



On $(LCS)_{2n+1}$ -Manifolds Satisfying Certain Conditions on the Concircular Curvature Tensor

Sunil Kumar Yadav^{†,1}, Praduman Kumar Dwivedi[‡] and Dayalal Suthar[†]

[†]Department of Mathematics
Alwar Institute of Engineering & Technology
North Ext., MIA, Alwar, Rajasthan, India
e-mail : prof_sky16@yahoo.com,
dd_suthar@yahoo.co.in

[‡]Department of Mathematics,
Institute of Engineering & Technology
North Ext., MIA, Alwar, Rajasthan, India
e-mail : drpkdwivedi@yahoo.co.in

Abstract : We classify Lorentzian concircular structure manifolds, which satisfy the condition $\tilde{C}(\xi, X) \cdot \tilde{C} = 0$, $\tilde{C}(\xi, X) \cdot R = 0$, $\tilde{C}(\xi, X) \cdot S = 0$ and $\tilde{C}(\xi, X) \cdot C = 0$.

Keywords : $(LCS)_{2n+1}$ -manifold; Concircular curvature tensor; Weyl Conformal curvature tensor; Einstein manifolds.

2010 Mathematics Subject Classification : 53C25.

1 Introduction

An $(2n + 1)$ -dimensional Lorentzian manifold M is smooth connected para contact Hausdorff manifold with Lorentzian metric g , that is, M admits a smooth symmetric tensor field g of type $(0, 2)$ such that for each point $p \in M$, the tensor $g_p : T_p M \times T_p M \rightarrow R$ is a non degenerate inner

¹Corresponding author email: prof_sky16@yahoo.com (S.K. Yadav)

product of signature $(-, +, \dots, +)$ where T_pM denotes the tangent space of M at p and R is the real number space. In a Lorentzian manifold (M, g) a vector field ρ defined by

$$g(X, \rho) = A(X)$$

for any vector field $X \in \chi(M)$ is said to be *concircular vector field* [1], if

$$(\nabla_X A)(Y) = \alpha [g(X, Y) + \omega(X)A(Y)]$$

where α is a non zero scalar function, A is a 1-form and ω is a closed 1-form.

Let M be a Lorentzian manifold admitting a unit time like concircular vector field ξ , called the characteristic vector field of the manifold. Then we have

$$g(\xi, \xi) = -1 \quad (1.1)$$

Since ξ is the unit concircular vector field, there exists a non-zero 1-form such that

$$g(X, \xi) = \eta(X) \quad (1.2)$$

and hence the equation

$$(\nabla_X \eta)(Y) = \alpha [g(X, Y) + \eta(X)\eta(Y)] \quad (\alpha \neq 0) \quad (1.3)$$

holds for all vector field X, Y , where ∇ denotes the operator of covariant differentiation with respect to Lorentzian metric g and α is a non zero scalar function satisfying

$$(\nabla_X \alpha) = (X\alpha) = \rho\eta(X), \quad (1.4)$$

where ρ being a scalar function. If we put

$$\phi X = \frac{1}{\alpha} \nabla_X \xi \quad (1.5)$$

Then from (1.3) and (1.5), we have

$$\phi^2 X = X + \eta(X)\xi, \quad (1.6)$$

from which it follows that ϕ is a symmetric $(1, 1)$ -tensor. Thus the Lorentzian manifold M together with unit time like concircular vector field ξ , its associate 1-form η and $(1, 1)$ -tensor field ϕ is said to be Lorentzian concircular structure manifolds (briefly $(LCS)_{2n+1}$ -manifold) [2]. In particular if $\alpha = 1$, then the manifold becomes LP-Sasakian structure of Matsumoto [3].

