



A General Composite Algorithms for Solving General Equilibrium Problems and Fixed Point Problems in Hilbert Spaces

Rabian Wangkeeree¹ and Thanatporn Bantaojai

Department of Mathematics, Faculty of Science,
Naresuan University, Phitsanulok 65000, Thailand

e-mail : rabianw@nu.ac.th,
princess_13322@hotmail.com

Abstract : In this paper, we introduce a general composite algorithm for finding a common element of the set of solutions of an general equilibrium problem and the fixed point set a nonexpansive mapping in the framework of Hilbert spaces. Strong convergence of such iterative scheme is obtained which solving some variational inequalities for a strongly monotone and strictly pseudo-contractive mapping. Our results extend the corresponding recent results of Yao and Liou [Y. Yao, Y.C. Liou, Composite Algorithms for Minimization over the Solutions of Equilibrium Problems and Fixed Point Problems, Abstract and Applied Analysis, Volume 2010 (2010), Article ID 763506, 19 pages].

Keywords : Composite algorithm; Minimization; Equilibrium problem; Fixed point problem; Nonexpansive mapping.

2010 Mathematics Subject Classification : 47H09; 47H10; 47H17.

1 Introduction

Let C be a nonempty closed convex subset of a real Hilbert space H . Recall that a mapping $A : C \rightarrow H$ is called α -inverse-strongly monotone if there exists a positive real number α such that $\langle Ax - Ay, x - y \rangle \geq \alpha \|Ax - Ay\|^2, \forall x, y \in C$. It is clear that any α -inverse-strongly monotone mapping is monotone and $\frac{1}{\alpha}$ -Lipschitz

¹Corresponding author email: rabianw@nu.ac.th (R. Wangkeeree)

continuous. Let $f : C \rightarrow H$ be a ρ -contraction; that is, there exists a constant $\rho \in [0, 1)$ such that $\|f(x) - f(y)\| \leq \rho\|x - y\|$ for all $x, y \in C$. A mapping $S : C \rightarrow C$ is said to be nonexpansive if $\|Sx - Sy\| \leq \|x - y\|$ for all $x, y \in C$. Denote the set of fixed points of S by $Fix(S)$.

Let $A : C \rightarrow H$ be a nonlinear mapping and $\phi : C \times C \rightarrow \mathbb{R}$ be a bifunction. Consider a general equilibrium problem:

$$\text{Find } z \in C \text{ such that } \phi(z, y) + \langle Az, y - z \rangle \geq 0, \forall y \in C. \quad (1.1)$$

The set of all solutions of the general equilibrium problem (1.1) is denoted by EP , i.e.,

$$EP = \{z \in C : \phi(z, y) + \langle Az, y - z \rangle \geq 0, \forall y \in C\}.$$

If $A = 0$, then (1.1) reduces to the following equilibrium problem of finding $z \in C$ such that

$$\phi(z, y) \geq 0, \forall y \in C. \quad (1.2)$$

If $F = 0$, then (1.1) reduces to the variational inequality problem of finding $z \in C$ such that

$$\langle Az, y - z \rangle \geq 0, \forall y \in C. \quad (1.3)$$

We note that the problem (1.1) is very general in the sense that it includes, as special cases, optimization problems, variational inequalities, minimax problems, Nash equilibrium problem in noncooperative games and others. See, e.g., [1–4].

In 2005, Combettes and Hirstoaga [5] introduced an iterative algorithm of finding the best approximation to the initial data and proved a strong convergence theorem. In 2007, by using the viscosity approximation method, Takahashi and Takahashi [6] introduced another iterative scheme for finding a common element of the set of solutions of the equilibrium problem and the set of fixed point points of a nonexpansive mapping. Subsequently, algorithms constructed for solving the equilibrium problems and fixed point problems have further developed by some authors. In particular, Ceng and Yao [7] introduced an iterative scheme for finding a common element of the set of solutions of the mixed equilibrium problem (1.1) and the set of common fixed points of finitely many nonexpansive mappings. Mainge and Moudafi [8] introduced an iterative algorithm for equilibrium problems and fixed point problems. Yao et. al. [9] considered an iterative scheme for finding a common element of the set of solutions of the equilibrium problem and the set of common fixed points of an infinite nonexpansive mappings. Noor et. al. [10] introduced an iterative method for solving fixed point problems and variational inequality problems. Wangkeeree [11] introduced a new iterative scheme for finding the common element of the set of common fixed points of nonexpansive mappings, the set of solutions of an equilibrium problem, and the set of solutions of the variational inequality. Wangkeeree and Kamraksa [12] introduced an iterative algorithm for finding a common element of the set of solutions of a mixed equilibrium problem, the set of fixed points of an infinite family of nonexpansive

mappings and the set of solutions of a general system of variational inequalities for a cocoercive mapping in a real Hilbert space. Their results extend and improve many results in the literature. Some works related to the equilibrium problem, fixed point problems and the variational inequality problem, please see [1–54] and the references therein.

However, we note that all constructed algorithms in [6–13] do not work to find the minimum-norm solution of the corresponding fixed point problems and the equilibrium problems. Very recently, Yao and Liou [14] proposed some algorithms for finding the minimum-norm solution of the fixed point problems and the equilibrium problems. They first suggested two new composite algorithms (one implicit and one explicit) for solving the above minimization problem. To be more precisely, let C be a nonempty closed convex subset of H , $\phi : C \times C \rightarrow \mathbb{R}$ be a bi-function satisfying certain conditions and $S : C \rightarrow C$ be a nonexpansive mapping such that $\Omega := F(S) \cap EP \neq \emptyset$. Let f be a contraction on a Hilbert space H . For given $x_0 \in C$ arbitrarily, let the sequence $\{x_n\}$ be generated iteratively by

$$\begin{cases} \phi(u_n, y) + \langle Ax_n, y - u_n \rangle + \frac{1}{r}\langle y - u_n, u_n - x_n \rangle \geq 0, & \forall y \in C, \\ x_{n+1} = \mu_n P_C[\alpha_n f(x_n) + (1 - \alpha_n)Sx_n] + (1 - \mu_n)u_n, & n \geq 0, \end{cases} \quad (1.4)$$

where A is an α -inverse strongly monotone mapping. They proved that if $\{\alpha_n\}$ and $\{\mu_n\}$ are two sequences in $[0,1]$ satisfying the following conditions:

- (i) $\lim_{n \rightarrow \infty} \alpha_n = 0$, $\sum_{n=0}^{\infty} \alpha_n = \infty$ and $\lim_{n \rightarrow \infty} \frac{\alpha_{n+1}}{\alpha_n} = 1$;
- (ii) $0 < \liminf_{n \rightarrow \infty} \mu_n \leq \limsup_{n \rightarrow \infty} \mu_n < 1$ and $\lim_{n \rightarrow \infty} \frac{\mu_{n+1} - \mu_n}{\alpha_{n+1}} = 0$,

then the sequence $\{x_n\}$ generated by (1.4) converges strongly to $x^* \in \Omega$ which is the unique solution of variational inequality

$$\langle (I - f)x^*, x - x^* \rangle \geq 0, \quad x \in \Omega.$$

In particular, if we take $f = 0$ in (1.4), then the sequence $\{x_n\}$ generated by

$$\begin{cases} \phi(u_n, y) + \langle Ax_n, y - u_n \rangle + \frac{1}{r}\langle y - u_n, u_n - x_n \rangle \geq 0, & \forall y \in C, \\ x_{n+1} = \mu_n P_C[(1 - \alpha_n)Sx_n] + (1 - \mu_n)u_n, & n \geq 0, \end{cases} \quad (1.5)$$

converges strongly to a solution of the minimization problem which is the problem of finding x^* such that

$$x^* = \arg \min_{x \in \Omega} \|x\|^2 \quad (1.6)$$

where Ω stands for the intersection set of the solution set of the general equilibrium problem and the fixed points set of a nonexpansive mapping.

On the other hand, iterative approximation methods for nonexpansive mappings have recently been applied to solve convex minimization problems; see, e.g.,

[15–17] and the references therein. Let B be a strongly positive bounded linear operator on H : that is, there is a constant $\bar{\gamma} > 0$ with property

$$\langle Bx, x \rangle \geq \bar{\gamma} \|x\|^2 \text{ for all } x \in H. \quad (1.7)$$

