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Stability Properties of Positive Solutions to a Quasilinear Elliptic Equation Involving the *p*-Laplacian and Indefinite Weight

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Abstract : In this note, we discuss the stability and instability results of positive solutions for the following reaction-diffusion equation

$$\begin{cases} -\Delta_p u = m(x)u^{p-1} - u^{\gamma-1} - ch(x) & \text{in } \Omega, \\ Bu = 0 & \text{on } \partial\Omega, \end{cases}$$
(0.1)

where $\Delta_p u = \operatorname{div}(|\nabla u|^{p-2}\nabla u)$ is the *p*-Laplacian operator, p > 1, $\gamma < p$, Ω is a bounded domain in $\mathbb{R}^N(N \geq 1)$ with smooth boundary, $Bu(x) = \alpha g(x)u(x) + (1-\alpha)\frac{\partial u(x)}{\partial n}$ where $\alpha \in [0,1]$ is a constant, $g: \partial\Omega \longrightarrow \mathbb{R}^+$ with g = 1 when $\alpha = 1$, i.e., the boundary condition may be of Dirichlet, Neumann or mixed type, c is a positive constant and the weight functions m(x) satisfies $m(x) \in C(\Omega)$ and m(x) > 1 for $x \in \Omega$ and $h: \overline{\Omega} \longrightarrow \mathbb{R}$ is a $C^{1,\alpha}(\overline{\Omega})$ function satisfying h(x) > 0 for $x \in \Omega$, max h(x) = 1 for $x \in \overline{\Omega}$ and h(x) = 0 for $x \in \partial\Omega$. Here u is the population density $m(x)u^{p-1} - u^{\gamma-1}$ represents the logistic growth and ch(x) represents the constant yield harvesting rate. we shall establish that every positive solution is linearly unstable.

Keywords : *p*-Laplacian; diffusive logistic equation; linearized stability; harvesting.

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1 Introduction

This paper deals with the stability properties of positive stationary solutions for nonlinear elliptic systems of the form

$$\begin{cases} -\Delta_p u = m(x)u^{p-1} - u^{\gamma-1} - ch(x) & \text{in } \Omega, \\ Bu = 0 & \text{on } \partial\Omega, \end{cases}$$
(1.1)

where $\Delta_p u = \operatorname{div}(|\nabla u|^{p-2}\nabla u)$ is the *p*-Laplacian operator $p > 1, \gamma < p, \Omega$ is a bounded domain in $\mathbb{R}^N(N \ge 1)$ with smooth boundary, $Bu(x) = \alpha g(x)u(x) + (1 - \alpha)\frac{\partial u(x)}{\partial n}$ where $\alpha \in [0, 1]$ is a constant, $g: \partial\Omega \longrightarrow \mathbb{R}^+$ with g = 1 when $\alpha = 1$, i.e., the boundary condition may be of Dirichlet, Neumann or mixed type, c is a positive constant and the weight functions m(x) satisfies $m(x) \in C(\Omega)$ and m(x) > 1 for $x \in \Omega$ and $h: \overline{\Omega} \longrightarrow \mathbb{R}$ is a $C^{1,\alpha}(\overline{\Omega})$ function satisfying h(x) > 0 for $x \in \Omega$, max h(x) = 1 for $x \in \overline{\Omega}$ and h(x) = 0 for $x \in \partial\Omega$. Here u is the population density $m(x)u^{p-1} - u^{\gamma-1}$ represents the logistic growth and ch(x) represents the constant yield harvesting rate (see [1, 2, 3, 4]). we shall prove the instability of solution u by showing that the principal eigenvalue μ_1 of the equation linearized about u is negative; the instability of u then follows from the well-known principle of linearized stability (see [5]). For existence results of positive solutions for Eq(1.1) (see [6]) We recall that if u be any non-negative solution of

$$\begin{cases} -\Delta_p u = g(x, u) & \text{in } \Omega, \\ u = 0 & \text{on } \partial\Omega, \end{cases}$$
(1.2)

then the linearized equation about u is

$$\begin{cases} -(p-1)\operatorname{div}(|\nabla u|^{p-2}\nabla\phi) - g_u(x,u)\phi = \mu\phi & \text{in }\Omega,\\ \phi = 0 & \text{on }\partial\Omega, \end{cases}$$
(1.3)

where $g_u(x, u)$ denotes the partial derivative of g(x, u) with respect to u and μ is eigenvalue of the operator Δ_p . Eq. (4) obtained from the formal derivative of the operator Δ_p .

Definition 1.1. we call a solution u of (1.1) a *linearly stable solution* if all eigenvalues of (1.1) are strictly positive, which can be *inferred* if the principal eigenvalue $\mu_1 > 0$. Otherwise, u is *linearly unstable*.

2 Main Results

These are the main results of the paper. Here we would establish instability (stability) of non-trivial stationary solution u of the equation (1.1) directly Stability Properties of Positive Solutions to a Quasilinear Elliptic Equation ... 77

by showing that the principle eigenvalue μ_1 of its linearization is negative (positive). The instability (stability) of u then follows from the well-known principle of linearized stability (see [5]).

