**Thai J**ournal of **Math**ematics Special Issue (2023) :Annual Meeting in Mathematics 2022 Pages 119 - 146

http://thaijmath.in.cmu.ac.th



# An Invariant-Preserving Three-Level Linearized Finite Difference Method for the Korteweg-de Vries-Kawahara Equation with Added Viscosity Term\*

## Kanyarat Phollamat<sup>1</sup>, Nattapol Ploymaklam<sup>2,\*</sup>

<sup>1</sup>Graduate Masters Degree Program in Applied Mathematics, Department of Mathematics, Faculty of Science, Chiang Mai University, Chiang Mai, 50200, Thailand e-mail : kanyarat\_phol@cmu.ac.th (K. Phollamat)
<sup>2</sup>Department of Mathematics, Faculty of Science, Chiang Mai University, Chiang Mai, 50200, Thailand

e-mail : nattapol.p@cmu.ac.th (N. Ploymaklam)

Abstract In this work, we aim to study numerical solutions of a nonlinear partial differential equation using a family of three-level linearized finite difference  $\theta$ -methods for a shallow water waves having surface tension in the form of Viscous Korteweg-de Vries-Kawahara equation with initial and boundary conditions. The model admits two invariants: momentum and energy. The scheme is proved to preserve both momentum and energy in the discrete sense when  $\theta = 1/3$ . In addition, we proved that the method converges uniformly. The method gives second-order of accuracy in space. Several numerical examples are presented to demonstrate the accuracy and efficiency of the proposed method.

#### **MSC:** 65M06; 65M12

**Keywords:** Viscous Korteweg-de Vries-Kawahara; Finite difference scheme; Convergence analysis; Stability analysis

Submission date: 31.05.2022 / Acceptance date: 15.12.2022

## **1. INTRODUCTION**

Nonlinear partial differential equations have an important role in mathematics, physics, and engineering. They are used as models to describe phenomena in solid state physics, fluid mechanics, chemical physics, plasma physics, geochemistry, and chemical kinematics fields, etc. See [1-5], for example.

One of the well-known nonlinear equations is the Korteweg-de Vries (KdV) equation which appears in the theories of shallow water waves having surface tension [6],[7].

The KdV equation [8] started with experiments by Russell in 1834, followed by theoretical investigations by Rayleigh and Boussinesq around 1870 and, finally, Korteweg and

<sup>\*</sup>Corresponding author.

Published by The Mathematical Association of Thailand. Copyright © 2023 by TJM. All rights reserved.

De Vries in 1895. The **Korteweg de Vries** equation (1.1). Its dimensionless from is given by

$$u_t + u_{xxx} - 6uu_x = 0, (1.1)$$

and the **Kawahara** equation is given by

 $u_t + auu_x + bu_{xxx} - cu_{xxxxx} = 0, (1.2)$ 

The Korteweg de Vries - Kawahara [9] equation is given by

$$u_t - \eta u_{xxxxx} + u_{xxx} + u_x + u_x = 0, \ x \in [a, b], t \in [0, T],$$
(1.3)

 $\eta \in \mathbb{R}$ , where u = u(x, t) is fluid velocity and t, x are temporal and spatial variables, respectively.

Ceballos et al. [10] studied the KdV–Kawahara equation in a bounded domain and obtained some numerical results. They showed that the KdV–Kawahara equation has smoothing effects that are uniform with respect to the size of the interval and they also proposed a simple finite different scheme for the problem and proved its stability. Natali [11] established the nonlinear stability of solitary traveling-wave solutions for the KdV–Kawahara equation. The main approach used to determine the stability of solitary traveling-waves come from the theory developed by Albert in [12]. Badali et al.[13] introduced a new solution for the KdV–Kawahara equation. Lie group analysis was used to carry out the integration of this equations. Coclite et al.[14] proved the well-posedness of the classical solutions for the Cauchy problem associated with the KdV–Kawahara equation.

In this article, we consider the KdV-Kawahara Equation with added viscosity term as follows:

$$u_t - \eta u_{xxxxx} + u_{xxx} + u u_x + u_x = \gamma u_{xx}, \quad x \in [a, b], \quad t \in [0, T],$$
(1.4)

with initial condition

$$u(x,0) = f(x), \quad x \in [a,b],$$
(1.5)

and boundary conditions

$$u(a,t) = u(b,t) = 0,$$
  

$$u_x(a,t) = u_x(b,t) = 0,$$
  

$$u_{xx}(a,t) = u_{xx}(b,t) = 0, \quad t \in [0,T],$$
(1.6)

where  $\gamma \geq 0$ .

The nonlinear term  $uu_x$  in equation (1.4) is difficult to approximate accurately using a simple numerical method. In 1981, Guo and Sanz-Serna [15] used two finite different sums to approximate the term in the KdV equation. Since then, there have been several attempts to estimate the term  $uu_x$  by splitting it into a sum of derivatives of u. Each term in the sum is estimated by using the central difference with or without some average values. In the early years, two layers of numerical solution from consecutive time steps are involved in the schemes. See [16–20] for example. In [18] and [21], Pan and Zhang developed linearized difference schemes which are three-level and conservative implicit for both Rosenau–RLW and general Rosenau–RLW equations. The second-order accuracy and unconditional stability were also proved. In [22], Wongsaijai and Poochinapan used the term Rosenua-KdV-RLW to refer to all three equations and applied an average value of two explicit finite differences to approximate the nonlinear term. This gives a collection of second-order  $\theta$ -schemes proven to preserve invariants when  $\theta = 1/3$ . We adapt their idea to the present problem. In their more recent works, Sun, Wang and Zhang [23] prove the pointwise estimates of a conservative difference scheme for Burgers' equation. Adapting the ideas from these works, Darayon et al. [24] applied second-order operators to the viscous Burgers-Poisson system and obtained point-wise convergence analysis. We adopt all these techniques in designing our finite difference method and in our analysis.

The content of this paper is organized as follows. In Section 2, we discuss some analytic properties of the solution that are essential to the stability and error analysis. In Section 3, we outline basic settings for finite difference method framework and propose a collection of  $\theta$ -schemes to approximate the solution of the KdV-Kawahara Equation with added viscosity term. We also prove the invariant properties of the proposed schemes and the existence and uniqueness of the resulting numerical solution in this section. In Section 4, we present the error analysis to show that the method has second-order accuracy. In Section 5, we discuss an extension to the non-homogeneous and test the proposed scheme on various examples to verify the theoretical results. Finally, discussion and conclusions are made in Sections 6-7.

# 2. Analytic Property

We will show that the solution of (1.4) with conditions (1.5) and (1.6) preserves the momentum and energy.

**Theorem 2.1** (Momentum Preserving). Let u be a solution of (1.4)-(1.6). Define

$$Q(t) = \int_{a}^{b} u(x,t) \, dx.$$

If  $u_0 \in L^1(a, b)$ , then

$$Q(t) = Q(0), \quad for \ all \quad t > 0.$$

*Proof.* From (1.4), we have  $u_t = \eta u_{xxxxx} - u_{xxx} - u_x - u_x + \gamma u_{xx}$ . Therefore,

$$\frac{d}{dt}Q(t) = \int_{a}^{b} \eta u_{xxxxx}(x,t) \, dx - \int_{a}^{b} u_{xxx}(x,t) \, dx - \int_{a}^{b} u(x,t)u_{x}(x,t) \, dx$$
$$- \int_{a}^{b} u_{x}(x,t) \, dx + \int_{a}^{b} \gamma u_{xx}(x,t) \, dx$$
$$= \left[\eta u_{xxxx}(x,t) - u_{xx}(x,t) - \frac{1}{2}u^{2}(x,t) - u(x,t) + \gamma u_{x}(x,t)\right]_{a}^{b} = 0$$

because of the boundary conditions (1.6). Therefore, the function Q(t) does not change over time. That is,

$$Q(t) = Q(0), \quad \text{for all} \quad t > 0.$$

**Theorem 2.2** (Energy Preserving). Let u be a solution of (1.4)-(1.6). Define

$$E(t) = \int_a^b u^2(x,t) \, dx.$$

If  $u_0 \in L^2(a, b)$ , then

 $E(t) \le E(0), \quad for \ all \quad t > 0.$ 

The inequality becomes equality when  $\gamma = 0$ .

*Proof.* Upon differentiating E, we obtain

$$\begin{split} \frac{1}{2} \frac{d}{dt} E(t) &= \eta \int_{a}^{b} u(x,t) u_{xxxxx}(x,t) \, dx - \int_{a}^{b} u(x,t) u_{xxx}(x,t) \, dx \\ &- \int_{a}^{b} u^{2}(x,t) u_{x}(x,t) \, dx - \int_{a}^{b} u(x,t) u_{x}(x,t) \, dx + \gamma \int_{a}^{b} u(x,t) u_{xx}(x,t) \, dx \\ &= \left[ \eta u_{x}(x,t) u_{xxx}(x,t) + \frac{\eta}{2} u_{xx}^{2}(x,t) - u(x,t) u_{xx}(x,t) + \frac{1}{2} u_{x}^{2}(x,t) \right. \\ &- \frac{1}{3} u^{3}(x,t) - \frac{1}{2} u^{2}(x,t) \Big]_{a}^{b} + \gamma \int_{a}^{b} u(x,t) u_{xx}(x,t) \, dx \\ &= -\gamma \int_{a}^{b} u_{x}^{2}(x,t) \, dx \le 0. \end{split}$$

Therefore, the function E(t) does not increase over time; that is,

 $E(t) \le E(0),$  for all t > 0.