A typical problem is to minimize a quadratic function over the set of the fixed points of a nonexpansive mapping on a real Hilbert space H :

$$\min_{x \in Fix(S)} \frac{1}{2} \langle Bx, x \rangle - \langle x, b \rangle, \quad (1.8)$$

where b is a given point in H . In 2003, Xu [16] proved that the sequence $\{x_n\}$ defined by the iterative method below, with the initial guess $x_0 \in H$ chosen arbitrarily:

$$x_{n+1} = (I - \alpha_n B)Tx_n + \alpha_n u, \quad n \geq 0, \quad (1.9)$$

converges strongly to the unique solution of the minimization problem (1.8) provided the sequence $\{\alpha_n\}$ satisfies certain conditions. Using the viscosity approximation method, Moudafi [18] introduced the following iterative iterative process for nonexpansive mappings (see [16] for further developments in both Hilbert and Banach spaces). Let f be a contraction on H . Starting with an arbitrary initial $x_0 \in H$, define a sequence $\{x_n\}$ recursively by

$$x_{n+1} = (1 - \alpha_n)Tx_n + \alpha_n f(x_n), \quad n \geq 0, \quad (1.10)$$

where $\{\alpha_n\}$ is a sequence in $(0, 1)$. It is proved [16, 18] that under certain appropriate conditions imposed on $\{\alpha_n\}$, the sequence $\{x_n\}$ generated by (1.10) strongly converges to the unique solution x^* in C of the variational inequality

$$\langle (I - f)x^*, x - x^* \rangle \geq 0, \quad x \in H. \quad (1.11)$$

Recently, Marino and Xu [19] mixed the iterative method (1.9) and the viscosity approximation method (1.10) introduced by Moudafi [18] and considered the following general iterative method:

$$x_{n+1} = (I - \alpha_n B)Tx_n + \alpha_n \gamma f(x_n), \quad n \geq 0, \quad (1.12)$$

where B is a strongly positive bounded linear operator on H . They proved that if the sequence $\{\alpha_n\}$ of parameters satisfies the certain conditions, then the sequence $\{x_n\}$ generated by (1.12) converges strongly to the unique solution x^* in H of the variational inequality

$$\langle (B - \gamma f)x^*, x - x^* \rangle \geq 0, \quad x \in H \quad (1.13)$$

which is the optimality condition for the minimization problem:

$$\min_{x \in Fix(S)} \frac{1}{2} \langle Bx, x \rangle - h(x),$$

where h is a potential function for γf (i.e., $h'(x) = \gamma f(x)$ for $x \in H$).

Recall that a mapping $F : H \rightarrow H$ is called δ -strongly monotone if there exists a positive constant δ such that

$$\langle Fx - Fy, x - y \rangle \geq \delta \|x - y\|^2, \forall x, y \in H. \quad (1.14)$$

Recall also that a mapping F is called λ -strictly pseudo-contractive if there exists a positive constant λ such that

$$\langle Fx - Fy, x - y \rangle \leq \|x - y\|^2 - \lambda \|(x - y) - (Fx - Fy)\|^2, \forall x, y \in H. \quad (1.15)$$

It is easy to see that (1.15) can be rewritten as

$$\langle (I - F)x - (I - F)y, x - y \rangle \geq \lambda \|(I - F)x - (I - F)y\|^2. \quad (1.16)$$

Remark 1.1. If F is a strongly positive bounded linear operator on H with coefficient $\bar{\gamma}$, then F is $\bar{\gamma}$ -strongly monotone and $\frac{1}{2}$ -strictly pseudo-contractive. In fact, since F is a strongly positive bounded linear operator with coefficient $\bar{\gamma}$, we have

$$\langle Fx - Fy, x - y \rangle = \langle F(x - y), x - y \rangle \geq \bar{\gamma} \|x - y\|^2.$$

Therefore, F is $\bar{\gamma}$ -strongly monotone. On the other hand,

$$\begin{aligned} & \|(I - F)x - (I - F)y\|^2 \\ &= \langle (x - y) - (Fx - Fy), (x - y) - (Fx - Fy) \rangle \\ &= \langle x - y, x - y \rangle - 2\langle Fx - Fy, x - y \rangle + \langle Fx - Fy, Fx - Fy \rangle \\ &= \|x - y\|^2 - 2\langle Fx - Fy, x - y \rangle + \|Fx - Fy\|^2 \\ &\leq \|x - y\|^2 - 2\langle Fx - Fy, x - y \rangle + \|F\|^2 \|x - y\|^2. \end{aligned} \quad (1.17)$$

Since F is strongly positive if and only if $\frac{1}{\|F\|}F$ is strongly positive, we may assume, with out loss of generality, that $\|F\| = 1$. From (1.17), we have

$$\begin{aligned} \langle Fx - Fy, x - y \rangle &\leq \|x - y\|^2 - \frac{1}{2} \|(I - F)x - (I - F)y\|^2 \\ &= \|x - y\|^2 - \frac{1}{2} \|(x - y) - (Fx - Fy)\|^2. \end{aligned}$$

Hence F is $\frac{1}{2}$ -strictly pseudo-contractive.

In this paper, motivated by the above results, we introduce a general iterative scheme below in a real Hilbert space H , with the initial guess $x_0 \in C$ chosen arbitrary,

$$\begin{cases} \phi(u_n, y) + \langle Ax_n, y - u_n \rangle + \frac{1}{r} \langle y - u_n, u_n - x_n \rangle \geq 0, & \forall y \in C, \\ x_{n+1} = \mu_n P_C[\alpha_n \gamma f(x_n) + (1 - \alpha_n F)Sx_n] + (1 - \mu_n)u_n, & n \geq 0. \end{cases} \quad (1.18)$$

where C is a nonempty closed and convex subset of H , $\{\alpha_n\}$ and $\{\mu_n\}$ are two sequences in $[0,1]$, $\phi : C \times C \rightarrow \mathbb{R}$ is a bifunction satisfying certain conditions,

$S : C \rightarrow C$ is a nonexpansive mapping such that $\Omega := Fix(S) \cap EP \neq \emptyset$, $f : C \rightarrow H$ is a contraction with coefficient $0 < \rho < 1$, F is δ -strongly monotone and λ -strictly pseudo-contractive with $\delta + \lambda > 1$, γ is a positive real number such that $\gamma < \frac{1}{\rho} \left(1 - \sqrt{\frac{1-\delta}{\lambda}} \right)$ and A is an α -inverse strongly monotone mapping. We prove that the proposed algorithm converges strongly to $x^* \in \Omega$ which is the unique solution of the following variational inequality

$$\langle (F - \gamma f)x^*, x - x^* \rangle \geq 0, \quad x \in \Omega.$$

In particular,

- (I) if F is a strongly positive bounded linear operator on H , then x^* is the unique solution of the variational inequality (1.13);
- (II) if $F = I$, the identity mapping on H and $\gamma = 1$, then x^* is the unique solution of the variational inequality (1.11);
- (III) if $F = I$, the identity mapping on H and $f = 0$, then x^* is the unique solution of minimization problem (1.6).

The results presented in this paper extend and improve the main results in Yao and Liou [14], Marino and Xu [19] and many others.

2 Preliminaries

Let C be a nonempty closed convex subset of a real Hilbert space H . For every point $x \in H$, there exists a unique nearest point in C , denoted by $P_C x$ such that

$$\|x - P_C x\| \leq \|x - y\| \quad \text{for all } y \in C.$$

P_C is called the *metric projection* of H onto C . It is well known that P_C is a nonexpansive mapping of H onto C and satisfies

$$\langle x - y, P_C x - P_C y \rangle \geq \|P_C x - P_C y\|^2 \tag{2.1}$$

for every $x, y \in H$. Moreover, $P_C x$ is characterized by the following properties: $P_C x \in C$ and

$$\langle x - P_C x, y - P_C x \rangle \leq 0, \tag{2.2}$$

$$\|x - y\|^2 \geq \|x - P_C x\|^2 + \|y - P_C x\|^2 \tag{2.3}$$

for all $x \in H, y \in C$. For more details see [20].

Throughout this paper, we assume that a bifunction $\phi : C \times C \rightarrow \mathbb{R}$ satisfies the following conditions:

- (A1) $\phi(x, x) = 0$ for all $x \in C$;
- (A2) ϕ is monotone, i.e., $\phi(x, y) + \phi(y, x) \leq 0$ for all $x, y \in C$;

- (A3) for each $x, y, z \in C$, $\lim_{t \downarrow 0} \phi(tz + (1-t)x, y) \leq \phi(x, y)$;
- (A4) for each $x \in C$, the mapping $y \mapsto \phi(x, y)$ is convex and lower semicontinuous.

We need the following lemmas for proving our main results.

Lemma 2.1 ([5]). *Let C be a nonempty closed convex subset of a real Hilbert space H . Let $\phi : C \times C \rightarrow \mathbb{R}$ be a bifunction which satisfies conditions (A1)-(A4). Let $r > 0$ and $x \in C$. Then, there exists $z \in C$ such that*

$$\phi(z, y) + \frac{1}{r} \langle y - z, z - x \rangle \geq 0, \forall y \in C.$$

Further, if $T_r(x) = \{z \in C : \phi(z, y) + \frac{1}{r} \langle y - z, z - x \rangle \geq 0, \forall y \in C\}$, then the following hold:

- (i) T_r is single-valued and T_r is firmly nonexpansive, i.e., for any $x, y \in H$,

$$\|T_r x - T_r y\|^2 \leq \langle T_r x - T_r y, x - y \rangle;$$

- (ii) EP is closed and convex and $EP = Fix(T_r)$.

Lemma 2.2 ([21]). *Let C be a nonempty closed convex subset of a real Hilbert space H . Let the mapping $A : C \rightarrow H$ be α -inverse strongly monotone and $r > 0$ be a constant. Then, we have*

$$\|(I - rA)x - (I - rA)y\|^2 \leq \|x - y\|^2 + r(r - 2\alpha)\|Ax - Ay\|^2, \forall x, y \in C.$$

In particular, if $0 \leq r \leq 2\alpha$, then $I - rA$ is nonexpansive.