2 Preliminaries

A differentiable manifold M of dimension $(2n + 1)$ is called $(LCS)_{2n+1}$ -manifold if it admits a $(1, 1)$ -tensor ϕ , a contravariant vector field ξ , a covariant vector field η and a Lorentzian metric g which satisfy the following

$$\eta(\xi) = -1, \tag{2.1}$$

$$\phi^2 = I + \eta \otimes \xi, \tag{2.2}$$

$$g(\phi X, \phi Y) = g(X, Y) + \eta(X)\eta(Y), \tag{2.3}$$

$$g(X, \xi) = \eta(X), \tag{2.4}$$

$$\phi\xi = 0, \quad \eta(\phi X) = 0. \tag{2.5}$$

for all X, Y in TM . Also in a $(LCS)_{2n+1}$ -manifold the following relations are satisfied [4].

$$\eta(R(X, Y)Z) = (\alpha^2 - \rho) [g(Y, Z)\eta(X) - g(X, Z)\eta(Y)], \tag{2.6}$$

$$R(X, Y)\xi = (\alpha^2 - \rho) [\eta(Y)X - \eta(X)Y], \tag{2.7}$$

$$R(\xi, X)Y = (\alpha^2 - \rho) [g(X, Y)\xi - \eta(Y)X], \tag{2.8}$$

$$R(\xi, X)\xi = (\alpha^2 - \rho) [\eta(X)\xi + X], \tag{2.9}$$

$$(\nabla_X \phi)(Y) = \alpha [g(X, Y)\xi + 2\eta(X)\eta(Y)\xi + \eta(Y)X], \tag{2.10}$$

$$S(X, \xi) = 2n(\alpha^2 - \rho) [\eta(X)], \tag{2.11}$$

$$S(\phi X, \phi Y) = S(X, Y) + 2n(\alpha^2 - \rho)\eta(X)\eta(Y). \tag{2.12}$$

Definition 2.1. A Lorentzian concircular structure manifold is said to be η -Einstein [5] if the Ricci operator Q satisfies

$$Q = aId + b\eta \otimes \xi,$$

where a and b are smooth functions on the manifolds, In particular if $b = 0$, then M is an Einstein manifolds.

Let (M, g) be an n -dimensional Riemannian manifold, then the Concircular curvature tensor C and the Weyl Conformal curvature tensor C are defined by [6]:

$$\tilde{C}(X, Y)Z = R(X, Y)Z - \frac{r}{n(n-1)} [g(Y, Z)X - g(X, Z)Y], \tag{2.13}$$

$$C(X, Y)Z = R(X, Y)Z - \frac{1}{(n-2)} [S(Y, Z)X - S(X, Z)Y + g(Y, Z)QX - g(X, Z)QY] + \frac{r}{n(n-1)} [g(Y, Z)X - g(X, Z)Y], \tag{2.14}$$

for all $X, Y, Z \in TM$, respectively, where r is the scalar curvature of M .

3 Main Results

In this section, we obtain a necessary and sufficient condition for $(LCS)_{2n+1}$ -manifolds satisfying the derivation conditions $\tilde{C}(\xi, X) \cdot \tilde{C} = 0$, $\tilde{C}(\xi, X) \cdot R = 0$, $\tilde{C}(\xi, X) \cdot S = 0$ and $\tilde{C}(\xi, X) \cdot C = 0$.

Theorem 3.1. *An $(2n + 1)$ -dimensional Lorentzian concircular structure manifold M satisfies*

$$\tilde{C}(\xi, X) \cdot \tilde{C} = 0$$

if and only if either the scalar curvature r of M is $r = 2n(2n + 1)$ or M is locally isometric to the Hyperbolic sphere $H^{2n+1}(\rho - \alpha^2)$.

Proof. In a Lorentzian concircular structure manifold M , we have

$$\tilde{C}(\xi, Y)Y = \left[(\alpha^2 - \rho) - \frac{r}{n(n-1)} \right] \{g(X, Y)\xi - \eta(X)Y\}, \quad (3.1)$$

$$\tilde{C}(X, Y)\xi = \left[(\alpha^2 - \rho) - \frac{r}{n(n-1)} \right] \{\eta(Y)X - \eta(X)Y\}. \quad (3.2)$$

The condition $\tilde{C}(\xi, X) \cdot \tilde{C} = 0$ implies that

$$\tilde{C}(\xi, U)\tilde{C}(X, Y)\xi - \tilde{C}(\tilde{C}(\xi, U)X, Y)\xi - \tilde{C}(X, \tilde{C}(\xi, U)Y)\xi = 0.$$