If  $\gamma = 0$ , then the proof above shows that E'(0) = 0. This gives E(t) = E(0). This completes the proof.

## 3. FINITE DIFFERENCE METHOD

## 3.1. DISCRETIZATION

In this section, we present a complete description of our finite difference scheme and an algorithm for the formulation of the problem (1.4)-(1.6). We discretize the spatial domain [a, b] into the partition  $x_i = a + ih$ , i = 0, ..., M - 1 for the step size h = (b - a)/M. For a time step  $\tau = T/N$ , we define  $t^n = n\tau$  for n = 0, ..., N. Let  $u_i^n$  be an approximation of  $u(x_i, t^n)$ . The numerical solution  $\mathbf{u}^n$  at the time  $t^n$  is taken from the solution space  $Z_h$  defined as

$$Z_{h} = \{ u = [u_{i}]_{i=-2}^{M+2} \mid u_{0} = u_{M} = 0, \ D_{h}^{-}u_{0} = 0, \ D_{h}^{+}u_{M} = 0, D_{h}^{-}D_{h}^{-}u_{0} = 0, \ D_{h}^{+}D_{h}^{+}u_{M} = 0 \}.$$

For any  $\mathbf{u}, \mathbf{v} \in Z_h$ , we define an inner product:

$$\langle \mathbf{u}, \mathbf{v} \rangle_h = h \sum_{i=1}^{M-1} u_i v_i$$

which allows us to define the discrete  $L_2$  norm

$$\|\mathbf{u}\|_{h}^{2} = \langle \mathbf{u}, \mathbf{u} \rangle_{h}. \tag{3.1}$$

We also define the discrete uniform norm

$$\|\mathbf{u}\|_{h,\infty} = \max_{i=1,\dots,M-1} |u_i|,\tag{3.2}$$

for later use in the analysis.

With the set up above, we define finite difference methods for approximating some partial derivatives and some averages of u at  $(x_i, t^n)$  as follows:

$$\begin{split} \mathcal{D}_{\tau}^{+}u_{i}^{n} &= \frac{u_{i}^{n+1} - u_{i}^{n}}{\tau}, \quad \mathcal{D}_{\tau}^{0}u_{i}^{n} = \frac{u_{i}^{n+1} - u_{i}^{n-1}}{2\tau}, \\ u_{i}^{n+1/2} &= \frac{u_{i}^{n+1} + u_{i}^{n}}{2}, \quad \overline{u}_{i}^{n} = \frac{u_{i}^{n+1} + u_{i}^{n-1}}{2}, \\ D_{h}^{+}u_{i}^{n} &= \frac{u_{i+1}^{n} - u_{i}^{n}}{h}, \quad D_{h}^{0}u_{i}^{n} = \frac{u_{i+1}^{n} - u_{i-1}^{n}}{2h}, \quad D_{h}^{-}u_{i}^{n} = \frac{u_{i}^{n} - u_{i-1}^{n}}{h}. \end{split}$$

Note that we can apply these operators to a vector in  $Z_h$  by acting on each element of the vector.

Using the boundary conditions in the definition of  $Z_h$  and summation by parts, one can easily prove the following results.

**Lemma 3.1.** For any two mesh functions  $\mathbf{u}, \mathbf{v} \in Z_h$ , we have

$$\begin{split} \langle D_h^0 \mathbf{u}, \mathbf{v} \rangle_h &= -\langle \mathbf{u}, D_h^0 \mathbf{v} \rangle_h \\ \langle D_h^+ \mathbf{u}, \mathbf{v} \rangle_h &= -\langle \mathbf{u}, D_h^- \mathbf{v} \rangle_h \\ \langle D_h^+ D_h^- \mathbf{u}, \mathbf{v} \rangle_h &= -\langle D_h^+ \mathbf{u}, D_h^+ \mathbf{v} \rangle_h \\ \langle \mathbf{u}, D_h^+ D_h^- \mathbf{u} \rangle_h &= -\langle D_h^+ \mathbf{u}, D_h^+ \mathbf{u} \rangle_h = - \|D_h^+ \mathbf{u}\|_h^2 \end{split}$$

**Lemma 3.2.** Let  $\mathbf{u} \in Z_h$ , The following relations hold.

$$\langle D_h^0 \mathbf{u}, \mathbf{u} \rangle_h = 0$$
$$\langle D_h^+ D_h^- D_h^0 \mathbf{u}, \mathbf{u} \rangle_h = 0$$
$$\langle D_h^+ D_h^+ D_h^- D_h^- D_h^0 \mathbf{u}, \mathbf{u} \rangle_h = 0.$$

**Lemma 3.3.** Let  $\mathbf{u} \in Z_h$ , The following relations hold.

$$\langle D_h^0 \mathbf{u}, D_h^0 \mathbf{u} \rangle_h \le \langle D_h^+ \mathbf{u}, D_h^+ \mathbf{u} \rangle_h$$
  
 $\| D_h^0 \mathbf{u} \|_{h,\infty} \le \| D_h^+ \mathbf{u} \|_{h,\infty}.$ 

## 3.2. Formulation of the Scheme

We propose a family of explicit three-level finite difference schemes for solving the Viscous Korteweg-de Vries-Kawahara equation (1.4) with conditions (1.5) and (1.6) as follows: for  $\theta \in [0, 1]$ , find  $\mathbf{u}^{n+1} \in Z_h$  satisfying

$$\mathcal{D}_{\tau}^{+} u_{i}^{0} - \eta D_{h}^{+} D_{h}^{+} D_{h}^{-} D_{h}^{0} u_{i}^{1/2} + D_{h}^{+} D_{h}^{-} D_{h}^{0} u_{i}^{1/2} + \frac{1}{2} \Psi_{\theta} (\mathbf{u}^{0}, \mathbf{u}^{1/2})_{i} + D_{h}^{0} u_{i}^{1/2} = \gamma D_{h}^{+} D_{h}^{-} u_{i}^{1/2}$$
(3.3)

$$u_i^0 = u_0(x_i) (3.4)$$

for  $i = 1 \dots, M - 1$ , and

$$\mathcal{D}_{\tau}^{0}u_{i}^{n} - \eta D_{h}^{+}D_{h}^{-}D_{h}^{-}D_{h}^{0}\overline{u}_{i}^{n} + D_{h}^{+}D_{h}^{-}D_{h}^{0}\overline{u}_{i}^{n} + \frac{1}{2}\Psi_{\theta}(\mathbf{u}^{n},\overline{\mathbf{u}}^{n})_{i} + D_{h}^{0}\overline{u}_{i}^{n} = \gamma D_{h}^{+}D_{h}^{-}\overline{u}_{i}^{n}$$

$$(3.5)$$

for  $i = 1 \dots, M - 1$  and  $n = 1 \dots, N - 1$ , where

$$\Psi_{\theta}(\mathbf{u}, \mathbf{v})_i := 2\theta u_i D_h^0 v_i + (1 - \theta) D_h^0 (uv)_i.$$
(3.6)

For the implementation of the three-level scheme, the first two initial steps of the solutions are required. Thus, we use (3.3)-(3.4) to compute  $\mathbf{u}^1$ . Then, in (3.5) we use  $\mathbf{u}^{n-1}$  and  $\mathbf{u}^n$  to compute  $\mathbf{u}^{n+1}$ .

In the initial step, the equation (3.3), with i = 1, ..., M - 1, can be written in a matrix-vector form:

$$\mathbf{u}^{1} + \left(\frac{\eta}{2}\right) \frac{\tau}{2h^{5}} A_{1}^{0} \mathbf{u}^{1} + \frac{1}{2} \left(\frac{\tau}{2h^{3}}\right) A_{2}^{0} \mathbf{u}^{1} + \frac{1}{2} \left(\frac{\tau\theta}{2h}\right) A_{3}^{0} \mathbf{u}^{1} + \frac{1}{2} \left(\frac{\tau(1-\theta)}{4h}\right) A_{4}^{0} \mathbf{u}^{1} + \frac{\tau}{4h} A_{5}^{0} \mathbf{u}^{1} - \frac{1}{2} \left(\frac{\gamma\tau}{h^{2}}\right) A_{6}^{0} \mathbf{u}^{1} = \mathbf{u}^{0} - \left(\frac{\eta}{2}\right) \frac{\tau}{2h^{5}} A_{1}^{0} \mathbf{u}^{0} - \frac{1}{2} \left(\frac{\tau}{2h^{3}}\right) A_{2}^{0} \mathbf{u}^{0} - \frac{1}{2} \left(\frac{\tau\theta}{2h}\right) A_{3}^{0} \mathbf{u}^{0} - \frac{1}{2} \left(\frac{\tau(1-\theta)}{4h}\right) A_{4}^{0} \mathbf{u}^{0} - \frac{\tau}{4h} A_{5}^{0} \mathbf{u}^{0} + \frac{1}{2} \left(\frac{\gamma\tau}{h^{2}}\right) A_{6}^{0} \mathbf{u}^{0}.$$
(3.7)