Lemma 2.3 ([22]). *Let C be a closed convex subset of a real Hilbert space H and let $S : C \rightarrow C$ be a nonexpansive mapping. Then, the mapping $I - S$ is demiclosed. That is, if $\{x_n\}$ is a sequence in C such that $x_n \rightarrow x^*$ weakly and $(I - S)x_n \rightarrow y$ strongly, then $(I - S)x^* = y$.*

Lemma 2.4 ([16]). *Assume $\{a_n\}$ is a sequence of nonnegative real numbers such that*

$$a_{n+1} \leq (1 - \gamma_n)a_n + \delta_n\gamma_n,$$

where $\{\gamma_n\}$ is a sequence in $(0, 1)$ and $\{\delta_n\}$ is a sequence such that

- (1) $\sum_{n=1}^{\infty} \gamma_n = \infty$;
- (2) $\limsup_{n \rightarrow \infty} \delta_n \leq 0$ or $\sum_{n=1}^{\infty} |\delta_n \gamma_n| < \infty$.

Then $\lim_{n \rightarrow \infty} a_n = 0$.

The following lemma can be found in [23, Lemma 2.7]. For the sake of the completeness, we include its proof in a Hilbert space's version.

Lemma 2.5. *Let H be a real Hilbert space and $F : H \rightarrow H$ a mapping.*

- (i) If F is δ -strongly monotone and λ -strictly pseudo-contractive with $\delta + \lambda > 1$, then $I - F$ is contractive with constant $\sqrt{(1 - \delta)/\lambda}$.
- (ii) If F is δ -strongly monotone and λ -strictly pseudo-contractive with $\delta + \lambda > 1$, then for any fixed number $\tau \in (0, 1)$, $I - \tau F$ is contractive with constant $1 - \tau(1 - \sqrt{(1 - \delta)/\lambda})$.

Proof. (i) For any $x, y \in H$, we have

$$\lambda \| (I - F)x - (I - F)y \|^2 \leq \|x - y\|^2 - \langle Fx - Fy, x - y \rangle \leq (1 - \delta) \|x - y\|^2, \forall x, y \in H.$$

Thus

$$\| (I - F)x - (I - F)y \| \leq \sqrt{\frac{1 - \delta}{\lambda}} \|x - y\|, \text{ for all } x, y \in H.$$

Since $\delta + \lambda > 1$, we have $\frac{1 - \delta}{\lambda} \in (0, 1)$. Hence $I - F$ is contractive with constant $\sqrt{(1 - \delta)/\lambda}$.

(ii) Since $I - F$ is contractive with constant $\sqrt{(1 - \delta)/\lambda}$, we have for any $\tau \in (0, 1)$,

$$\begin{aligned} \|x - y - \tau(Fx - Fy)\| &= \| (1 - \tau)(x - y) + \tau[(I - F)x - (I - F)y] \| \\ &\leq (1 - \tau) \|x - y\| + \tau \| (I - F)x - (I - F)y \| \\ &\leq (1 - \tau) \|x - y\| + \tau \sqrt{\frac{1 - \delta}{\lambda}} \|x - y\| \\ &= \left(1 - \tau \left(1 - \sqrt{\frac{1 - \delta}{\lambda}} \right) \right) \|x - y\|, \text{ for all } x, y \in H. \end{aligned}$$

Hence $I - \tau F$ is contractive with constant $1 - \tau(1 - \sqrt{(1 - \delta)/\lambda})$. \square

3 Main Results

Now, we give a lemma in order to prove our main results.

Lemma 3.1. Let C be a nonempty closed and convex subset of a real Hilbert space H . Let $S : C \rightarrow C$ be a nonexpansive mapping and $A : C \rightarrow H$ be an α -inverse strongly monotone mapping. Let $\phi : C \times C \rightarrow \mathbb{R}$ be a bifunction which satisfies conditions (A1)-(A4) such that $\Omega := EP \cap Fix(S)$ is nonempty. Let $F : C \rightarrow H$ be δ -strongly monotone and λ -strictly pseudo-contractive with $\delta + \lambda > 1$, $f : C \rightarrow H$ a ρ -contraction, γ a positive real number such that $\gamma < (1 - \sqrt{(1 - \delta)/\lambda})/\rho$ and r a constant such that $r \in (0, 2\alpha)$. For given $x_0 \in C$ arbitrarily, let the sequence $\{x_n\}$ be generated iteratively by (1.18). Suppose that $\{\alpha_n\}$ and $\{\mu_n\}$ are two sequences in $[0, 1]$. Then, the sequence $\{x_n\}$ is bounded. Furthermore, if the sequences $\{\alpha_n\}$ and $\{\mu_n\}$ satisfy the following conditions:

$$(C1) \quad \lim_{n \rightarrow \infty} \alpha_n = 0 \text{ and } \lim_{n \rightarrow \infty} \frac{\alpha_{n+1}}{\alpha_n} = 1;$$

(C2) $0 < \liminf_{n \rightarrow \infty} \mu_n \leq \limsup_{n \rightarrow \infty} \mu_n < 1$ and $\lim_{n \rightarrow \infty} \frac{\mu_{n+1} - \mu_n}{\alpha_{n+1}} = 0$,
then $\lim_{n \rightarrow \infty} \|x_n - Sx_n\| = 0$.

Proof. First, we rewrite the sequence $\{x_n\}$ by the following :

$$x_{n+1} = \mu_n P_C[\alpha_n \gamma f(x_n) + (1 - \alpha_n F)Sx_n] + (1 - \mu_n)T_r(x_n - rAx_n), n \geq 0, \quad (3.1)$$

where the mapping T_r is defined in Lemma 2.1. Pick $z \in \Omega$. Let

$$u_n = T_r(x_n - rAx_n) \text{ and } y_n = \alpha_n \gamma f(x_n) + (1 - \alpha_n F)Sx_n$$

for all $n \geq 0$. The nonexpansivity of T_r and $I - rA$ implies that

$$\begin{aligned} \|u_n - z\| &= \|T_r(x_n - rAx_n) - T_r(z - rAz)\| \\ &\leq \|x_n - z\| \text{ for all } z \in \Omega. \end{aligned} \quad (3.2)$$

Applying Lemma 2.5, we can calculate the following

$$\begin{aligned} \|x_{n+1} - z\| &= \|\mu_n(P_C[y_n] - z) + (1 - \mu_n)(u_n - z)\| \\ &\leq \mu \|P_C[y_n] - z\| + (1 - \mu_n) \|u_n - z\| \\ &\leq \mu_n \|y_n - z\| + (1 - \mu_n) \|x_n - z\| \\ &= \mu_n \|\alpha_n \gamma f(x_n) + (I - \alpha_n F)Sx_n - z\| + (1 - \mu_n) \|x_n - z\| \\ &= \mu_n \|\alpha_n \gamma f(x_n) + (I - \alpha_n F)Sx_n - (I - \alpha_n F)z - \alpha_n F(z)\| \\ &\quad + (1 - \mu_n) \|x_n - z\| \\ &\leq \mu_n \alpha_n \|\gamma f(x_n) - F(z)\| + \mu_n \|(I - \alpha_n F)Sx_n - (I - \alpha_n F)z\| \\ &\quad + (1 - \mu_n) \|x_n - z\| \\ &\leq \mu_n \alpha_n \|\gamma f(x_n) - \gamma f(z)\| + \mu_n \alpha_n \|\gamma f(z) - F(z)\| \\ &\quad + \mu_n \left(1 - \alpha_n \left(1 - \sqrt{\frac{1-\delta}{\lambda}}\right)\right) \|x_n - z\| + (1 - \mu_n) \|x_n - z\| \\ &\leq \mu_n \alpha_n \gamma \rho \|x_n - z\| + \mu_n \alpha_n \|\gamma f(z) - F(z)\| \\ &\quad + \mu_n \left(1 - \alpha_n \left(1 - \sqrt{\frac{1-\delta}{\lambda}}\right)\right) \|x_n - z\| + (1 - \mu_n) \|x_n - z\| \\ &= \left(1 - \mu_n \alpha_n \left(1 - \sqrt{\frac{1-\delta}{\lambda}} - \gamma \rho\right)\right) \|x_n - z\| \\ &\quad + \mu_n \alpha_n \|\gamma f(z) - F(z)\| \\ &= \left(1 - \mu_n \alpha_n \left(1 - \sqrt{\frac{1-\delta}{\lambda}} - \gamma \rho\right)\right) \|x_n - z\| \\ &\quad + \frac{\mu_n \alpha_n (1 - \sqrt{(1-\delta)/\lambda} - \gamma \rho)}{(1 - \sqrt{(1-\delta)/\lambda} - \gamma \rho)} \|\gamma f(z) - F(z)\|. \end{aligned}$$

By induction, we obtain, for all $n \geq 0$,

$$\|x_n - z\| \leq \max \left\{ \|x_0 - z\|, \frac{\|\gamma f(z) - F(z)\|}{(1 - \sqrt{(1-\delta)/\lambda} - \gamma \rho)} \right\}.$$

Hence, $\{x_n\}$ is bounded. Consequently, we deduce that $\{u_n\}$, $\{f(x_n)\}$, $\{Sx_n\}$ and $\{y_n\}$ are all bounded.

