq u \text{ and } y \succeq v.$$

**Theorem 3.1.** *In addition to hypotheses of theorem 2.1, Suppose that for every  $(x, y), (z, t)$  in  $X \times X$ , there exist a element  $(u, v)$  in  $X \times X$  that is comparable to  $(x, y)$  and  $(z, t)$ , then  $F$  has a coupled coincidence point.*

*Proof.* Suppose  $(x, y)$  and  $(z, t)$  are coupled coincidence points of  $F$  and  $g$ , that is  $gx = F(x, y)$ ,  $gy = F(y, x)$ ,  $gz = F(z, t)$  and  $gt = F(t, z)$ . We are going to show that  $gx = gz$  and  $gy = gt$ . By assumption, there exists  $(u, v) \in X \times X$ , comparable to  $(x, y)$  and  $(z, t)$ . We define sequences  $\{gx_n\}$  and  $\{gy_n\}$  as follows:

$$u_0 = u, v_0 = v \quad gu_{n+1} = F(u_n, v_n) \text{ and } gv_{n+1} = F(v_n, u_n) \text{ for all } n \geq 1.$$

Since  $(u, v)$  is comparable with  $(x, y)$ , we may assume that

$$(x, y) \succeq (u, v) = (u_0, v_0).$$

Using the mathematical induction, it is easy to prove that

$$(x, y) \succeq (u_n, v_n) \text{ for all } n \geq 1. \tag{3.1}$$

Using (2.2) and (3.1), we have

$$\left. \begin{aligned} \varphi(d(gx, gu_{n+1})) &= \varphi(d(F(x, y), F(u_n, v_n))) \\ &\leq \frac{1}{2}\varphi(\theta(gx, gy, gu_n, gv_n)) \\ &\quad - \psi(\theta(gx, gy, gu_n, gv_n)) \end{aligned} \right\} \tag{3.2}$$

We have

$$\theta(gx, gy, gu_n, gv_n) = \theta(gv_n, gu_n, gy, gx). \tag{3.3}$$

Indeed

$$\begin{aligned} \theta(gx, gy, gu_n, gv_n) &= \frac{\alpha}{2} [d(gx, gu_n) + d(gy, gv_n)] \\ &\quad + \frac{\beta}{2} [d(gu_n, gu_{n+1}) + d(gv_n, gv_{n+1})] \\ &\quad + \frac{\gamma}{2} [d(gx, gu_{n+1}) + d(gy, gv_{n+1}) \\ &\quad + d(gx, gu_n) + d(gy, gv_n)] \end{aligned}$$

and

$$\begin{aligned} \theta(gv_n, gu_n, gy, gx) &= \frac{\alpha}{2} [d(gu_n, gx) + d(gv_n, gy)] \\ &\quad + \frac{\beta}{2} [d(gv_n, gv_{n+1}) + d(gu_n, gu_{n+1})] \\ &\quad + \frac{\gamma}{2} [d(gv_n, gy) + d(gu_n, gx) \\ &\quad + d(gy, gv_{n+1}) + d(gx, gu_{n+1})], \end{aligned}$$

then

$$\left. \begin{aligned} \varphi(d(gv_{n+1}, gy)) &= \varphi(d(F(v_n, u_n), F(y, x))) \\ &\leq \frac{1}{2}\varphi(\theta(gx, gy, gu_n, gv_n)) \\ &\quad - \psi(\theta(gx, gy, gu_n, gv_n)) \end{aligned} \right\} \tag{3.4}$$

Using (3.2), (3.4) and the property of  $\varphi$ , we get

$$\begin{aligned} \varphi(d(gx, gu_{n+1}) + d(gv_{n+1}, gy)) &\leq \varphi(d(gx, gu_{n+1})) + \varphi(d(gv_{n+1}, gy)) \\ &\leq \varphi(\theta(gx, gy, gu_n, gv_n)) \\ &\quad - 2\psi(\theta(gx, gy, gu_n, gv_n)). \end{aligned}$$

Since  $\psi$  is nonnegative, we obtain

$$\varphi(d(gx, gu_{n+1}) + d(gv_{n+1}, gy)) \leq \varphi(\theta(gx, gy, gu_n, gv_n)).$$

Thus, since  $\varphi$  is nondecreasing, it follows

$$d(gx, gu_{n+1}) + d(gv_{n+1}, gy) \leq \theta(gx, gu_n, gy, gv_n),$$

hence

$$\left. \begin{aligned} d(gx, gu_{n+1}) + d(gv_{n+1}, gy) &\leq \frac{\alpha}{2} [d(gx, gu_n) + d(gy, gv_n)] \\ &\quad + \frac{\beta}{2} [d(gu_n, gu_{n+1}) + d(gv_n, gv_{n+1})] \\ &\quad + \frac{\gamma}{2} [d(gx, gu_{n+1}) + d(gy, gv_{n+1}) \\ &\quad + d(gx, gu_n) + d(gy, gv_n)] \end{aligned} \right\} \quad (3.5)$$

By using the triangular inequality

$$d(gu_n, gu_{n+1}) \leq d(gu_n, gx) + d(gx, gu_{n+1}),$$

$$d(gv_n, gv_{n+1}) \leq d(gv_n, gy) + d(gy, gv_{n+1}),$$

we get from (3.5)

$$d(gx, gu_{n+1}) + d(gv_{n+1}, gy) \leq \left( \frac{\alpha + \beta + \gamma}{1 - \beta - \gamma} \right) [d(gx, gu_n) + d(gy, gv_n)] \quad (3.6)$$