For  $n = 1, 2, \ldots, N - 1$ , the equation (3.5),  $i = 1, \ldots, M - 1$ , can be written as

$$\frac{1}{2}\mathbf{u}^{n+1} + \left(\frac{\eta}{2}\right)\frac{\tau}{2h^5}A_1^n\mathbf{u}^{n+1} + \frac{1}{2}\left(\frac{\tau}{2h^3}\right)A_2^n\mathbf{u}^{n+1} + \frac{1}{2}\left(\frac{\tau\theta}{2h}\right)A_3^n\mathbf{u}^{n+1} \\
+ \frac{1}{2}\left(\frac{\tau(1-\theta)}{4h}\right)A_4^n\mathbf{u}^{n+1} + \frac{\tau}{4h}A_5^n\mathbf{u}^{n+1} - \frac{1}{2}\left(\frac{\gamma\tau}{h^2}\right)A_6^n\mathbf{u}^{n+1} \\
= \frac{1}{2}\mathbf{u}^{n-1} - \left(\frac{\eta}{2}\right)\frac{\tau}{2h^5}A_1^n\mathbf{u}^{n-1} - \frac{1}{2}\left(\frac{\tau}{2h^3}\right)A_2^n\mathbf{u}^{n-1} - \frac{1}{2}\left(\frac{\tau\theta}{2h}\right)A_3^n\mathbf{u}^{n-1} \\
- \frac{1}{2}\left(\frac{\tau(1-\theta)}{4h}\right)A_4^n\mathbf{u}^{n-1} - \frac{\tau}{4h}A_5^n\mathbf{u}^{n-1} + \frac{1}{2}\left(\frac{\gamma\tau}{h^2}\right)A_6^n\mathbf{u}^{n-1}.$$
(3.8)

Here, the coefficients  $A_1^n$ ,  $A_2^n$ ,  $A_3^n$ ,  $A_4^n$ ,  $A_5^n$  and  $A_6^n$  are circulant pentadiagonal matrices or circulant tridiagonal matrices whose nonzero entries on the  $i^{\text{th}}$  row are given by (-5, 4, -1, 0, 5, -4, 1), (2, -1, 0, -2, 1),  $(-u_i^n, 0, u_i^n)$ ,  $(-u_{i-1}^n, 0, u_{i+1}^n)$ , (-1, 0, 1) and (1, -2, 1), respectively.

Next, we will show the numerical solution obtained from the proposed scheme is bounded. The following result is necessary for the proof of boundedness.

**Lemma 3.4.** (Discrete Sobolev's inequality) [25–27]. Define L = b - a. If  $\mathbf{u}^n \in Z_h$ , then

$$\|\mathbf{u}^n\|_{h,\infty} \le \frac{\sqrt{L}}{2} \|D_h^+ \mathbf{u}^n\|_h.$$
(3.9)

**Theorem 3.5.** Let  $\mathbf{u}^1$  and  $\mathbf{u}^{n+1}$  be solutions of the schemes (3.3) and (3.5). Then,  $\|D_h^+\mathbf{u}^1\|_h$  and  $\|D_h^+\mathbf{u}^{n+1}\|_h$  are bounded. It follows that  $\|\mathbf{u}^1\|_{h,\infty}$  and  $\|\mathbf{u}^{n+1}\|_{h,\infty}$  are also bounded.

*Proof.* We take inner product of (3.3), i = 1, ..., M - 1 with  $-D_h^+ D_h^- \mathbf{u}^{1/2}$  to get

$$\langle \mathcal{D}_{\tau}^{+} \mathbf{u}^{0}, -D_{h}^{+} D_{h}^{-} \mathbf{u}^{1/2} \rangle_{h} - \langle \eta D_{h}^{+} D_{h}^{+} D_{h}^{-} D_{h}^{-} D_{h}^{0} \mathbf{u}^{1/2}, -D_{h}^{+} D_{h}^{-} \mathbf{u}^{1/2} \rangle_{h} + \langle D_{h}^{+} D_{h}^{-} D_{h}^{0} \mathbf{u}^{1/2}, -D_{h}^{+} D_{h}^{-} \mathbf{u}^{1/2} \rangle_{h} + \langle D_{h}^{0} \mathbf{u}^{1/2}, -D_{h}^{+} D_{h}^{-} \mathbf{u}^{1/2} \rangle_{h} - \langle \gamma D_{h}^{+} D_{h}^{-} \mathbf{u}^{1/2}, -D_{h}^{+} D_{h}^{-} \mathbf{u}^{1/2} \rangle_{h} = -\langle \frac{1}{2} \Psi_{\theta}(\mathbf{u}^{0}, \mathbf{u}^{1/2}), -D_{h}^{+} D_{h}^{-} \mathbf{u}^{1/2} \rangle_{h}.$$
(3.10)

124

Now we estimate each item in (3.10) as follows. For the first term on the left-hand side, using (3.1) and Lemma 3.1, we have

$$\begin{aligned} \mathcal{A}_{1} &= \langle \mathcal{D}_{\tau}^{+} \mathbf{u}^{0}, -D_{h}^{+} D_{h}^{-} \mathbf{u}^{1/2} \rangle_{h} \\ &= \left\langle \frac{1}{2} D_{h}^{+} \mathbf{u}^{1} + \frac{1}{2} D_{h}^{+} \mathbf{u}^{0}, \frac{1}{\tau} D_{h}^{+} \mathbf{u}^{1} - \frac{1}{\tau} D_{h}^{+} \mathbf{u}^{0} \right\rangle_{h} \\ &= \frac{1}{2\tau} \| D_{h}^{+} \mathbf{u}^{1} \|_{h}^{2} - \frac{1}{2\tau} \| D_{h}^{+} \mathbf{u}^{0} \|_{h}^{2}. \end{aligned}$$
(3.11)

For the second term to the fourth term on the left-hand side, using Lemma 3.2, we have

$$\mathcal{A}_{2} = -\langle \eta D_{h}^{+} D_{h}^{+} D_{h}^{-} D_{h}^{-} D_{h}^{0} \mathbf{u}^{1/2}, -D_{h}^{+} D_{h}^{-} \mathbf{u}^{1/2} \rangle_{h} = 0, \qquad (3.12)$$

$$\mathcal{A}_{3} = \langle D_{h}^{+} D_{h}^{-} D_{h}^{0} \mathbf{u}^{1/2}, -D_{h}^{+} D_{h}^{-} \mathbf{u}^{1/2} \rangle_{h} = 0, \qquad (3.13)$$

$$\mathcal{A}_4 = \langle D_h^0 \mathbf{u}^{1/2}, -D_h^+ D_h^- \mathbf{u}^{1/2} \rangle_h = 0.$$
(3.14)

For the fifth term on the left-hand side, we have

$$\mathcal{A}_{5} = -\langle \gamma D_{h}^{+} D_{h}^{-} \mathbf{u}^{1/2}, -D_{h}^{+} D_{h}^{-} \mathbf{u}^{1/2} \rangle_{h} = \gamma \| D_{h}^{+} D_{h}^{-} \mathbf{u}^{1/2} \|_{h}^{2}.$$
(3.15)

Note that

$$D_h^0(uv)_i = \frac{1}{2}u_{i+1}D_h^+v_i + (D_h^0u_i)v_i + \frac{1}{2}u_{i-1}D_h^+v_{i-1}.$$
(3.16)

For the first term on the right-hand side of (3.10), using the Cauchy–Schwarz inequality, Young's inequality, Lemma 3.3 and (3.6), (3.16), we have

$$\begin{aligned} \mathcal{A}_{6} &= -\langle \frac{1}{2} \Psi_{\theta}(\mathbf{u}^{0}, \mathbf{u}^{1/2}), -D_{h}^{+} D_{h}^{-} \mathbf{u}^{1/2} \rangle_{h} \\ &= \frac{1}{2} h \sum_{i=1}^{M-1} (\Psi_{\theta}(\mathbf{u}^{0}, \mathbf{u}^{1/2})_{i}) (D_{h}^{+} D_{h}^{-} u_{i}^{1/2}) \\ &= \frac{1}{2} h \sum_{i=1}^{M-1} (2\theta u_{i}^{0} D_{h}^{0} u_{i}^{1/2} + (1-\theta) D_{h}^{0} (u^{0} u^{1/2})_{i}) (D_{h}^{+} D_{h}^{-} u_{i}^{1/2}) \\ &= \theta h \sum_{i=1}^{M-1} (u_{i}^{0} D_{h}^{0} u_{i}^{1/2}) (D_{h}^{+} D_{h}^{-} u_{i}^{1/2}) \\ &+ \frac{(1-\theta)}{2} h \sum_{i=1}^{M-1} \left( \frac{1}{2} u_{i+1}^{0} D_{h}^{+} u_{i}^{1/2} + (D_{h}^{0} u_{i}^{0}) u_{i}^{1/2} + \frac{1}{2} u_{i-1}^{0} D_{h}^{+} u_{i-1}^{1/2} \right) (D_{h}^{+} D_{h}^{-} u_{i}^{1/2}) \\ &\leq \theta C \| D_{h}^{0} \mathbf{u}^{1/2} \|_{h} \| D_{h}^{+} D_{h}^{-} \mathbf{u}^{1/2} \|_{h} + \frac{1-\theta}{4} C \| D_{h}^{+} \mathbf{u}^{1/2} \|_{h} \| D_{h}^{+} D_{h}^{-} \mathbf{u}^{1/2} \|_{h} \\ &+ \frac{(1-\theta)}{2} \| \mathbf{u}^{1/2} \|_{h,\infty} \left( \| D_{h}^{0} \mathbf{u}^{0} \|_{h} \| D_{h}^{+} D_{h}^{-} \mathbf{u}^{1/2} \|_{h} \right) + \frac{1-\theta}{4} C \| D_{h}^{+} \mathbf{u}^{1/2} \|_{h} \| D_{h}^{+} D_{h}^{-} \mathbf{u}^{1/2} \|_{h} \\ &\leq C \| D_{h}^{+} \mathbf{u}^{1/2} \|_{h} \| D_{h}^{+} D_{h}^{-} \mathbf{u}^{1/2} \|_{h} \\ &\leq C \| D_{h}^{+} \mathbf{u}^{1/2} \|_{h} \| D_{h}^{+} D_{h}^{-} \mathbf{u}^{1/2} \|_{h} \\ &\leq \frac{C^{2}}{4\gamma} \| D_{h}^{+} \mathbf{u}^{1/2} \|_{h}^{2} + \gamma \| D_{h}^{+} D_{h}^{-} \mathbf{u}^{1/2} \|_{h}^{2}. \end{aligned}$$