Next, assume that the control conditions (C1) and (C2) hold. From (3.1), we have

$$\begin{aligned}\|x_{n+2} - x_{n+1}\| &= \|\mu_{n+1}P_C[y_{n+1}] + (1 - \mu_{n+1})u_{n+1} - \mu_nP_C[y_n] - (1 - \mu_n)u_n\| \\ &= \|\mu_{n+1}(P_C[y_{n+1}] - P_C[y_n]) + (\mu_{n+1} - \mu_n)P_C[y_n] \\ &\quad + (1 - \mu_{n+1})(u_{n+1} - u_n) + (\mu_n - \mu_{n+1})u_n\| \\ &\leq \mu_{n+1}\|y_{n+1} - y_n\| + (1 - \mu_{n+1})\|u_{n+1} - u_n\| \\ &\quad + |\mu_{n+1} - \mu_n|(\|P_C[y_n]\| + \|u_n\|).\end{aligned}$$

Now, we estimate $\|y_{n+1} - y_n\|$ and $\|u_{n+1} - u_n\|$. We have

$$\begin{aligned}\|y_{n+1} - y_n\| &= \|\alpha_{n+1}\gamma f(x_{n+1}) + (I - \alpha_{n+1}F)Sx_{n+1} - \alpha_n\gamma f(x_n) - (I - \alpha_nF)Sx_n\| \\ &= \|(\alpha_{n+1}\gamma f(x_{n+1}) - \alpha_{n+1}\gamma f(x_n)) + (\alpha_{n+1}\gamma f(x_n) - \alpha_n\gamma f(x_n)) \\ &\quad + [(I - \alpha_{n+1}F)Sx_{n+1} - (I - \alpha_{n+1}F)Sx_n] \\ &\quad + [(I - \alpha_{n+1}F)Sx_n - (I - \alpha_nF)Sx_n]\| \\ &\leq \alpha_{n+1}\gamma\rho\|x_{n+1} - x_n\| + |\alpha_{n+1} - \alpha_n|\|\gamma f(x_n)\| \\ &\quad + \left(1 - \alpha_{n+1}\left(1 - \sqrt{\frac{1-\delta}{\lambda}}\right)\right)\|x_{n+1} - x_n\| + |\alpha_n - \alpha_{n+1}|\|F(Sx_n)\| \\ &= \left(1 - \alpha_{n+1}\left(1 - \sqrt{\frac{1-\delta}{\lambda}}\right)\right)\|x_{n+1} - x_n\| + \alpha_{n+1}\gamma\rho\|x_{n+1} - x_n\| \\ &\quad + |\alpha_{n+1} - \alpha_n|(\gamma\|f(x_n)\| + \|F(Sx_n)\|),\end{aligned}$$

and

$$\begin{aligned}\|u_{n+1} - u_n\| &= \|T_r(x_{n+1} - rAx_{n+1}) - T_r(x_n - rAx_n)\| \\ &\leq \|(x_{n+1} - rAx_{n+1}) - (x_n - rAx_n)\| \\ &\leq \|x_{n+1} - x_n\|.\end{aligned}$$

Then, we obtain

$$\begin{aligned}\|x_{n+2} - x_{n+1}\| &\leq \mu_{n+1}\left(1 - \alpha_{n+1}\left(1 - \sqrt{\frac{1-\delta}{\lambda}}\right)\right)\|x_{n+1} - x_n\| \\ &\quad + \mu_{n+1}\alpha_{n+1}\gamma\rho\|x_{n+1} - x_n\| \\ &\quad + \mu_{n+1}|\alpha_{n+1} - \alpha_n|(\gamma\|f(x_n)\| + \|F(Sx_n)\|) \\ &\quad + (1 - \mu_{n+1})\|x_{n+1} - x_n\| + |\mu_{n+1} - \mu_n|(\|P_C[y_n]\| + \|u_n\|) \\ &\leq \left(1 - \alpha_{n+1}\mu_{n+1}\left(1 - \sqrt{\frac{1-\delta}{\lambda}} - \gamma\rho\right)\right)\|x_{n+1} - x_n\| \\ &\quad + (|\alpha_{n+1} - \alpha_n| + |\mu_{n+1} - \mu_n|)M,\end{aligned}$$

where $M > 0$ is a constant satisfying

$$\sup_n\{\mu_{n+1}(\gamma\|f(x_n)\| + \|F(Sx_n)\|), \|P_C[y_n]\| + \|u_n\|\} \leq M.$$

This together with (C1), (C2) and Lemma 2.4 implies that

$$\lim_{n \rightarrow \infty} \|x_{n+2} - x_{n+1}\| = 0. \quad (3.3)$$

By the convexity of the norm $\|\cdot\|$, we have

$$\begin{aligned} \|x_{n+1} - z\|^2 &= \|\mu_n(P_C[y_n] - z) + (1 - \mu_n)(u_n - z)\|^2 \\ &\leq \mu_n \|P_C[y_n] - z\|^2 + (1 - \mu_n) \|u_n - z\|^2 \\ &\leq \mu_n \|y_n - z\|^2 + (1 - \mu_n) \|u_n - z\|^2 \\ &= \mu_n \|\alpha_n \gamma f(x_n) + (I - \alpha_n F)Sx_n - z\|^2 + (1 - \mu_n) \|u_n - z\|^2 \\ &= \mu_n \|\alpha_n \gamma f(x_n) - \alpha_n F(z) + (I - \alpha_n F)Sx_n - (I - \alpha_n F)z\|^2 \\ &\quad + (1 - \mu_n) \|u_n - z\|^2 \\ &\leq \mu_n \|(I - \alpha_n F)Sx_n - (I - \alpha_n F)z\|^2 + \mu_n \alpha_n^2 \|\gamma f(x_n) - F(z)\|^2 \\ &\quad + 2\mu_n \alpha_n \langle (I - \alpha_n F)Sx_n - (I - \alpha_n F)z, \gamma f(x_n) - F(z) \rangle \\ &\quad + (1 - \mu_n) \|u_n - z\|^2 \\ &\leq \mu_n \left(1 - \alpha_n \left(1 - \sqrt{\frac{1-\delta}{\lambda}}\right)\right)^2 \|x_n - z\|^2 + \mu_n \alpha_n^2 \|\gamma f(x_n) - F(z)\|^2 \\ &\quad + 2\alpha_n \mu_n \left(1 - \alpha_n \left(1 - \sqrt{\frac{1-\delta}{\lambda}}\right)\right) \|\gamma f(x_n) - F(z)\| \|x_n - z\| \\ &\quad + (1 - \mu_n) \|u_n - z\|^2 \\ &\leq \mu_n \left(1 - \alpha_n \left(1 - \sqrt{\frac{1-\delta}{\lambda}}\right)\right) \|x_n - z\|^2 + \mu_n \alpha_n^2 \|\gamma f(x_n) - F(z)\|^2 \\ &\quad + 2\alpha_n \mu_n \left(1 - \alpha_n \left(1 - \sqrt{\frac{1-\delta}{\lambda}}\right)\right) \|\gamma f(x_n) - F(z)\| \|x_n - z\| \\ &\quad + (1 - \mu_n) \|u_n - z\|^2. \end{aligned} \quad (3.4)$$

From Lemma 2.2, we get

$$\begin{aligned} \|u_n - z\|^2 &= \|T_r(x_n - rAx_n) - T_r(z - rAz)\|^2 \\ &\leq \|(x_n - rAx_n) - (z - rAz)\|^2 \\ &\leq \|x_n - z\|^2 + r(r - 2\alpha) \|Ax_n - Az\|^2. \end{aligned} \quad (3.5)$$

Substituting (3.5) into (3.4), we have

$$\begin{aligned} \|x_{n+1} - z\|^2 &\leq \mu_n \left(1 - \alpha_n \left(1 - \sqrt{\frac{1-\delta}{\lambda}}\right)\right) \|x_n - z\|^2 + \mu_n \alpha_n^2 \|\gamma f(x_n) - F(z)\|^2 \\ &\quad + 2\alpha_n \mu_n \left(1 - \alpha_n \left(1 - \sqrt{\frac{1-\delta}{\lambda}}\right)\right) \|\gamma f(x_n) - F(z)\| \|x_n - z\| \\ &\quad + (1 - \mu_n) [\|x_n - z\|^2 + r(r - 2\alpha) \|Ax_n - Az\|^2] \end{aligned}$$

$$\begin{aligned}
&= \left(1 - \alpha_n \mu_n \left(1 - \sqrt{\frac{1-\delta}{\lambda}}\right)\right) \|x_n - z\|^2 + \mu_n \alpha_n^2 \|\gamma f(x_n) - F(z)\|^2 \\
&\quad + 2\alpha_n \mu_n \left(1 - \alpha_n \left(1 - \sqrt{\frac{1-\delta}{\lambda}}\right)\right) \|\gamma f(x_n) - F(z)\| \|x_n - z\| \\
&\quad + (1 - \mu_n)r(r - 2\alpha) \|Ax_n - Az\|^2.
\end{aligned} \tag{3.6}$$