Our main result is formulated in the following theorem.

Theorem 2.1. Every positive solution of (1.1) is linearly unstable.

Proof. From (4) the linearized equation about u is

$$-(p-1)\operatorname{div}(|\nabla u|^{p-2}\nabla\phi) - [m(x)(p-1)u^{p-2} - (\gamma-1)u^{\gamma-2}]\phi = \mu\phi, \quad (2.1)$$

$$B\phi = 0. \tag{2.2}$$

Let μ_1 be the principal eigenvalue and let $\psi(x) > 0$ be a corresponding eigenfunction. Multiplying (1) by $(p-1)\psi(x)$ and (5) by u, then subtracting and integrating over Ω , we obtain

$$(p-1) \int_{\Omega} \left[u(x) \operatorname{div}(|\nabla u(x)|^{p-2} \nabla \psi(x)) - \psi(x) \operatorname{div}(|\nabla u(x)|^{p-2} \nabla u(x)) \right] dx + \int_{\Omega} \left[m(x)(p-1)u(x)^{p-1} - (\gamma-1)u(x)^{\gamma-1}) \right] \psi(x) dx + \int_{\Omega} (p-1)ch(x)\psi(x) dx = -\mu_1 \int_{\Omega} (u(x)\psi(x)) dx$$

$$(2.3)$$

But by using the Green's first identity we obtain

$$\begin{split} \int_{\Omega} u \operatorname{div}(|\nabla u|^{p-2} \nabla \psi) dx &= -\int_{\Omega} |\nabla u|^{p-2} (u \Delta \psi) dx + \int_{\Omega} u \nabla (|\nabla u|^{p-2}) \nabla \psi \\ &= -\int_{\Omega} \nabla (u |\nabla u|^{p-2}) \nabla \psi (x) dx + \int_{\Omega} u \nabla (|\nabla u|^{p-2}) \nabla \psi \\ &+ \int_{\partial \Omega} u |\nabla u|^{p-2} (\frac{\partial \psi}{\partial n}) dS \\ &= \int_{\partial \Omega} u |\nabla u|^{p-2} (\frac{\partial \psi}{\partial n}) dS - \int_{\Omega} \nabla u (|\nabla u|^{p-2}) \nabla \psi \quad (2.4) \end{split}$$

and

$$\begin{split} \int_{\Omega} \psi \operatorname{div}(|\nabla u|^{p-2} \nabla u) dx &= -\int_{\Omega} |\nabla u|^{p-2} (\psi \Delta u) dx + \int_{\Omega} \psi \nabla (|\nabla u|^{p-2}) \nabla u \\ &= -\int_{\Omega} \nabla (\psi |\nabla u|^{p-2}) \nabla u(x) dx + \int_{\Omega} \psi \nabla (|\nabla u|^{p-2}) \nabla u \\ &+ \int_{\partial \Omega} \psi |\nabla u|^{p-2} (\frac{\partial u}{\partial n}) dS \\ &= \int_{\partial \Omega} \psi |\nabla u|^{p-2} (\frac{\partial u}{\partial n}) dS - \int_{\Omega} \nabla u(|\nabla u|^{p-2}) \nabla \psi \quad (2.5) \end{split}$$

By using (2.4) and (2.5) in (2.3) and hypothesis we get

$$-\mu_1 \int_{\Omega} (u(x)\psi(x))dx = \int_{\Omega} \left[m(x)(p-1)u(x)^{p-1} - (\gamma-1)u(x)^{\gamma-1}) \right] \psi(x)dx + \int_{\Omega} (p-1)ch(x)\psi(x)dx + \int_{\partial\Omega} |\nabla u|^{p-2} \left[u(\frac{\partial\psi}{\partial n}) - \psi(s)(\frac{\partial u}{\partial n}) \right] dS$$

We notice that $(\alpha = 1)$ then h = 1 we have Bu = u = 0 for $x \in \partial \Omega$ and also we have $\psi = 0$ for $x \in \partial \Omega$. Hence

$$\int_{\partial\Omega} |\nabla u|^{p-2} [u(\frac{\partial\psi}{\partial n}) - \psi(s)(\frac{\partial u}{\partial n})] dS = 0$$

and when $\alpha \neq 1$ we have

$$\int_{\partial\Omega} |\nabla u|^{p-2} \left[u(\frac{\partial\psi}{\partial n}) - \psi(s)(\frac{\partial u}{\partial n}) \right] dS = \int_{\partial\Omega} \left\{ \frac{\alpha h\psi}{(1-\alpha)} \right\} (u-u) dS = 0$$

then we get

$$\begin{aligned} -\mu_1 \int_{\Omega} (u(x)\psi(x))dx &= \int_{\Omega} \left[m(x)(p-1)u(x)^{p-1} - (\gamma-1)u(x)^{\gamma-1}) \right] \psi(x)dx \\ &+ \int_{\Omega} (p-1)ch(x)\psi(x)dx > 0 \end{aligned}$$

But $\psi > 0$ and u > 0 in Ω and Hence it is easy to see that $\mu_1 < 0$. Then the result follows (see [5]).

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