We have that (3.10) can be written as

$$\mathcal{A}_1 + \mathcal{A}_2 + \mathcal{A}_3 + \mathcal{A}_4 + \mathcal{A}_5 = \mathcal{A}_6,$$

which simplifies to

$$\begin{aligned} \frac{1}{2\tau} \Big( \|D_h^+ \mathbf{u}^1\|_h^2 - \|D_h^+ \mathbf{u}^0\|_h^2 \Big) + \gamma \|D_h^+ D_h^- \mathbf{u}^{1/2}\|_h^2 &\leq \frac{C^2}{4\gamma} \|D_h^+ \mathbf{u}^{1/2}\|_h^2 + \gamma \|D_h^+ D_h^- \mathbf{u}^{1/2}\|_h^2 \\ \|D_h^+ \mathbf{u}^1\|_h^2 - \|D_h^+ \mathbf{u}^0\|_h^2 &\leq \frac{\tau C^2}{4\gamma} \Big( \|D_h^+ \mathbf{u}^1\|_h^2 + \|D_h^+ \mathbf{u}^0\|_h^2 \Big). \end{aligned}$$

Hence,

$$\|D_{h}^{+}\mathbf{u}^{1}\|_{h}^{2} - \|D_{h}^{+}\mathbf{u}^{0}\|_{h}^{2} \le C\tau \Big(\|D_{h}^{+}\mathbf{u}^{1}\|_{h}^{2} + \|D_{h}^{+}\mathbf{u}^{0}\|_{h}^{2}\Big).$$
(3.18)

Define

$$B^{1} = \|D_{h}^{+}\mathbf{u}^{1}\|_{h}^{2}, \quad B^{0} = \|D_{h}^{+}\mathbf{u}^{0}\|_{h}^{2}, \tag{3.19}$$

then (3.18) can be rewritten as follows:

$$B^{1} - B^{0} \le C\tau(B^{1} + B^{0})$$
$$(1 - C\tau)B^{1} \le (1 + C\tau)B^{0}.$$

If  $\tau$  is sufficiently small, i.e.  $\tau \leq \frac{1}{2C}$ , then

$$B^{1} \leq \frac{(1+C\tau)}{(1-C\tau)} B^{0} \leq (1+4C\tau) B^{0}.$$
(3.20)

Hence,  $\|D_h^+ \mathbf{u}^1\|_h$  is bounded. It follows that  $\|\mathbf{u}^1\|_{h,\infty}$  is also bounded. Next, assume that  $\|D_h^+ \mathbf{u}^k\|_h$  is bounded for k = 2, ..., n. Then, there exists a constant C that satisfies

$$||D_h^+ u^k||_h \le \frac{2}{\sqrt{L}}C, \quad ||u^k||_{h,\infty} \le C, \quad k = 1, 2, \dots, n.$$
 (3.21)

We will show that  $\|D_h^+ \mathbf{u}^{n+1}\|_h, n \ge 1$ , is bounded. We first take inner product of (3.5),  $i = 1, \ldots, M - 1$  with  $-2D_h^+ D_h^- \overline{\mathbf{u}}^n$  to get

$$\langle \mathcal{D}_{\tau}^{0} \mathbf{u}^{n}, -2D_{h}^{+} D_{h}^{-} \overline{\mathbf{u}}^{n} \rangle_{h} - \langle \eta D_{h}^{+} D_{h}^{+} D_{h}^{-} D_{h}^{-} D_{h}^{0} \overline{\mathbf{u}}^{n}, -2D_{h}^{+} D_{h}^{-} \overline{\mathbf{u}}^{n} \rangle_{h}$$

$$+ \langle D_{h}^{+} D_{h}^{-} D_{h}^{0} \overline{\mathbf{u}}^{n}, -2D_{h}^{+} D_{h}^{-} \overline{\mathbf{u}}^{n} \rangle_{h} + \langle D_{h}^{0} \overline{\mathbf{u}}^{n}, -2D_{h}^{+} D_{h}^{-} \overline{\mathbf{u}}^{n} \rangle_{h}$$

$$- \langle \gamma D_{h}^{+} D_{h}^{-} \overline{\mathbf{u}}^{n}, -2D_{h}^{+} D_{h}^{-} \overline{\mathbf{u}}^{n} \rangle_{h} = - \langle \frac{1}{2} \Psi_{\theta} (\mathbf{u}^{n}, \overline{\mathbf{u}}^{n}), -2D_{h}^{+} D_{h}^{-} \overline{\mathbf{u}}^{n} \rangle_{h}.$$

$$(3.22)$$

Now estimate each item in (3.22) as follows. For the first term on the left-hand side, using (3.1), Lemma 3.1, we have

$$\mathcal{B}_{1} = \langle \mathcal{D}_{\tau}^{0} \mathbf{u}^{n}, -2D_{h}^{+} D_{h}^{-} \overline{\mathbf{u}}^{n} \rangle_{h}$$

$$= 2 \Big\langle \frac{1}{2} D_{h}^{+} \mathbf{u}^{n+1} + \frac{1}{2} D_{h}^{+} \mathbf{u}^{n-1}, \frac{1}{2\tau} D_{h}^{+} \mathbf{u}^{n+1} - \frac{1}{2\tau} D_{h}^{+} \mathbf{u}^{n-1} \Big\rangle_{h}$$

$$= \frac{1}{2\tau} \| D_{h}^{+} \mathbf{u}^{n+1} \|_{h}^{2} - \frac{1}{2\tau} \| D_{h}^{+} \mathbf{u}^{n-1} \|_{h}^{2}.$$
(3.23)

For the second term to the fourth term on the left-hand side, using Lemma 3.2, we have

$$\mathcal{B}_2 = -\langle \eta D_h^+ D_h^- D_h^- D_h^0 \overline{\mathbf{u}}^n, -2D_h^+ D_h^- \overline{\mathbf{u}}^n \rangle_h = 0, \qquad (3.24)$$

$$\mathcal{B}_3 = \langle D_h^+ D_h^- D_h^0 \overline{\mathbf{u}}^n, -2D_h^+ D_h^- \overline{\mathbf{u}}^n \rangle_h = 0, \qquad (3.25)$$

$$\mathcal{B}_4 = \langle D_h^0 \overline{\mathbf{u}}^n, -2D_h^+ D_h^- \overline{\mathbf{u}}^n \rangle_h = 0.$$
(3.26)

126

For the fifth term on the left-hand side, we have

$$\mathcal{B}_{5} = -\langle \gamma D_{h}^{+} D_{h}^{-} \overline{\mathbf{u}}^{n}, -2D_{h}^{+} D_{h}^{-} \overline{\mathbf{u}}^{n} \rangle_{h}$$
  
$$= 2\gamma \| D_{h}^{+} D_{h}^{-} \overline{\mathbf{u}}^{n} \|_{h}^{2}.$$
(3.27)

For the first term on the right-hand side of (3.22), using the Cauchy–Schwarz inequality, Young's inequality, Lemma 3.3 and (3.6), (3.16), (3.21), we have

$$\mathcal{B}_{6} = -\langle \frac{1}{2} \Psi_{\theta}(\mathbf{u}^{n}, \overline{\mathbf{u}}^{n}), -2D_{h}^{+}D_{h}^{-}\overline{\mathbf{u}}^{n}\rangle_{h} \\
= h \sum_{i=1}^{M-1} (\Psi_{\theta}(\mathbf{u}^{n}, \overline{\mathbf{u}}^{n})_{i})(D_{h}^{+}D_{h}^{-}\overline{u}_{i}^{n}) \\
= h \sum_{i=1}^{M-1} (2\theta u_{i}^{n}D_{h}^{0}\overline{u}_{i}^{n} + (1-\theta)D_{h}^{0}(u^{n}\overline{u}^{n})_{i})(D_{h}^{+}D_{h}^{-}\overline{u}_{i}^{n}) \\
= 2\theta h \sum_{i=1}^{M-1} (u_{i}^{n}D_{h}^{0}\overline{u}_{i}^{n})(D_{h}^{+}D_{h}^{-}\overline{u}_{i}^{n}) \\
+ (1-\theta)h \sum_{i=1}^{M-1} \left(\frac{1}{2}u_{i+1}^{n}D_{h}^{+}\overline{u}_{i}^{n} + (D_{h}^{0}u_{i}^{n})\overline{u}_{i}^{n} + \frac{1}{2}u_{i-1}^{n}D_{h}^{+}\overline{u}_{i-1}^{n}\right)(D_{h}^{+}D_{h}^{-}\overline{u}_{i}^{n}) \\
\leq 2C \|D_{h}^{+}\overline{\mathbf{u}}^{n}\|_{h}\|D_{h}^{+}D_{h}^{-}\overline{\mathbf{u}}^{n}\|_{h} \\
\leq \frac{C^{2}}{2\gamma} \|D_{h}^{+}\overline{\mathbf{u}}^{n}\|_{h}^{2} + 2\gamma \|D_{h}^{+}D_{h}^{-}\overline{\mathbf{u}}^{n}\|_{h}^{2}.$$
(3.28)