Therefore,

$$\begin{aligned}
&(1 - \mu_n)r(2\alpha - r) \|Ax_n - Az\|^2 \\
&\leq \left(1 - \alpha_n \mu_n \left(1 - \sqrt{\frac{1-\delta}{\lambda}}\right)\right) \|x_n - z\|^2 - \|x_{n+1} - z\|^2 \\
&\quad + \mu_n \alpha_n^2 \|\gamma f(x_n) - F(z)\|^2 \\
&\quad + 2\alpha_n \mu_n \left(1 - \alpha_n \left(1 - \sqrt{\frac{1-\delta}{\lambda}}\right)\right) \|\gamma f(x_n) - F(z)\| \|x_n - z\| \\
&\leq \|x_n - z\|^2 - \|x_{n+1} - z\|^2 + \mu_n \alpha_n^2 \|\gamma f(x_n) - F(z)\|^2 \\
&\quad + 2\alpha_n \mu_n \left(1 - \alpha_n \left(1 - \sqrt{\frac{1-\delta}{\lambda}}\right)\right) \|\gamma f(x_n) - F(z)\| \|x_n - z\| \\
&\leq (\|x_n - z\| + \|x_{n+1} - z\|) \|x_n - x_{n+1}\| + \mu_n \alpha_n^2 \|\gamma f(x_n) - F(z)\|^2 \\
&\quad + 2\alpha_n \left(1 - \alpha_n \left(1 - \sqrt{\frac{1-\delta}{\lambda}}\right)\right) \|\gamma f(x_n) - F(z)\| \|x_n - z\|.
\end{aligned}$$

Since $\liminf_{n \rightarrow \infty} (1 - \mu_n)r(2\alpha - r) > 0$, $\|x_n - x_{n+1}\| \rightarrow 0$ and $\alpha_n \rightarrow 0$, we derive

$$\lim_{n \rightarrow \infty} \|Ax_n - Az\| = 0.$$

From Lemma 2.1, we obtain

$$\begin{aligned}
\|u_n - z\|^2 &= \|T_r(x_n - rAx_n) - T_r(z - rAz)\|^2 \\
&\leq \langle (x_n - rAx_n) - (z - rAz), u_n - z \rangle \\
&= \frac{1}{2} \left(\|(x_n - rAx_n) - (z - rAz)\|^2 + \|u_n - z\|^2 \right. \\
&\quad \left. - \|(x_n - z) - r(Ax_n - Az) - (u_n - z)\|^2 \right) \\
&\leq \frac{1}{2} \left(\|x_n - z\|^2 + \|u_n - z\|^2 \right. \\
&\quad \left. - \|(x_n - u_n) - r(Ax_n - Az)\|^2 \right) \\
&= \frac{1}{2} \left(\|x_n - z\|^2 + \|u_n - z\|^2 - \|x_n - u_n\|^2 \right. \\
&\quad \left. + 2r \langle x_n - u_n, Ax_n - Az \rangle - r^2 \|Ax_n - Az\|^2 \right).
\end{aligned}$$

Thus, we deduce

$$\|u_n - z\|^2 \leq \|x_n - z\|^2 - \|x_n - u_n\|^2 + 2r\|x_n - u_n\|\|Ax_n - Az\|. \quad (3.7)$$

By (3.4) and (3.7), we have

$$\begin{aligned} \|x_{n+1} - z\|^2 &\leq \mu_n \left(1 - \alpha_n \left(1 - \sqrt{\frac{1-\delta}{\lambda}} \right) \right) \|x_n - z\|^2 + \mu_n \alpha_n^2 \|\gamma f(x_n) - F(z)\|^2 \\ &\quad + 2\alpha_n \mu_n \left(1 - \alpha_n \left(1 - \sqrt{\frac{1-\delta}{\lambda}} \right) \right) \|\gamma f(x_n) - F(z)\| \|x_n - z\| \\ &\quad + (1 - \mu_n) [\|x_n - z\|^2 - \|x_n - u_n\|^2 + 2r\|x_n - u_n\|\|Ax_n - Az\|] \\ &\leq \left(1 - \alpha_n \mu_n \left(1 - \sqrt{\frac{1-\delta}{\lambda}} \right) \right) \|x_n - z\|^2 + \mu_n \alpha_n^2 \|\gamma f(x_n) - F(z)\|^2 \\ &\quad + 2\alpha_n \mu_n \left(1 - \alpha_n \left(1 - \sqrt{\frac{1-\delta}{\lambda}} \right) \right) \|\gamma f(x_n) - F(z)\| \|x_n - z\| \\ &\quad + (1 - \mu_n) [-\|x_n - u_n\|^2 + 2r\|x_n - u_n\|\|Ax_n - Az\|]. \end{aligned}$$

It follows that

$$\begin{aligned} (1 - \mu_n) \|x_n - u_n\|^2 &\leq \|x_n - z\|^2 - \|x_{n+1} - z\|^2 + \mu_n \alpha_n^2 \|\gamma f(x_n) - F(z)\|^2 \\ &\quad + 2\alpha_n \mu_n \left(1 - \alpha_n \left(1 - \sqrt{\frac{1-\delta}{\lambda}} \right) \right) \|\gamma f(x_n) - F(z)\| \|x_n - z\| \\ &\quad + (1 - \mu_n) [2r\|x_n - u_n\|\|Ax_n - Az\|] \\ &\leq (\|x_n - z\| - \|x_{n+1} - z\|) \|x_n - x_{n+1}\| + \mu_n \alpha_n^2 \|\gamma f(x_n) - F(z)\|^2 \\ &\quad + 2\alpha_n \left(1 - \alpha_n \left(1 - \sqrt{\frac{1-\delta}{\lambda}} \right) \right) \|\gamma f(x_n) - F(z)\| \|x_n - z\| \\ &\quad + 2r(1 - \mu_n) \|x_n - u_n\|\|Ax_n - Az\|. \end{aligned}$$

Since $\liminf_{n \rightarrow \infty} (1 - \mu_n) > 0$, $\alpha_n \rightarrow 0$, $\|x_{n+1} - x_n\| \rightarrow 0$ and $\|Ax_n - Az\| \rightarrow 0$, we derive that

$$\lim_{n \rightarrow \infty} \|x_n - u_n\| = 0. \quad (3.8)$$

Note that $x_{n+1} - x_n = \mu_n(P_C[y_n] - x_n) + (1 - \mu_n)(u_n - x_n)$. Using (3.3), (3.8) and the condition (C2), we have

$$\|P_C[y_n] - x_n\| \rightarrow 0.$$

Therefore,

$$\begin{aligned} \|Sx_n - x_n\| &\leq \|Sx_n - P_C[y_n]\| + \|P_C[y_n] - x_n\| \\ &\leq \|Sx_n - y_n\| + \|P_C[y_n] - x_n\| \\ &\leq \alpha_n \|\gamma f(x_n) - F(Sx_n)\| + \|P_C[y_n] - x_n\| \rightarrow 0. \quad (3.9) \end{aligned}$$

This completes the proof. \square

Now we show the strong convergence of the sequence $\{x_n\}$ generated by (1.18).

Theorem 3.2. *Let $C, H, S, A, \phi, F, \Omega, f, r$ and $\{x_n\}$ be as in Lemma 3.1. Assume the sequences $\{\alpha_n\}$ and $\{\mu_n\}$ satisfy the following conditions :*

$$(D1) \lim_{n \rightarrow \infty} \alpha_n = 0, \sum_{n=0}^{\infty} \alpha_n = \infty \text{ and } \lim_{n \rightarrow \infty} \frac{\alpha_{n+1}}{\alpha_n} = 1;$$

$$(D2) 0 < \liminf_{n \rightarrow \infty} \mu_n \leq \limsup_{n \rightarrow \infty} \mu_n < 1 \text{ and } \lim_{n \rightarrow \infty} \frac{\mu_{n+1} - \mu_n}{\alpha_{n+1}} = 0.$$

Then the sequence $\{x_n\}$ converges strongly to x^* of the following variational inequality

$$\langle (F - \gamma f)x^*, x - x^* \rangle \geq 0, \quad x \in \Omega \quad (3.10)$$

or equivalently $x^* = P_\Omega(I - F + \gamma f)x^*$, where P_Ω is the metric projection of H onto Ω .

Proof. Let $\Phi = P_\Omega$. Then $\Phi(I - F - \gamma f)$ is a contraction on C . In fact, from Lemma 2.5 (i), we have

$$\begin{aligned} \|\Phi(I - F - \gamma f)x - \Phi(I - F - \gamma f)y\| \\ &\leq \|(I - F - \gamma f)x - (I - F - \gamma f)y\| \\ &\leq \|(I - F)x - (I - F)y\| + \gamma \|f(x) - f(y)\| \\ &\leq \sqrt{\frac{1-\delta}{\lambda}} \|x - y\| + \alpha\gamma \|x - y\| \\ &= \left(\sqrt{\frac{1-\delta}{\lambda}} + \alpha\gamma \right) \|x - y\|, \text{ for all } x, y \in C. \end{aligned} \quad (3.11)$$

Therefore, $\Phi(I - F - \gamma f)$ is a contraction on C with coefficient $\left(\sqrt{\frac{1-\delta}{\lambda}} + \alpha\gamma \right) \in (0, 1)$. Thus, by Banach contraction principal, $P_\Omega(I - F - \gamma f)$ has a unique fixed point x^* . That is $P_\Omega(I - F - \gamma f)x^* = x^*$ which mean that x^* is the unique solution in Ω of the variational inequality (3.10). Next, we show that

$$\limsup_{n \rightarrow \infty} \langle \gamma f(x^*) - F(x^*), Sx_n - x^* \rangle \leq 0. \quad (3.12)$$