By iteration, we get

$$d(gx, gu_{n+1}) + d(gv_{n+1}, gy) \leq \left( \frac{\alpha + \beta + \gamma}{1 - \beta - \gamma} \right)^{n+1} [d(gx, gu_0) + d(gy, gv_0)] \quad (3.7)$$

since  $\frac{\alpha + \beta + \gamma}{1 - \beta - \gamma} < 1$ , (3.7) implies that

$$\lim_{n \rightarrow \infty} [d(gx, gu_{n+1}) + d(gv_{n+1}, gy)] = 0 \quad (3.8)$$

Similarly, we show that

$$\lim_{n \rightarrow \infty} [d(gz, gu_{n+1}) + d(gv_{n+1}, gt)] = 0. \quad (3.9)$$

Using (3.8) and (3.9), we have  $gx = gz$  and  $gy = gt$ .  $\square$

## 4 Application.

Set  $Y = \{\psi : \mathbb{R}^+ \rightarrow \mathbb{R}^+, \psi \text{ is a Lebesgue integrable which is nonnegative, satisfies } \int_0^\varepsilon \psi(t)dt > 0, \text{ for each } \varepsilon > 0 \text{ and subadditive, that is: } \int_0^{\varepsilon+\mu} \psi(t)dt \leq \int_0^\varepsilon \psi(t)dt + \int_0^\mu \psi(t)dt \text{ for all } \varepsilon > 0 \text{ and } \mu > 0\}$ .



**Example 4.1.** We consider  $\psi(x) = \frac{1}{1+x}$ ,  $\psi : \mathbb{R}^+ \rightarrow \mathbb{R}^+$ ,  $\psi$  is a Lebesgue integrable which is nonnegative, satisfies  $\int_0^\varepsilon \psi(t)dt = \ln(1 + \varepsilon) > 0$ , for each  $\varepsilon > 0$ .  $\psi$  is subadditive, indeed: since  $1 + \varepsilon + \mu \leq 1 + \varepsilon + \mu + \varepsilon\mu$ , then

$$\begin{aligned} \int_0^{\varepsilon+\mu} \psi(t)dt = \ln(1 + \varepsilon + \mu) &\leq \ln(1 + \varepsilon)(1 + \mu) \\ &= \ln(1 + \varepsilon) + \ln(1 + \mu) \\ &= \int_0^\varepsilon \psi(t)dt + \int_0^\mu \psi(t)dt. \end{aligned}$$

This shows that  $\psi$  is an example of subadditive, non-negative, Lebesgue integrable function.

**Theorem 4.2.** Let  $(X, \preceq)$  be a partially ordered set and suppose there exists a metric  $d$  on  $X$  such that  $(X, d)$  is a complete metric space. Let  $F : X \times X \rightarrow X$  be a continuous mapping having the mixed monotone property on  $X$  such that there exist two elements  $x_0, y_0 \in X$  with

$$gx_0 \preceq F(x_0, y_0) \quad \text{and} \quad gy_0 \succeq F(y_0, x_0).$$

Suppose there exist  $\varphi \in \Phi$  and  $\psi \in \Psi_1$  such that

$$\int_0^{\varphi(d(F(x,y), F(u,v)))} \chi(t)dt \leq \int_0^{\frac{1}{2}\varphi(\Theta(gx,gy,gu,gv))} \chi(t)dt - \int_0^{\psi(\Theta(gx,gy,gu,gv))} \chi(t)dt$$

for all  $gx \succeq gu$  and  $gy \preceq gv$ .

$$\begin{aligned} \Theta(gx, gy, gu, gv) &= \frac{\alpha}{2} [d(gx, gu) + d(gy, gv)] \\ &\quad + \frac{\beta}{2} [d(gx, F(x, y)) + d(gy, F(y, x)) \\ &\quad + d(gu, F(u, v)) + d(gv, F(v, u))] \\ &\quad + \frac{\gamma}{2} [d(gx, F(u, v)) + d(gy, F(v, u)) \\ &\quad + d(gu, F(x, y)) + d(gv, F(y, x))] \end{aligned}$$

where  $\alpha > 0$  and  $\beta, \gamma \geq 0$  such that  $\alpha + 2\beta + 2\gamma < 2$ . Suppose  $F(X \times X) \subset g(X)$ ,  $g$  continuous and compatible with  $F$  also suppose either

(a)  $F$  is continuous or

(b)  $X$  has the following property

- (i) If a nondecreasing sequence  $\{x_n\} \rightarrow x$ , then  $x_n \preceq x$ , for all  $n \geq 1$ ,
- (ii) If a non-increasing sequence  $\{y_n\} \rightarrow y$ . then  $y_n \succeq y$ , for all  $n > 1$ ,

then there exist  $x, y \in X$  such that  $gx = F(x, y)$  and  $gy = F(y, x)$ . That is  $F$  and  $g$  have a coupled coincidence point in  $X$ .

*Proof.* Define  $\Lambda : \mathbb{R}^+ \rightarrow \mathbb{R}^+$  by  $\Lambda(\varepsilon) = \int_0^\varepsilon \psi(t)dt$ , where  $\psi \in Y$ . Thus  $\Lambda$  is continuous and nondecreasing with  $\Lambda(0) = 0$ . Then 3.1 becomes

$$\Lambda(\varphi(d(F(x, y), F(u, v)))) \leq \frac{1}{2}\Lambda(\varphi(\Theta(gx, gy, gu, gv))) - \Lambda(\psi(\Theta(gx, gy, gu, gv)))$$

which further can be written as

$$\varphi_1(d(F(x, y), F(u, v))) \leq \frac{1}{2}\varphi_1(\Theta(gx, gy, gu, gv)) - \psi_1(\Theta(gx, gy, gu, gv))$$

where  $\varphi_1 = \Lambda \circ \varphi$  and  $\psi_1 = \Lambda \circ \psi$ , hence by Theorem 2.1, we have the results.  $\square$

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(Received 30 August 2012)

(Accepted 12 March 2015)