We have that (3.22) can be written as

$$\mathcal{B}_1+\mathcal{B}_2+\mathcal{B}_3+\mathcal{B}_4+\mathcal{B}_5=\mathcal{B}_6,$$

which simplifies to

$$\begin{aligned} \frac{1}{2\tau} \Big( \|D_h^+ \mathbf{u}^{n+1}\|_h^2 - \|D_h^+ \mathbf{u}^{n-1}\|_h^2 \Big) + 2\gamma \|D_h^+ D_h^- \overline{\mathbf{u}}^n\|_h^2 &\leq \frac{C^2}{2\gamma} \|D_h^+ \overline{\mathbf{u}}^n\|_h^2 \\ &+ 2\gamma \|D_h^+ D_h^- \overline{\mathbf{u}}^n\|_h^2 \\ \|D_h^+ \mathbf{u}^{n+1}\|_h^2 - \|D_h^+ \mathbf{u}^{n-1}\|_h^2 &\leq \frac{\tau C^2}{2\gamma} \|D_h^+ \mathbf{u}^{n+1}\|_h^2 \\ &+ \frac{\tau C^2}{2\gamma} \|D_h^+ \mathbf{u}^{n-1}\|_h^2. \end{aligned}$$

Hence,

$$\|D_{h}^{+}\mathbf{u}^{n+1}\|_{h}^{2} - \|D_{h}^{+}\mathbf{u}^{n-1}\|_{h}^{2} \le C\tau \Big(\|D_{h}^{+}\mathbf{u}^{n+1}\|_{h}^{2} + \|D_{h}^{+}\mathbf{u}^{n-1}\|_{h}^{2}\Big).$$
(3.29)

Define

$$B^{n} = \|D_{h}^{+}\mathbf{u}^{n+1}\|_{h}^{2} + \|D_{h}^{+}\mathbf{u}^{n}\|_{h}^{2},$$
(3.30)

then (3.29) can be rewritten as follows:

$$B^{n} - B^{n-1} \le C\tau (B^{n} + B^{n-1})$$
  
(1 - C\tau) B^{n} \le (1 + C\tau) B^{n-1}.

If  $\tau$  is sufficiently small, i.e.  $\tau \leq \frac{1}{2C}$ , then

$$B^{n} \leq \frac{(1+C\tau)}{(1-C\tau)} B^{n-1} \leq (1+4C\tau) B^{n-1} \leq e^{(4C\tau n)} B^{1} \leq e^{(4CT)} B^{1}.$$
 (3.31)

Hence,  $\|D_h^+ \mathbf{u}^{n+1}\|_h$  is bounded. It follows that  $\|\mathbf{u}^{n+1}\|_{h,\infty}$  is also bounded.

# 3.3. Stability Analysis

We will show that numerical solution of (3.3)–(3.5) preserves the invariants in the discrete sense.

Theorem 3.6. Define

$$Q_h^n = h \sum_{i=1}^{M-1} u_i^{n+1/2} + \frac{\theta \tau}{2} h \sum_{i=1}^{M-1} u_i^n D_h^0 u_i^{n+1}.$$
(3.32)

If  $\mathbf{u}^n$  is a solution of (3.3)-(3.5), then

$$Q_h^n = Q_h^{n-1} = \dots = Q_h^0 = h \sum_{i=1}^{M-1} u_i^0 + \frac{\theta\tau}{2} h \sum_{i=1}^{M-1} u_i^0 D_h^0 u_i^1,$$
(3.33)

for any  $\theta \in [0,1]$ .

*Proof.* Multiply (3.5) by  $\tau h$  and take summation on  $i = 1, \ldots, M - 1$  to arrive at

$$\tau h \sum_{i=1}^{M-1} (D_{\tau}^{0} u_{i}^{n}) - \eta \tau h \sum_{i=1}^{M-1} (D_{h}^{+} D_{h}^{+} D_{h}^{-} D_{h}^{-} D_{h}^{0} \overline{u}_{i}^{n}) + \tau h \sum_{i=1}^{M-1} (D_{h}^{+} D_{h}^{-} D_{h}^{0} \overline{u}_{i}^{n}) + \frac{1}{2} \tau h \sum_{i=1}^{M-1} \Psi_{\theta}(\mathbf{u}^{n}, \overline{\mathbf{u}}^{n})_{i} + \tau h \sum_{i=1}^{M-1} (D_{h}^{0} \overline{u}_{i}^{n}) = \gamma \tau h \sum_{i=1}^{M-1} (D_{h}^{+} D_{h}^{-} u_{i}^{n}).$$

We get

$$\frac{1}{2}h\sum_{i=1}^{M-1} \left(u_i^{n+1} - u_i^{n-1}\right) - \eta\tau h\sum_{i=1}^{M-1} \left(D_h^+ D_h^+ D_h^- D_h^- D_h^0 \overline{u}_i^n\right) + \tau h\sum_{i=1}^{M-1} \left(D_h^+ D_h^- D_h^0 \overline{u}_i^n\right) + \theta\tau h\sum_{i=1}^{M-1} \left(u_i^n D_h^0 \overline{u}_i^n\right) + \frac{1-\theta}{2}\tau h\sum_{i=1}^{M-1} D_h^0 \left(u_i^n \overline{u}_i^n\right) + \tau h\sum_{i=1}^{M-1} \left(D_h^0 \overline{u}_i^n\right) = \gamma\tau h\sum_{i=1}^{M-1} \left(D_h^+ D_h^- u_i^n\right)$$

Since all terms other than the first and fourth terms vanish, we obtain

$$\frac{1}{2}h\sum_{i=1}^{M-1} \left(u_i^{n+1} - u_i^{n-1}\right) + \theta\tau h\sum_{i=1}^{M-1} \left(u_i^n D_h^0 \overline{u}_i^n\right) = 0$$

and hence,

$$\frac{1}{2}h\sum_{i=1}^{M-1} \left(u_i^{n+1} - u_i^{n-1}\right) + \frac{\theta\tau}{4}h\sum_{i=1}^{M-1} \left(u_i^n u_{i+1}^{n+1} - u_i^n u_{i-1}^{n+1} + u_i^n u_{i+1}^{n-1} - u_i^n u_{i-1}^{n-1}\right) = 0.$$

After rewriting, we get

$$\frac{1}{2}h\sum_{i=1}^{M-1} \left(u_i^{n+1} - u_i^{n-1}\right) + \frac{\theta\tau}{4}h\sum_{i=1}^{M-1} \left(u_i^n u_{i+1}^{n+1} - u_i^n u_{i-1}^{n+1} + u_{i-1}^n u_i^{n-1} - u_{i+1}^n u_i^{n-1}\right) = 0$$

and thus,

$$\frac{1}{2}h\sum_{i=1}^{M-1} \left(u_i^{n+1} - u_i^{n-1}\right) + \frac{\theta\tau}{2}h\sum_{i=1}^{M-1} \left(u_i^n D_h^0 u_i^{n+1} - u_i^{n-1} D_h^0 u_i^n\right) = 0$$

This shows that  $Q_h^n - Q_h^{n-1} = 0$  for n = 1, ..., N - 1. Similarly, multiply (3.3) by  $\tau h$  and take summation over *i* to obtain

$$h\sum_{i=1}^{M-1} u_i^1 = h\sum_{i=1}^{M-1} u_i^0 - \frac{\theta\tau}{2}h\sum_{i=1}^{M-1} u_i^0 D_h^0 u_i^1 = 0.$$

Substitute this into  $Q_h^0$  to find that

$$Q_h^0 = h \sum_{i=1}^{M-1} u_i^0 + \frac{\theta \tau}{4} h \sum_{i=1}^{M-1} u_i^0 D_h^0 u_i^1$$

as needed.

Theorem 3.7. Define

$$E_h^n = \frac{1}{2} \|\mathbf{u}^{n+1}\|_h^2 + \frac{1}{2} \|\mathbf{u}^n\|_h^2.$$
(3.34)

Let  $\mathbf{u}^n$  be a solution of (3.3) and (3.5). If  $\theta = \frac{1}{3}$ , then

$$E_h^n \le E_h^{n-1} \le \dots \le E_h^0 \le \|\mathbf{u}^0\|_h^2$$
(3.35)

for any n > 0.