Indeed, we can choose a subsequence $\{Sx_{n_k}\}$ of $\{Sx_n\}$ such that

$$\limsup_{n \rightarrow \infty} \langle \gamma f(x^*) - F(x^*), Sx_n - x^* \rangle = \limsup_{k \rightarrow \infty} \langle \gamma f(x^*) - F(x^*), Sx_{n_k} - x^* \rangle. \quad (3.13)$$

Without loss of generality, we may further assume that $Sx_{n_k} \rightarrow \tilde{x}$ weakly. This together with Lemma 3.1, we have $x_{n_k} \rightarrow \tilde{x}$ weakly. Applying Lemma 3.1 and Lemma 2.3, we obtain $\tilde{x} \in Fix(S)$. Next we show $\tilde{x} \in EP$. Since $u_n = T_r(x_n - rAx_n)$, for any $y \in C$ we have

$$\phi(u_n, y) + \frac{1}{r} \langle y - u_n, u_n - (x_n - rAx_n) \rangle \geq 0.$$

From the monotonicity of F , we have

$$\frac{1}{r} \langle y - u_n, u_n - (x_n - rAx_n) \rangle \geq \phi(y, u_n), \forall y \in C.$$

Hence,

$$\langle y - u_n, \frac{u_{n_i} - x_{n_i}}{r} + Ax_{n_i} \rangle \geq \phi(y, u_{n_i}), \forall y \in C. \quad (3.14)$$

Put $z_t = ty + (1-t)\tilde{x}$ for all $t \in (0, 1]$ and $y \in C$. Then, we have $z_t \in C$. So, from (3.14) we have

$$\begin{aligned} \langle z_t - u_{n_i}, Az_t \rangle &\geq \langle z_t - u_{n_i}, Az_t \rangle - \langle z_t - u_{n_i}, \frac{u_{n_i} - x_{n_i}}{r} + Ax_{n_i} \rangle \\ &\quad + \phi(z_t, u_{n_i}) \\ &= \langle z_t - u_{n_i}, Az_t - Au_{n_i} \rangle + \langle z_t - u_{n_i}, Au_{n_i} - Ax_{n_i} \rangle \\ &\quad + \langle z_t - u_{n_i}, \frac{u_{n_i} - x_{n_i}}{r} \rangle + \phi(z_t, u_{n_i}). \end{aligned} \quad (3.15)$$

Note that $\|Au_{n_i} - Ax_{n_i}\| \leq \frac{1}{\alpha} \|u_{n_i} - x_{n_i}\| \rightarrow 0$. Further, from monotonicity of A , we have $\langle z_t - u_{n_i}, Az_t - Au_{n_i} \rangle \geq 0$. Letting $i \rightarrow \infty$ in (3.15), we have

$$\langle z_t - \tilde{x}, Az_t \rangle \geq \phi(z_t, \tilde{x}). \quad (3.16)$$

From (A1), (A4) and (3.16), we also have

$$\begin{aligned} 0 &= \phi(z_t, z_t) \leq t\phi(z_t, y) + (1-t)\phi(z_t, \tilde{x}) \\ &\leq t\phi(z_t, y) + (1-t)\langle z_t - \tilde{x}, Az_t \rangle \\ &= t\phi(z_t, y) + (1-t)t\langle y - \tilde{x}, Az_t \rangle \end{aligned}$$

and hence

$$0 \leq \phi(z_t, y) + (1-t)\langle Az_t, y - \tilde{x} \rangle. \quad (3.17)$$

Letting $t \rightarrow 0$ in (3.17), we have, for each $y \in C$,

$$0 \leq \phi(\tilde{x}, y) + \langle y - \tilde{x}, A\tilde{x} \rangle. \quad (3.18)$$

This implies that $\tilde{x} \in EP$. Therefore, $\tilde{x} \in \Omega$. Therefore,

$$\limsup_{n \rightarrow \infty} \langle \gamma f(x^*) - F(x^*), Sx_n - x^* \rangle = \langle \gamma f(x^*) - F(x^*), \tilde{x} - x^* \rangle \leq 0.$$

Finally, we prove that $x_n \rightarrow x^*$ as $n \rightarrow \infty$. From Lemma 2.5 and (1.18), we obtain

$$\begin{aligned}
\|x_{n+1} - x^*\|^2 &= \|\mu_n(P_C[y_n] - x^*) + (1 - \mu_n)(u_n - x^*)\|^2 \\
&\leq \mu_n \|P_C[y_n] - x^*\|^2 + (1 - \mu_n) \|u_n - x^*\|^2 \\
&\leq \mu_n \|y_n - x^*\|^2 + (1 - \mu_n) \|u_n - x^*\|^2 \\
&\leq \mu \|\alpha_n \gamma f(x_n) - \alpha_n F(x^*) + (I - \alpha_n F)Sx_n - (I - \alpha_n F)x^*\|^2 \\
&\quad + (1 - \mu_n) \|u_n - x^*\|^2 \\
&\leq \mu_n \|(I - \alpha_n F)Sx_n - (I - \alpha_n F)x^*\|^2 + \alpha_n^2 \|\gamma f(x_n) - F(x^*)\|^2 \\
&\quad + 2\alpha_n \mu_n \langle (I - \alpha_n F)Sx_n - (I - \alpha_n F)x^*, \gamma f(x_n) - \gamma f(x^*) \rangle \\
&\quad + 2\alpha_n \mu_n \langle (I - \alpha_n F)Sx_n - (I - \alpha_n F)x^*, \gamma f(x^*) - F(x^*) \rangle \\
&\quad + (1 - \mu_n) \|u_n - x^*\|^2 \\
&\leq \mu_n \|(I - \alpha_n F)Sx_n - (I - \alpha_n F)x^*\|^2 + \alpha_n^2 \|\gamma f(x_n) - F(x^*)\|^2 \\
&\quad + 2\alpha_n \mu_n \|(I - \alpha_n F)Sx_n - (I - \alpha_n F)x^*\| \|\gamma f(x_n) - \gamma f(x^*)\| \\
&\quad + 2\alpha_n \mu_n \langle (I - \alpha_n F)Sx_n - (I - \alpha_n F)x^*, \gamma f(x^*) - F(x^*) \rangle \\
&\quad + (1 - \mu_n) \|u_n - x^*\|^2 \\
&\leq \mu_n \left(1 - \alpha_n \left(1 - \sqrt{\frac{1-\delta}{\lambda}} \right) \right)^2 \|x_n - x^*\|^2 + \mu_n \alpha_n^2 \|\gamma f(x_n) - F(x^*)\|^2 \\
&\quad + 2\alpha_n \mu_n \gamma \rho \left(1 - \alpha_n \left(1 - \sqrt{\frac{1-\delta}{\lambda}} \right) \right) \|x_n - x^*\|^2 \\
&\quad + 2\alpha_n \mu_n \langle (I - \alpha_n F)Sx_n - (I - \alpha_n F)x^*, \gamma f(x^*) - F(x^*) \rangle \\
&\quad + (1 - \mu_n) \|u_n - x^*\|^2 \\
&\leq \mu_n \left(1 - 2\alpha_n \left(1 - \sqrt{\frac{1-\delta}{\lambda}} \right) + 2\alpha_n \gamma \rho \left(1 - \alpha_n \left(1 - \sqrt{\frac{1-\delta}{\lambda}} \right) \right) \right) \\
&\quad \times \|x_n - x^*\|^2 + 2\alpha_n \mu_n \langle Sx_n - x^*, \gamma f(x^*) - F(x^*) \rangle \\
&\quad + 2\alpha_n^2 \mu_n \langle F(x^*) - F(Sx_n), \gamma f(x^*) - F(x^*) \rangle \\
&\quad + \mu_n \alpha_n^2 [\|x_n - x^*\|^2 + \|\gamma f(x_n) - F(x^*)\|^2] + (1 - \mu_n) \|x_n - x^*\|^2 \\
&= \left(1 - 2\alpha_n \mu_n \left(1 - \sqrt{\frac{1-\delta}{\lambda}} \right) + 2\alpha_n \gamma \rho \mu_n \left(1 - \alpha_n \left(1 - \sqrt{\frac{1-\delta}{\lambda}} \right) \right) \right) \\
&\quad \times \|x_n - x^*\|^2 + 2\alpha_n \mu_n \langle Sx_n - x^*, \gamma f(x^*) - F(x^*) \rangle \\
&\quad + 2\alpha_n^2 \mu_n \langle F(x^*) - F(Sx_n), \gamma f(x^*) - F(x^*) \rangle \\
&\quad + \mu_n \alpha_n^2 [\|x_n - x^*\|^2 + \|\gamma f(x_n) - F(x^*)\|^2] \\
&= \left(1 - 2\alpha_n \mu_n \left(1 - \sqrt{\frac{1-\delta}{\lambda}} - \gamma \rho \left(1 - \alpha_n \left(1 - \sqrt{\frac{1-\delta}{\lambda}} \right) \right) \right) \right) \\
&\quad \times \|x_n - x^*\|^2 + 2\alpha_n \mu_n \langle Sx_n - x^*, \gamma f(x^*) - F(x^*) \rangle \\
&\quad + 2\alpha_n^2 \mu_n \langle F(x^*) - F(Sx_n), \gamma f(x^*) - F(x^*) \rangle \\
&\quad + \mu_n \alpha_n^2 [\|x_n - x^*\|^2 + \|\gamma f(x_n) - F(x^*)\|^2] \\
&= (1 - \gamma_n) \|x_n - x^*\|^2 + \delta_n \gamma_n,
\end{aligned}$$