In view of (3.2), we get

$$\begin{aligned} 0 = & \left[(\alpha^2 - \rho) - \frac{r}{n(n+1)} \right] \times [g(U, \tilde{C}(X, Y)\xi)\xi - \tilde{C}(X, Y)\xi\eta(U) \\ & - g(U, X)\tilde{C}(\xi, Y)\xi + \eta(X)\tilde{C}(U, Y)\xi - g(U, Y)\tilde{C}(X, \xi)\xi \\ & + \eta(Y)\tilde{C}(X, U)\xi - \tilde{C}(X, Y)U]. \end{aligned}$$

Using (3.1), we have

$$\begin{aligned} 0 = & \left[(\alpha^2 - \rho) - \frac{r}{n(n+1)} \right] \\ & \times [\tilde{C}(X, Y)U - \left((\alpha^2 - \rho) - \frac{r}{n(n+1)} \right) (g(U, Y)X - g(U, X)Y)]. \end{aligned}$$

Therefore either the scalar curvature $r = 2n(2n + 1)(\alpha^2 - \rho)$ or

$$\left[\tilde{C}(X, Y)U - \left((\alpha^2 - \rho) - \frac{r}{n(n+1)} \right) (g(U, Y)X - g(U, X)Y) \right] = 0.$$

In view of (2.13), we get

$$R(X, Y)U = (\alpha^2 - \rho) [g(Y, U)X - g(X, U)Y]$$

This equation implies that M is of constant curvature $(\rho - \alpha^2)$. Consequently it is locally isometric to the Hyperbolic space $H^{2n+1}(\rho - \alpha^2)$.

Conversely, if it has the scalar curvature $r = 2n(2n + 1)(\alpha^2 - \rho)$ then from (3.2) it follows that $\tilde{C}(\xi, X) = 0$. Similarly, in the second case, since constant $r = 2n(2n + 1)(\alpha^2 - \rho)$, therefore again we get $\tilde{C}(\xi, X) = 0$. \square

Using the fact $\tilde{C}(\xi, X) \cdot R = 0$, $\tilde{C}(\xi, X)$ is acting as a derivation, we have the following a corollary.

Corollary 3.2. *An $(2n + 1)$ -dimensional Lorentzian concircular structure manifold M satisfies*

$$\tilde{C}(\xi, X) \cdot R = 0$$

if and only if either M is locally isometric to the Hyperbolic sphere $H^{2n+1}(\rho - \alpha^2)$ or M has the scalar curvature $r = 2n(2n + 1)$.

Theorem 3.3. *Let (M, g) be an $(2n+1)$ -dimensional Riemannian manifold. Then $R \cdot \tilde{C} = R \cdot R$*

Proof. Let $X, Y, U, V, W \in TM$. Then

$$\begin{aligned} (R(X, Y)\tilde{C})(U, V, W) &= R(X, Y)\tilde{C}(U, V)W - \tilde{C}(R(X, Y)U, V)W \\ &\quad - \tilde{C}(U, R(X, Y)V)W - \tilde{C}(U, V)R(X, Y)W. \end{aligned}$$

From (2.13) and symmetric properties of the curvature tensor R , we have

$$\begin{aligned} (R(X, Y)\tilde{C})(U, V, W) &= R(X, Y)R(U, V)W - R(R(X, Y)U, V)W \\ &\quad - R(U, R(X, Y)V)W - R(U, V)R(X, Y)W \\ &= (R(X, Y) \cdot R)(U, V, W). \end{aligned}$$

which proves the Theorem 3.3. \square

Theorem 3.4. *An $(2n + 1)$ -dimensional Lorentzian concircular structure manifold M satisfies*

$$\tilde{C}(\xi, X) \cdot S = 0$$

if and only if either M has the scalar curvature $r = 2n(2n + 1)(\alpha^2 - \rho)$ or is an Einstein manifold with the scalar curvature $r = 2n(2n + 1)(\alpha^2 - \rho)$.