Proof. First, consider the summation

$$h \sum_{i=1}^{M-1} \left[ u_i^n \left( D_h^0 \overline{u}_i^n \right) \overline{u}_i^n + D_h^0 \left( u_i^n \overline{u}_i^n \right) \overline{u}_i^n \right]$$
  
=  $h \sum_{i=1}^{M-1} \left[ u_i^n \overline{u}_{i+1}^n \overline{u}_i^n - u_i^n \overline{u}_{i-1}^n \overline{u}_i^n + u_{i+1}^n \overline{u}_{i+1}^n \overline{u}_i^n - u_{i-1}^n \overline{u}_{i-1}^n \overline{u}_i^n \right] = 0.$  (3.36)

We multiply (3.5) by  $2\tau h \overline{u}_i^n$  and take summation over *i* to obtain

$$2\tau h \sum_{i=1}^{M-1} \overline{u}_i^n (D_\tau^0 u_i^n) - 2\eta \tau h \sum_{i=1}^{M-1} \overline{u}_i^n (D_h^+ D_h^+ D_h^- D_h^- D_h^0 \overline{u}_i^n) + 2\tau h \sum_{i=1}^{M-1} \overline{u}_i^n (D_h^+ D_h^- D_h^0 \overline{u}_i^n) + \frac{1}{2} (2\tau h) \sum_{i=1}^{M-1} \overline{u}_i^n \Psi_\theta(\mathbf{u}^n, \overline{\mathbf{u}}^n)_i + 2\tau h \sum_{i=1}^{M-1} \overline{u}_i^n (D_h^0 \overline{u}_i^n) = 2\gamma \tau h \sum_{i=1}^{M-1} \overline{u}_i^n (D_h^+ D_h^- u_i^n).$$

Using (3.36) and Lemma 3.1, we get

$$\frac{1}{2}h\sum_{i=1}^{M-1} \left[ \left( u_i^{n+1} \right)^2 - \left( u_i^{n-1} \right)^2 \right] - 2\eta\tau h\sum_{i=1}^{M-1} \overline{u}_i^n (D_h^+ D_h^+ D_h^- D_h^0 \overline{u}_i^n) 
+ 2\tau h\sum_{i=1}^{M-1} \overline{u}_i^n (D_h^+ D_h^- D_h^0 \overline{u}_i^n) + (3\theta - 1)\tau h\sum_{i=1}^{M-1} D_h^0 \left( u_i^n \overline{u}_i^n \right) \overline{u}_i^n 
+ 2\tau h\sum_{i=1}^{M-1} \overline{u}_i^n (D_h^0 \overline{u}_i^n) = -2\gamma\tau h\sum_{i=1}^{M-1} (D_h^+ \overline{u}_i^n)^2.$$
(3.37)

Take  $\theta = \frac{1}{3}$ . Using Lemma 3.2 and (3.37), we arrive at

$$\frac{1}{2}h\sum_{i=1}^{M-1} \left[ \left( u_i^{n+1} \right)^2 - \left( u_i^{n-1} \right)^2 \right] + 2\gamma\tau h\sum_{i=1}^{M-1} (D_h^+ \overline{u}_i^n)^2 = 0.$$
(3.38)

This shows that

$$E_h^n - E_h^{n-1} + 2\gamma\tau h \sum_{i=1}^{M-1} (D_h^+ \overline{u}_i^n)^2 = 0, \qquad (3.39)$$

for n = 1, ..., N - 1.

Using similar idea, one can show from (3.3)–(3.4) that

$$\|\mathbf{u}^{1}\|_{h}^{2} - \|\mathbf{u}^{0}\|_{h}^{2} + 2\gamma\tau h \sum_{i=1}^{M-1} (D_{h}^{+}u_{i}^{1/2})^{2} = 0.$$
(3.40)

Substitute this into the definition of  $E_h^0$  to derive the desired result.

## 3.4. EXISTENCE AND UNIQUENESS

In this subsection, we prove the solvability of solutions for the scheme (3.3)-(3.5). This guarantees the existence and uniqueness of our numerical solution.

**Theorem 3.8.** The finite difference schemes (3.3)-(3.5) is uniquely solvable.

*Proof.* We first consider from 
$$(3.3)$$

$$\left(\frac{u_i^1 - u_i^0}{\tau}\right) - \eta D_h^+ D_h^+ D_h^- D_h^- D_h^0 \left(\frac{u_i^1 + u_i^0}{2}\right) + D_h^+ D_h^- D_h^0 \left(\frac{u_i^1 + u_i^0}{2}\right) + \frac{1}{2} \Psi_\theta \left(\mathbf{u}^0, \left(\frac{\mathbf{u}^1 + \mathbf{u}^0}{2}\right)\right)_i + D_h^0 \left(\frac{u_i^1 + u_i^0}{2}\right) = \gamma D_h^+ D_h^- \left(\frac{u_i^1 + u_i^0}{2}\right).$$

We get

$$\frac{1}{\tau}u_{i}^{1} - \frac{\eta}{2}D_{h}^{+}D_{h}^{+}D_{h}^{-}D_{h}^{-}D_{h}^{0}u_{i}^{1} + \frac{1}{2}D_{h}^{+}D_{h}^{-}D_{h}^{0}u_{i}^{1} 
+ \frac{1}{4}\Psi_{\theta}(\mathbf{u}^{0},\mathbf{u}^{1})_{i} + \frac{1}{2}D_{h}^{0}u_{i}^{1} - \frac{\gamma}{2}D_{h}^{+}D_{h}^{-}u_{i}^{1} = 0,$$
(3.41)

We take the inner product of (3.41), i = 1, ..., M - 1 with  $\mathbf{u}^1$  to obtain

$$\frac{1}{\tau} \langle \mathbf{u}^1, \mathbf{u}^1 \rangle_h - \frac{\eta}{2} \langle D_h^+ D_h^+ D_h^- D_h^- D_h^0 \mathbf{u}^1, \mathbf{u}^1 \rangle_h + \frac{1}{2} \langle D_h^+ D_h^- D_h^0 \mathbf{u}^1, \mathbf{u}^1 \rangle_h + \frac{1}{4} \langle \Psi_\theta(\mathbf{u}^0, \mathbf{u}^1), \mathbf{u}^1 \rangle_h + \frac{1}{2} \langle D_h^0 \mathbf{u}^1, \mathbf{u}^1 \rangle_h - \frac{\gamma}{2} \langle D_h^+ D_h^- \mathbf{u}^1, \mathbf{u}^1 \rangle_h = 0.$$

Using Lemma 3.2, we have

$$\frac{1}{\tau} \langle \mathbf{u}^1, \mathbf{u}^1 \rangle_h + \frac{1}{4} \langle \Psi_\theta(\mathbf{u}^0, \mathbf{u}^1), \mathbf{u}^1 \rangle_h - \frac{\gamma}{2} \langle D_h^+ D_h^- \mathbf{u}^1, \mathbf{u}^1 \rangle_h = 0,$$
  
$$\frac{1}{\tau} \langle \mathbf{u}^1, \mathbf{u}^1 \rangle_h = -\frac{1}{4} \langle \Psi_\theta(\mathbf{u}^0, \mathbf{u}^1), \mathbf{u}^1 \rangle_h + \frac{\gamma}{2} \langle D_h^+ D_h^- \mathbf{u}^1, \mathbf{u}^1 \rangle_h.$$
(3.42)

Consider the summation

or

$$h\sum_{i=1}^{M-1} \left[ u_i^0 \left( D_h^0 u_i^1 \right) + D_h^0 \left( u_i^0 u_i^1 \right) \right] u_i^1$$
  
=  $h\sum_{i=1}^{M-1} \left[ u_i^0 u_{i+1}^1 u_i^1 - u_i^0 u_{i-1}^1 u_i^1 + u_{i+1}^0 u_{i+1}^1 u_i^1 - u_{i-1}^0 u_{i-1}^1 u_i^1 \right] = 0.$  (3.43)

Now estimate each item in (3.42) as follows. For the first term, we have

$$\mathcal{D}_1 \equiv \frac{1}{\tau} \langle \mathbf{u}^1, \mathbf{u}^1 \rangle_h = \frac{1}{\tau} \| \mathbf{u}^1 \|_h^2.$$
(3.44)

For the second term, using Cauchy-Schwarz inequality, Young's inequality, Theorem 3.5 and (3.43), we obtain

$$\mathcal{D}_{2} \equiv -\frac{1}{4} \langle \Psi_{\theta}(\mathbf{u}^{0}, \mathbf{u}^{1}), \mathbf{u}^{1} \rangle_{h}$$

$$= -\frac{1}{4} h \sum_{i=1}^{M-1} \left[ 2\theta u_{i}^{0} D_{h}^{0} u_{i}^{1} + (1-\theta) D_{h}^{0} (u_{i}^{0} u_{i}^{1}) \right] u_{i}^{1}$$

$$\leq Ch \sum_{i=1}^{M-1} |D_{h}^{0} u_{i}^{1}| |u_{i}^{1}|$$

$$\leq C \left( ||D_{h}^{+} \mathbf{u}^{1}||_{h}^{2} + ||\mathbf{u}^{1}||_{h}^{2} \right).$$
(3.45)

For the third term, using Lemma 3.1, we have

$$\mathcal{D}_3 \equiv \frac{\gamma}{2} \langle D_h^+ D_h^- \mathbf{u}^1, \mathbf{u}^1 \rangle_h = -\frac{\gamma}{2} \| D_h^+ \mathbf{u}^1 \|_h^2.$$
(3.46)

We have that (3.42) can be written as

$$\mathcal{D}_1 = \mathcal{D}_2 + \mathcal{D}_3,$$

which simplifies to

$$\frac{1}{\tau} \|\mathbf{u}^{1}\|_{h}^{2} \leq C\left(\|D_{h}^{+}\mathbf{u}^{1}\|_{h}^{2} + \|\mathbf{u}^{1}\|_{h}^{2}\right) - \frac{\gamma}{2} \|D_{h}^{+}\mathbf{u}^{1}\|_{h}^{2} 
\|\mathbf{u}^{1}\|_{h}^{2} \leq C\tau\left(\|D_{h}^{+}\mathbf{u}^{1}\|_{h}^{2} + \|\mathbf{u}^{1}\|_{h}^{2}\right) - C\tau \|D_{h}^{+}\mathbf{u}^{1}\|_{h}^{2}.$$
(3.47)