where $\gamma_n = 2\alpha_n\mu_n \left(1 - \sqrt{\frac{1-\delta}{\lambda}} - \gamma\rho \left(1 - \alpha_n \left(1 - \sqrt{\frac{1-\delta}{\lambda}} \right) \right) \right)$ and
 $\delta_n = \frac{\langle Sx_n - x^*, \gamma f(x^*) - F(x^*) \rangle}{\left(1 - \sqrt{\frac{1-\delta}{\lambda}} - \gamma\rho \left(1 - \alpha_n \left(1 - \sqrt{\frac{1-\delta}{\lambda}} \right) \right) \right)} + \frac{\alpha_n \langle F(x^*) - F(Sx_n), \gamma f(x^*) - F(x^*) \rangle}{\left(1 - \sqrt{\frac{1-\delta}{\lambda}} - \gamma\rho \left(1 - \alpha_n \left(1 - \sqrt{\frac{1-\delta}{\lambda}} \right) \right) \right)}$
 $+ \frac{\alpha_n [\|x_n - x^*\|^2 + \|f(x_n) - F(x^*)\|^2]}{2 \left(1 - \sqrt{\frac{1-\delta}{\lambda}} - \gamma\rho \left(1 - \alpha_n \left(1 - \sqrt{\frac{1-\delta}{\lambda}} \right) \right) \right)}$. It is clear that $\sum_{n=0}^{\infty} \gamma_n = \infty$ and $\limsup_{n \rightarrow \infty} \delta_n \leq 0$. Hence, all conditions of Lemma 2.4 are satisfied. Therefore, $x_n \rightarrow x^*$. This completes the proof. \square

The following example shows that there exist the sequences $\{\alpha_n\}$ and $\{\mu_n\}$ satisfying the conditions (D1) and (D2) of Theorem 3.2.

Example 3.1. For each $n \geq 0$, let $\alpha_n = \frac{1}{n+1}$ and $\mu_n = \frac{1}{2} + \frac{1}{n+1}$. Then, it is easily to obtain $\lim_{n \rightarrow \infty} \alpha_n = 0$, $\sum_{n=0}^{\infty} \alpha_n = \infty$ and $\lim_{n \rightarrow \infty} \frac{\alpha_{n+1}}{\alpha_n} = 1$, $0 < \frac{1}{2} = \liminf_{n \rightarrow \infty} \mu_n \leq \limsup_{n \rightarrow \infty} \mu_n = \frac{1}{2} < 1$ and $\lim_{n \rightarrow \infty} \frac{\mu_{n+1} - \mu_n}{\alpha_{n+1}} = 0$. Hence conditions (D1) and (D2) of Theorem 3.2 are satisfied.

Corollary 3.3. Let $C, H, S, A, \phi, \Omega, f, r$ be as in Lemma 3.1. Let the sequence $\{x_n\}$ be generated by

$$\begin{cases} \phi(u_n, y) + \langle Ax_n, y - u_n \rangle + \frac{1}{r} \langle y - u_n, u_n - x_n \rangle \geq 0, & \forall y \in C, \\ x_{n+1} = \mu_n P_C[\alpha_n \gamma f(x_n) + (1 - \alpha_n B)Sx_n] + (1 - \mu_n)u_n, & n \geq 0. \end{cases}$$

where B is a strongly positive bounded linear operator with coefficient $\bar{\gamma} > \frac{1}{2}$ and $0 < \gamma < (1 - \sqrt{2 - 2\bar{\gamma}})/\rho$. Assume the sequences $\{\alpha_n\}$ and $\{\mu_n\}$ satisfy the following conditions :

$$(D1) \quad \lim_{n \rightarrow \infty} \alpha_n = 0, \quad \sum_{n=0}^{\infty} \alpha_n = \infty \text{ and } \lim_{n \rightarrow \infty} \frac{\alpha_{n+1}}{\alpha_n} = 1;$$

$$(D2) \quad 0 < \liminf_{n \rightarrow \infty} \mu_n \leq \limsup_{n \rightarrow \infty} \mu_n < 1 \text{ and } \lim_{n \rightarrow \infty} \frac{\mu_{n+1} - \mu_n}{\alpha_{n+1}} = 0.$$

Then the sequence $\{x_n\}$ converges strongly to x^* of the following variational inequality

$$\langle (B - \gamma f)x^*, x - x^* \rangle \geq 0, \quad x \in \Omega$$

or equivalently $\tilde{x} = P_{\Omega}(I - B + \gamma f)\tilde{x}$, where P_{Ω} is the metric projection of H onto Ω .

Setting $\gamma = 1$ and $F = I$, the identity mapping on C in Theorem 3.2, we obtain the following result.

Corollary 3.4 ([14, Theorem 3.7]). Let $C, H, S, A, \phi, \Omega, f, r$ be as in Lemma 3.1. Let the sequence $\{x_n\}$ be generated by

$$\begin{cases} \phi(u_n, y) + \langle Ax_n, y - u_n \rangle + \frac{1}{r} \langle y - u_n, u_n - x_n \rangle \geq 0, & \forall y \in C, \\ x_{n+1} = \mu_n P_C[\alpha_n f(x_n) + (1 - \alpha_n)Sx_n] + (1 - \mu_n)u_n, & n \geq 0. \end{cases}$$

Assume the sequences $\{\alpha_n\}$ and $\{\mu_n\}$ satisfy the following conditions :

(D1) $\lim_{n \rightarrow \infty} \alpha_n = 0$, $\sum_{n=0}^{\infty} \alpha_n = \infty$ and $\lim_{n \rightarrow \infty} \frac{\alpha_{n+1}}{\alpha_n} = 1$;

(D2) $0 < \liminf_{n \rightarrow \infty} \mu_n \leq \limsup_{n \rightarrow \infty} \mu_n < 1$ and $\lim_{n \rightarrow \infty} \frac{\mu_{n+1} - \mu_n}{\alpha_{n+1}} = 0$.

Then the sequence $\{x_n\}$ converges strongly to x^* of the following variational inequality

$$\langle (I - f)x^*, x - x^* \rangle \geq 0, \quad x \in \Omega.$$

Acknowledgements : The first author is supported by grant from under the program Strategic Scholarships for Frontier Research Network for the Ph.D. Program Thai Doctoral degree from the Office of the Higher Education Commission, Thailand and the second author is supported by the Thailand Research Fund under Grant TRG5280011.

References

- [1] E. Blum, W. Oettli, From optimization and variational inequalities to equilibrium problems, *Math. Stud.* 63 (1994) 123–145.
- [2] S. Takahashi, W. Takahashi, Strong convergence theorem for a generalized equilibrium problem and a nonexpansive mapping in a Hilbert space, *Nonlinear Anal.* 69 (2008) 1025–1033.
- [3] A. Moudafi, M. Théra, Proximal and dynamical approaches to equilibrium problems, in: *Lecture Notes in Economics and Mathematical Systems* vol. 477, Springer, 1999, pp. 187–201.
- [4] A. Moudafi, Weak convergence theorems for nonexpansive mappings and equilibrium problems, *J. Nonlinear Convex Anal.* 9 (2008) 37–43.
- [5] P.L. Combettes, A. Hirstoaga, Equilibrium programming in Hilbert spaces, *J. Nonlinear Convex Anal.* 6 (2005) 117–136.
- [6] S. Takahashi, W. Takahashi, Viscosity approximation methods for equilibrium problems and fixed point problems in Hilbert spaces, *J. Math. Anal. Appl.* 331 (2007) 506–515.
- [7] L.C. Ceng, J.C. Yao, A hybrid iterative scheme for mixed equilibrium problems and fixed point problems, *J. Comput. Appl. Math.* 214 (2008) 186–201.
- [8] P.E. Mainge, A. Moudafi, Coupling viscosity methods with the extragradient algorithm for solving equilibrium problems, *J. Nonlinear Convex Anal.* 9 (2008) 283–294.
- [9] Y. Yao, Y.C. Liou, C. Lee, M.M. Wong, Convergence theorem for equilibrium problems and fixed point problems, *Fixed Point Theory* 10 (2) (2009) 347–363.