Proof. The condition $\tilde{C}(\xi, X) \cdot S = 0$ implies that

$$S(\tilde{C}(\xi, X)Y, \xi) + S(Y, \tilde{C}(\xi, X)\xi) = 0.$$

In view of (3.2), it gives

$$\left[(\alpha^2 - \rho) - \frac{r}{n(n-1)} \right] \times [g(X, Y)S(\xi, \xi) - S(X, \xi)\eta(Y) + S(Y, \xi)\eta(X) + S(X, \xi)] = 0.$$

By the use of (2.11), we have

$$\left[(\alpha^2 - \rho) - \frac{r}{n(n-1)} \right] [S(X, Y) - 2n(\alpha^2 - \rho)g(X, Y)] = 0.$$

Therefore, either the scalar curvature of M is $r = 2n(2n+1)(\alpha^2 - \rho)$ or $S(X, Y) = 2n(\alpha^2 - \rho)g(X, Y)$ which implies that M is an Einstein manifold with the scalar curvature $r = 2n(2n+1)(\alpha^2 - \rho)$, which proves the Theorem 3.4. \square

Theorem 3.5. *An $(2n+1)$ -dimensional Lorentzian concircular structure manifold M satisfies*

$$\tilde{C}(\xi, X) \cdot C = 0$$

if and only if either M has the scalar curvature $r = 2n(2n+1)(\alpha^2 - \rho)$ or is an η -Einstein manifold.

Proof. The condition $\tilde{C}(\xi, X) \cdot C = 0$ implies that

$$\left[\tilde{C}(\xi, U)C(X, Y)W - C(\tilde{C}(\xi, U)X, Y)W - C(X, \tilde{C}(\xi, U)Y)W \right] = 0$$

Thus in view of (3.2) gives

$$0 = \left[(\alpha^2 - \rho) - \frac{r}{n(n-1)} \right] \times [C(X, Y)W, U)\xi - \eta(C(X, Y)W)U - g(U, X)C(\xi, Y)W + \eta(X)C(Y, U)W - g(U, Y)C(X, \xi)W + \eta(Y)C(X, U)W + \eta(W)C(X, Y)W - g(U, W)C(X, Y)\xi].$$

So either the scalar curvature of M is $r = 2n(2n+1)(\alpha^2 - \rho)$ or the equation

$$0 = C(X, Y)W, U)\xi - \eta(C(X, Y)W)U - g(U, X)C(\xi, Y)W + \eta(X)C(Y, U)W - g(U, Y)C(X, \xi)W + \eta(Y)C(X, U)W + \eta(W)C(X, Y)W - g(U, W)C(X, Y)\xi$$

holds on M . Taking the inner product of this equation with ξ , we get

$$\begin{aligned} 0 = & -C(X, Y, W, U) - C(X, Y)W\eta(U) - g(U, X)\eta(C(\xi, Y)W) \\ & + \eta(X)\eta(C(Y, U)W) - g(U, Y)\eta(C(X, \xi)W) \\ & + \eta(Y)\eta(C(X, U)W) + \eta(W)\eta(C(X, Y)W) - g(U, W)\eta(C(X, Y)\xi). \end{aligned} \quad (3.3)$$

Using (2.6), (2.11) and (2.14) in (3.3), we get

$$\begin{aligned} & S(Y, W) \\ = & \left[(\alpha^2 - \rho) - \frac{r}{2n(2n+1)} \right] g(Y, W) + \left[(\alpha^2 - \rho) + \frac{r}{2n(2n+1)} \right] \eta(Y)\eta(W), \end{aligned}$$

which proves the Theorem 3.5. \square

Acknowledgement : The authors are thankful to the referee for his comments in the improvement of this paper.

References

- [1] M. Kon, Invariant sub manifolds in Sasakian manifolds, *Mathematische Annalen* 219 (1976) 277–290.
- [2] A.A.Shaikh, Lorentzian almost paracontact manifolds with structure of concircular type, *Kyungpook Math. J.* 43 (2003) 305–314.
- [3] K. Matsumoto, On Lorentzian paracontact manifolds, *Bull of Yamagata Univ. Nat. Soci.* 12 (1989) 151–156.
- [4] A.A. Shaikh, T. Basu, S.Eyasmin, On the existence of ϕ -recurrent $(LCS)_n$ -manifolds, *Extracta Mathematicae* 231 (2008) 305–314.
- [5] T. Adati, T. Miyasawa, On P-Sasakian manifolds satisfying certain conditions, *Tensor (N.S.)* 33 (1979) 173–178.
- [6] K. Yano, M. Kon, *Structure on Manifolds*, Series in Pure Math., Vol.3, World Sci., 1984.

(Received 28 January 2011)

(Accepted 18 August 2011)