If  $\tau$  is sufficiently small, i.e.  $\tau \leq \frac{1}{2C}$ , then

$$(1 - C\tau) \|\mathbf{u}^1\|_h^2 = 0.$$

Consequently,

$$\|\mathbf{u}^1\|_h^2 = 0.$$

This implies that there uniquely exists the trivial solution satisfying (3.3). Similarly, from (3.5), we have

$$\left(\frac{u_i^{n+1} - u_i^{n-1}}{2\tau}\right) - \eta D_h^+ D_h^+ D_h^- D_h^- D_h^0 \left(\frac{u_i^{n+1} + u_i^{n-1}}{2}\right) + D_h^+ D_h^- D_h^0 \left(\frac{u_i^{n+1} + u_i^{n-1}}{2}\right)$$
  
+  $\frac{1}{2} \Psi_\theta \left(\mathbf{u}^n, \left(\frac{\mathbf{u}^{n+1} + \mathbf{u}^{n-1}}{2}\right)\right)_i + D_h^0 \left(\frac{u_i^{n+1} + u_i^{n-1}}{2}\right) = \gamma D_h^+ D_h^- \left(\frac{u_i^{n+1} + u_i^{n-1}}{2}\right).$ 

We get

$$\frac{1}{2\tau}u_{i}^{n+1} - \frac{\eta}{2}D_{h}^{+}D_{h}^{+}D_{h}^{-}D_{h}^{-}D_{h}^{0}u_{i}^{n+1} + \frac{1}{2}D_{h}^{+}D_{h}^{-}D_{h}^{0}u_{i}^{n+1} 
+ \frac{1}{4}\Psi_{\theta}(\mathbf{u}^{n},\mathbf{u}^{n+1})_{i} + \frac{1}{2}D_{h}^{0}u_{i}^{n+1} - \frac{\gamma}{2}D_{h}^{+}D_{h}^{-}u_{i}^{n+1} = 0,$$
(3.48)

We take the inner product of (3.48), i = 1, ..., M - 1 with  $\mathbf{u}^{n+1}$  to obtain

$$\frac{1}{2\tau} \langle \mathbf{u}^{n+1}, \mathbf{u}^{n+1} \rangle_h - \frac{\eta}{2} \langle D_h^+ D_h^+ D_h^- D_h^- D_h^0 \mathbf{u}^{n+1}, \mathbf{u}^{n+1} \rangle_h + \frac{1}{2} \langle D_h^+ D_h^- D_h^0 \mathbf{u}^{n+1}, \mathbf{u}^{n+1} \rangle_h \\ + \frac{1}{4} \langle \Psi_\theta(\mathbf{u}^n, \mathbf{u}^{n+1}), \mathbf{u}^{n+1} \rangle_h + \frac{1}{2} \langle D_h^0 \mathbf{u}^{n+1}, \mathbf{u}^{n+1} \rangle_h - \frac{\gamma}{2} \langle D_h^+ D_h^- \mathbf{u}^{n+1}, \mathbf{u}^{n+1} \rangle_h = 0.$$

Using Lemma 3.2, we have

$$\frac{1}{2\tau} \langle \mathbf{u}^{n+1}, \mathbf{u}^{n+1} \rangle_h + \frac{1}{4} \langle \Psi_\theta(\mathbf{u}^n, \mathbf{u}^{n+1}), \mathbf{u}^{n+1} \rangle_h - \frac{\gamma}{2} \langle D_h^+ D_h^- \mathbf{u}^{n+1}, \mathbf{u}^{n+1} \rangle_h = 0,$$

or

$$\frac{1}{2\tau} \langle \mathbf{u}^{n+1}, \mathbf{u}^{n+1} \rangle_h = -\frac{1}{4} \langle \Psi_\theta(\mathbf{u}^n, \mathbf{u}^{n+1}), \mathbf{u}^{n+1} \rangle_h + \frac{\gamma}{2} \langle D_h^+ D_h^- \mathbf{u}^{n+1}, \mathbf{u}^{n+1} \rangle_h.$$
(3.49)

Considering the summation, we obtain

$$h \sum_{i=1}^{M-1} \left[ u_i^n \left( D_h^0 u_i^{n+1} \right) + D_h^0 \left( u_i^n u_i^{n+1} \right) \right] u_i^{n+1}$$
  
=  $h \sum_{i=1}^{M-1} \left[ u_i^n u_{i+1}^{n+1} u_i^{n+1} - u_i^n u_{i-1}^{n+1} u_i^{n+1} + u_{i+1}^n u_{i+1}^{n+1} u_i^{n+1} - u_{i-1}^n u_{i-1}^{n+1} u_i^{n+1} \right]$   
= 0. (3.50)

Now estimate each item in (3.49) as follows. For the first term, we have

$$\mathcal{F}_1 \equiv \frac{1}{2\tau} \langle \mathbf{u}^{n+1}, \mathbf{u}^{n+1} \rangle_h = \frac{1}{2\tau} \| \mathbf{u}^{n+1} \|_h^2.$$
(3.51)

For the second term, using Cauchy-Schwarz inequality, Young's inequality, Theorem 3.5 and (3.50), we obtain

$$\mathcal{F}_{2} \equiv -\frac{1}{4} \langle \Psi_{\theta}(\mathbf{u}^{n}, \mathbf{u}^{n+1}), \mathbf{u}^{n+1} \rangle_{h}$$
  
$$\leq C \left( \|D_{h}^{+} \mathbf{u}^{n+1}\|_{h}^{2} + \|\mathbf{u}^{n+1}\|_{h}^{2} \right).$$
(3.52)

For the third term, using Lemma 3.1, we have

$$\mathcal{F}_3 \equiv \frac{\gamma}{2} \langle D_h^+ D_h^- \mathbf{u}^{n+1}, \mathbf{u}^{n+1} \rangle_h = -\frac{\gamma}{2} \| D_h^+ \mathbf{u}^{n+1} \|_h^2.$$
(3.53)

We have that (3.49) can be written as

$$\mathcal{F}_1 = \mathcal{F}_2 + \mathcal{F}_3,$$

which simplifies to

$$\begin{aligned} \frac{1}{2\tau} \|\mathbf{u}^{n+1}\|_{h}^{2} &\leq C\left(\|D_{h}^{+}\mathbf{u}^{n+1}\|_{h}^{2} + \|\mathbf{u}^{n+1}\|_{h}^{2}\right) - \frac{\gamma}{2} \|D_{h}^{+}\mathbf{u}^{n+1}\|_{h}^{2} \\ \|\mathbf{u}^{n+1}\|_{h}^{2} &\leq 2C\tau\left(\|D_{h}^{+}\mathbf{u}^{n+1}\|_{h}^{2} + \|\mathbf{u}^{n+1}\|_{h}^{2}\right) - 2C\tau \|D_{h}^{+}\mathbf{u}^{n+1}\|_{h}^{2}.\end{aligned}$$

If  $\tau$  is sufficiently small, i.e.  $\tau \leq \frac{1}{2C}$ , then

$$(1 - 2C\tau) \|\mathbf{u}^{n+1}\|_h^2 = 0.$$

Consequently,

$$\|\mathbf{u}^{n+1}\|_h^2 = 0.$$

This implies that there uniquely exists the trivial solution satisfying (3.5). Hence,  $\mathbf{u}^1$  and  $\mathbf{u}^{n+1}$  are uniquely solvable, and this completes the proof of the theorem.

## 4. Convergence Analysis

In this section, we study the error analysis of the numerical solution obtained from the proposed scheme.

Define  $e_i^n = v_i^n - u_i^n$ , where  $v_i^n$  is the exact solution of (1.4)-(1.6) at the point  $(x_i, t^n)$ , and  $u_i^n$  is the numerical solution obtained from (3.3)-(3.5). From (3.3)-(3.4), we have that the truncation errors at the time step  $t^0$ , denoted  $\mathcal{T}^0$ , satisfies

$$\mathcal{D}_{\tau}^{+}e_{i}^{0} - \eta D_{h}^{+}D_{h}^{+}D_{h}^{-}D_{h}^{-}D_{h}^{0}e_{i}^{1/2} + D_{h}^{+}D_{h}^{-}D_{h}^{0}e_{i}^{1/2} + \frac{1}{2}[\Psi_{\theta}(\mathbf{v}^{0},\mathbf{v}^{1/2})_{i} - \Psi_{\theta}(\mathbf{u}^{0},\mathbf{u}^{1/2})_{i}] + D_{h}^{0}e_{i}^{1/2} = \gamma D_{h}^{+}D_{h}^{-}e_{i}^{1/2} + \mathcal{T}_{i}^{0}.$$
(4.1)

Using Taylor series expansion, one can show there exists  $c_1$  such that

$$|\mathcal{T}_i^0| \le c_1(\tau + h^2).$$

On the other hand, we have from (3.5) that the truncation errors at the time step  $t^n$ ,  $n \ge 1$ , denoted  $\mathcal{T}^n$ , satisfies

$$\mathcal{D}_{\tau}^{0} e_{i}^{n} - \eta D_{h}^{+} D_{h}^{+} D_{h}^{-} D_{h}^{-} D_{h}^{0} \overline{e}_{i}^{n} + D_{h}^{+} D_{h}^{-} D_{h}^{0} \overline{e}_{i}^{n} + \frac{1}{2} [\Psi_{\theta}(\mathbf{v}^{n}, \overline{\mathbf{v}}^{n})_{i} - \Psi_{\theta}(\mathbf{u}^{n}, \overline{\mathbf{u}}^{n})_{i}] \\ + D_{h}^{0} \overline{e}_{i}^{n} = \gamma D_{h}^{+} D_{h}^{-} \overline{e}_{i}^{n} + \mathcal{T}_{i}^{n}.$$
(4.2)