- [10] M.A. Noor, Y. Yao, R. Chen, Y.C. Liou, An iterative method for fixed point problems and variational inequality problems, *Math. Communications* 12 (2007) 121–132.
- [11] R. Wangkeeree, An Extragradient Approximation Method for Equilibrium Problems and Fixed Point Problems of a Countable Family of Nonexpansive Mappings, *Fixed Point Theory and Applications* 2008 (2008), Article ID 134148, 17 pages.
- [12] R. Wangkeeree, U. Kamraksa, An iterative approximation method for solving a general system of variational inequality problems and mixed equilibrium problems, *Nonlinear Analysis: Hybrid Systems* 3 (2009) 615–630.
- [13] S.S. Zhang, H.W. Joseph Lee, C.K. Chan, Quadratic minimization for equilibrium problem variational inclusion and fixed point problem, *Applied Math and Mech.* 31 (2010) 917–928.
- [14] Y. Yao, Y.C. Liou, Composite Algorithms for Minimization over the Solutions of Equilibrium Problems and Fixed Point Problems, *Abstract and Applied Analysis*, Volume 2010 (2010), Article ID 763506, 19 pages.
- [15] F. Deutsch, I. Yamada, Minimizing certain convex functions over the intersection of the fixed point sets of nonexpansive mappings, *Numer. Funct. Anal. Optim.* 19 (1998) 33–56.
- [16] H.K. Xu, An iterative approach to quadratic optimization, *J. Optim. Theory Appl.* 116 (2003) 659–678.
- [17] H.K. Xu, Iterative algorithms for nonlinear operators, *J. London Math. Soc.* 66 (2002) 240–256.
- [18] A. Moudafi, Viscosity approximation methods for fixed-points problems, *J. Math. Anal. Appl.* 241 (2000) 46–55.
- [19] G. Marino, H.K. Xu, A general iterative method for nonexpansive mapping in Hilbert spaces, *J. Math. Anal. Appl.* 318 (2006) 43–52.
- [20] W. Takahashi, *Nonlinear Functional Analysis*, Yokohama Publishers, Yokohama, 2000.
- [21] N. Nadezhkina, W. Takahashi, Weak convergence theorem by an extragradient method for nonexpansive mappings and monotone mappings, *J. Optim. Theory Appl.* 128 (2006) 191–201.
- [22] Z. Opial, Weak convergence of the sequence of successive approximations for nonexpansive mappings, *Bull. Amer. Math. Soc.* 73 (1967) 595–597.
- [23] H. Piri, H. Vaezi, Strong Convergence of a Generalized Iterative Method for Semigroups of Nonexpansive Mappings in Hilbert Spaces, *Fixed Point Theory and Applications*, Volume 2010 (2010), Article ID 907275, 16 pages.

- [24] L.C. Ceng, J.C. Yao, A relaxed extragradient-like method for a generalized mixed equilibrium problem, a general system of generalized equilibria and a fixed point problem, *Nonlinear Analysis* 72 (2010) 1922–1937.
- [25] L.C. Ceng, S. Al-Homidan, Q.H. Ansari, J.C. Yao, An iterative scheme for equilibrium problems and fixed point problems of strict pseudocontraction mappings, *J. Comput. Appl. Math.* 223 (2009) 967–974.
- [26] L.C. Ceng, S. Schaible, J.C. Yao, Implicit iteration scheme with perturbed mapping for equilibrium problems and fixed point problems of finitely many nonexpansive mappings, *J. Optim. Theory Appl.* 139 (2008) 403–418.
- [27] S.S. Chang, H.W. Joseph Lee, C.K. Chan, A new method for solving equilibrium problem fixed point problem and variational inequality problem with application to optimization, *Nonlinear Anal.* 70 (2009) 3307–3319.
- [28] W. Chantarangsi, C. Jaiboon, P. Kumam, A viscosity hybrid steepest descent method for generalized mixed equilibrium problems and variational inequalities for relaxed cocoercive mapping in Hilbert spaces, *Abstract and Applied Analysis*, Volume 2010 (2010), Article ID 390972, 39 pages.
- [29] F. Cianciaruso, G. Marino, L. Muglia, Y. Yao, A hybrid projection algorithm for finding solutions of mixed equilibrium problem and variational inequality problem, *Fixed Point Theory and Applications*, Volume 2010 (2010), Article ID 383740, 19 pages.
- [30] F. Cianciaruso, G. Marino, L. Muglia, Y. Yao, On a two-step algorithm for hierarchical fixed point problems and variational inequalities, *J. Inequalities Appl.* 2009 (2009), Article ID 208692, 13 pages.
- [31] V. Colao, G.L. Acedo, G. Marino, An implicit method for finding common solutions of variational inequalities and systems of equilibrium problems and fixed points of infinite family of nonexpansive mappings, *Nonlinear Anal.* 71 (2009) 2708–2715.
- [32] V. Colao, G. Marino, H.K. Xu, An iterative method for finding common solutions of equilibrium and fixed point problems, *J. Math. Anal. Appl.* 344 (2008) 340–352.
- [33] P.L. Combettes, Strong convergence of block-iterative outer approximation methods for convex optimization, *SIAM J. Control Optim.* 38 (2000) 538–565.
- [34] P.L. Combettes, J.C. Pesquet, Proximal thresholding algorithm for minimization over orthonormal bases, *SIAM J. Optim.* 18 (2007) 1351–1376.
- [35] J.S. Jung, Strong convergence of composite iterative methods for equilibrium problems and fixed point problems, *Appl. Math. Comput.* 213 (2009) 498–505.
- [36] C. Klin-eam, S. Suantai, W. Takahashi, Strong Convergence of Generalized Projection Algorithms for Nonlinear Operators, *Abstract and Applied Analysis*, Volume 2009 (2009), Article ID 649831, 18 pages.

- [37] J.W. Peng, S.Y. Wu, J.C. Yao, A new iterative method for finding common solutions of a system of equilibrium problems, fixed-point problems, and variational inequalities, *Abstract and Applied Analysis*, Volume 2010 (2010), Article ID 428293, 27 pages.
- [38] J.W. Peng, J.C. Yao, A new hybrid-extragradient method for generalized mixed equilibrium problems and fixed point problems and variational inequality problems, *Taiwanese J. Math.* 12 (2008) 1401–1433.
- [39] J.W. Peng, J.C. Yao, Ishikawa iterative algorithms for a generalized equilibrium problem and fixed point problems of a pseudo-contraction mapping, *Journal of Global Optimization* 46 (2010) 331–345.
- [40] S. Plubtieng, R. Punpaeng, A new iterative method for equilibrium problems and fixed point problems of nonexpansive mappings and monotone mappings, *Appl. Math. Comput.* 197 (2008) 548–558.
- [41] X. Qin, Y.J. Cho, S.M. Kang, Convergence theorems of common elements for equilibrium problems and fixed point problems in Banach spaces, *J. Comput. Appl. Math.* 225 (2009) 20–30.
- [42] S. Saewan, P. Kumam, K. Wattanawitton, Convergence theorem based on a new hybrid projection method for finding a common solution of generalized equilibrium and variational inequality problems in Banach spaces, *Abstract and Applied Analysis*, Volume 2010 (2010), Article ID 734126, 25 pages.
- [43] W. Takahashi, M. Toyoda, Weak convergence theorems for nonexpansive mappings and monotone mappings, *J. Optim. Theory Appl.* 118 (2003) 417–428.
- [44] S. Wang, G. Marino, F. Wang, Strong convergence theorems for a generalized equilibrium problem with a relaxed monotone mapping and a countable family of nonexpansive mappings in a Hilbert space, *Fixed Point Theory and Applications*, Volume 2010 (2010), Article ID 230304, 22 pages.
- [45] Y. Yao, Y.C. Liou, G. Marino, Strong convergence of two iterative algorithms for non-expansive mappings in Hilbert spaces, *Fixed Point Theory and Applications*, Volume 2009 (2009), Article ID 279058, 7 pages.
- [46] Y. Yao, Y.C. Liou, Y.J. Wu, An extragradient method for mixed equilibrium problems and fixed point problems, *Fixed Point Theory and Applications*, Volume 2009 (2009), Article ID 632819, 15 pages.
- [47] Y. Yao, Y.C. Liou, J.C. Yao, A new hybrid iterative algorithm for fixed point problems, variational inequality problems, and mixed equilibrium problems, *Fixed Point Theory and Applications*, Volume 2008 (2008), Article ID 417089, 15 pages.
- [48] Y. Yao, Y.C. Liou, J.C. Yao, An extragradient method for fixed point problems and variational inequality problems, *J. Inequalities Appl.*, Volume 2007 (2007), Article ID 38752, 12 pages.

- [49] Y. Yao, Y.C. Liou, J.C. Yao, An iterative algorithm for approximating convex minimization problem, *Appl. Math. Comput.* 188 (2007) 648–656.
- [50] Y. Yao, Y.C. Liou, J.C. Yao, Convergence theorem for equilibrium problems and fixed point problems of infinite family of nonexpansive mappings, *Fixed Point Theory and Applications*, Volume 2007 (2007), Article ID 64363, 12 pages.
- [51] Y. Yao, M.A. Noor, R. Chen, Y.C. Liou, Strong convergence of three-step relaxed hybrid steepest-descent methods for variational inequalities, *Appl. Math. Comput.* 201 (2008) 175–183.
- [52] Y. Yao, J.C. Yao, On modified iterative method for nonexpansive mappings and monotone mappings, *Appl. Math. Comput.* 186 (2007) 1551–1558.
- [53] L.C. Zeng, Q.H. Ansari, David S. Shyu, J.C. Yao, Strong and weak convergence theorems for common solutions of generalized equilibrium problems and zeros of maximal monotone operators, *Fixed Point Theory and Applications*, Volume 2010 (2010), Article ID 590278, 33 pages.
- [54] L.C. Zeng, S. Kum, J.C. Yao, Algorithm for solving a generalized mixed equilibrium problem with perturbation in a Banach space, *Fixed Point Theory and Applications*, Volume 2010 (2010), Article ID 794503, 22 pages.

(Received 31 January 2011)

(Accepted 16 February 2011)