Using Taylor series expansion, one can show there exists  $c_2$  such that

$$|\mathcal{T}_i^n| \le c_2(\tau^2 + h^2).$$

**Theorem 4.1.** The solution  $\mathbf{u}^n$  of the scheme (3.3)-(3.5) converges in the sense

$$\|\mathbf{e}^n\|_{h,\infty} \le c_6(\tau^{3/2} + h^2)$$

 $\inf \left(\tau^{3/2} + h^2\right) \le \min \left\{\sqrt{2c_4}, \frac{1}{c_6}\right\} \ and \ \tau \le \min \left\{1, \frac{1}{2c_4}, \frac{1}{4c_5}\right\}, \\ where$ 

$$\begin{split} c_{3} &= \max_{x \in [a,b], t \in [0,T]} \{ |v(x,t)|, |v_{x}(x,t)| \}, \\ c_{4} &= \max\left\{ \left( \frac{c_{3}^{2}(1+3\theta)^{2} + c_{3}^{2}(1-\theta)^{2}}{32\gamma} + \frac{c_{3}^{2}(1-\theta)^{2}}{8\gamma} \right), \frac{2c_{1}}{\gamma} \right\}, \\ c_{5} &= \max\left\{ \frac{1}{4} \left( \frac{5c_{3}^{2}((1+3\theta)^{2} + (1-\theta)^{2})}{16\gamma} + \frac{5((3+\theta)^{2} + 5(1-\theta)^{2})}{16\gamma} + \frac{5c_{3}^{2}(1-\theta)^{2}}{4\gamma} \right), \\ \left( \frac{5c_{3}^{2}\theta^{2}}{\gamma} + \frac{5c_{3}^{2}(1-\theta)^{2}}{8\gamma} + \frac{5c_{3}^{2}(1-\theta)^{2}}{4\gamma} \right), \frac{5c_{2}}{\gamma} \right\}, \\ c_{6} &= \frac{\sqrt{L}}{2} \sqrt{4c_{4}e^{c_{5}T}}. \end{split}$$

*Proof.* Since  $\mathbf{e}^0 = \mathbf{0}$ , we have

$$\begin{split} \Psi_{\theta}(\mathbf{v}^{0},\mathbf{v}^{1/2}) - \Psi_{\theta}(\mathbf{u}^{0},\mathbf{u}^{1/2}) &= \Psi_{\theta}(\mathbf{v}^{0},\mathbf{e}^{1/2}) + \Psi_{\theta}(\mathbf{e}^{0},\mathbf{v}^{1/2}) - \Psi_{\theta}(\mathbf{e}^{0},\mathbf{e}^{1/2}) \\ &= \Psi_{\theta}(\mathbf{v}^{0},\mathbf{e}^{1/2}). \end{split}$$

Thus, the error equation (4.1) is reduced to

$$\frac{e_i^1}{\tau} - \frac{1}{2}\eta D_h^+ D_h^+ D_h^- D_h^- D_h^0 e_i^1 + \frac{1}{2}D_h^+ D_h^- D_h^0 e_i^1 + \frac{1}{4}\Psi_\theta(\mathbf{v}^0, \mathbf{e}^1)_i + \frac{1}{2}D_h^0 e_i^1 = \frac{\gamma}{2}D_h^+ D_h^- e_i^1 + \mathcal{T}_i^0.$$
(4.3)

Take the inner product of the system (4.3), where i = 1, ..., M - 1, with  $-D_h^+ D_h^- \mathbf{e}^1$  to get

$$\langle \frac{\mathbf{e}^{1}}{\tau}, -D_{h}^{+}D_{h}^{-}\mathbf{e}^{1}\rangle_{h} - \langle \frac{1}{2}\eta D_{h}^{+}D_{h}^{+}D_{h}^{-}D_{h}^{-}D_{h}^{0}\mathbf{e}^{1}, -D_{h}^{+}D_{h}^{-}\mathbf{e}^{1}\rangle_{h} + \langle \frac{1}{2}D_{h}^{+}D_{h}^{-}D_{h}^{0}\mathbf{e}^{1}, -D_{h}^{+}D_{h}^{-}\mathbf{e}^{1}\rangle_{h}$$

$$+ \langle \frac{1}{4}\Psi_{\theta}(\mathbf{v}^{0}, \mathbf{e}^{1}), -D_{h}^{+}D_{h}^{-}\mathbf{e}^{1}\rangle_{h} + \langle \frac{1}{2}D_{h}^{0}\mathbf{e}^{1}, -D_{h}^{+}D_{h}^{-}\mathbf{e}^{1}\rangle_{h}$$

$$= \langle \frac{\gamma}{2}D_{h}^{+}D_{h}^{-}\mathbf{e}^{1}, -D_{h}^{+}D_{h}^{-}\mathbf{e}^{1}\rangle_{h} + \langle \mathcal{T}^{0}, -D_{h}^{+}D_{h}^{-}\mathbf{e}^{1}\rangle_{h}.$$

$$(4.4)$$

Using Lemma 3.1 and Lemma 3.2, (4.4) is reduced to

$$\langle \frac{\mathbf{e}^{1}}{\tau}, -D_{h}^{+}D_{h}^{-}\mathbf{e}^{1}\rangle_{h} + \langle \frac{1}{4}\Psi_{\theta}(\mathbf{v}^{0}, \mathbf{e}^{1}), -D_{h}^{+}D_{h}^{-}\mathbf{e}^{1}\rangle_{h}$$
$$= \langle \frac{\gamma}{2}D_{h}^{+}D_{h}^{-}\mathbf{e}^{1}, -D_{h}^{+}D_{h}^{-}\mathbf{e}^{1}\rangle_{h} + \langle \mathcal{T}^{0}, -D_{h}^{+}D_{h}^{-}\mathbf{e}^{1}\rangle_{h}.$$

Rewrite

$$\langle \frac{\mathbf{e}^{1}}{\tau}, -D_{h}^{+}D_{h}^{-}\mathbf{e}^{1}\rangle_{h} - \langle \frac{\gamma}{2}D_{h}^{+}D_{h}^{-}\mathbf{e}^{1}, -D_{h}^{+}D_{h}^{-}\mathbf{e}^{1}\rangle_{h}$$

$$= -\langle \frac{1}{4}\Psi_{\theta}(\mathbf{v}^{0}, \mathbf{e}^{1}), -D_{h}^{+}D_{h}^{-}\mathbf{e}^{1}\rangle_{h} + \langle \mathcal{T}^{0}, -D_{h}^{+}D_{h}^{-}\mathbf{e}^{1}\rangle_{h}.$$

$$(4.5)$$

The left-hand side of (4.5) can be simplified into

$$\frac{1}{\tau} \|D_h^+ \mathbf{e}^1\|_h^2 + \frac{\gamma}{2} \|D_h^+ D_h^- \mathbf{e}^1\|_h^2.$$
(4.6)

For the first term on the right-hand side of (4.5), using Lemma 3.1 and Lemma 3.3, we arrive at

$$\begin{split} \langle \frac{1}{4} \Psi_{\theta}(\mathbf{v}^{0}, \mathbf{e}^{1}), D_{h}^{+} D_{h}^{-} \mathbf{e}^{1} \rangle_{h} &= \frac{\theta}{2} h \sum_{i=1}^{M-1} v_{i}^{0} D_{h}^{0} e_{i}^{1} (D_{h}^{+} D_{h}^{-} e_{i}^{1}) \\ &+ \frac{1-\theta}{4} h \sum_{i=1}^{M-1} \left( \frac{1}{2} v_{i+1}^{0} D_{h}^{+} e_{i}^{1} + (D_{h}^{0} v_{i}^{0}) e_{i}^{1} + \frac{1}{2} v_{i-1}^{0} D_{h}^{+} e_{i-1}^{1} \right) (D_{h}^{+} D_{h}^{-} e_{i}^{1}) \\ &\leq \frac{(1+3\theta)}{8} c_{3} \| D_{h}^{+} \mathbf{e}^{1} \|_{h} \| D_{h}^{+} D_{h}^{-} \mathbf{e}^{1} \|_{h} + \frac{(1-\theta)}{4} c_{3} \| \mathbf{e}^{1} \|_{h} \| D_{h}^{+} D_{h}^{-} \mathbf{e}^{1} \|_{h} \\ &+ \frac{(1-\theta)}{8} c_{3} \| D_{h}^{+} \mathbf{e}^{1} \|_{h} \| D_{h}^{+} D_{h}^{-} \mathbf{e}^{1} \|_{h} \\ &\leq \frac{c_{3}^{2} (3\theta+1)^{2} + c_{3}^{2} (1-\theta)^{2}}{32\gamma} \| D_{h}^{+} \mathbf{e}^{1} \|_{h}^{2} + \frac{3\gamma}{8} \| D_{h}^{+} D_{h}^{-} \mathbf{e}^{1} \|_{h}^{2} \\ &+ \frac{c_{3}^{2} (1-\theta)^{2}}{8\gamma} \| \mathbf{e}^{1} \|_{h}^{2}. \end{split}$$

As for the last term in (4.5), using Cauchy–Schwarz inequality, we arrive at

$$\langle \mathcal{T}^{0}, -D_{h}^{+}D_{h}^{-}\mathbf{e}^{1}\rangle_{h} \leq \|\mathcal{T}^{0}\|_{h}\|D_{h}^{+}D_{h}^{-}\mathbf{e}^{1}\|_{h}$$

$$\leq \frac{2}{\gamma}\|\mathcal{T}^{0}\|_{h}^{2} + \frac{\gamma}{8}\|D_{h}^{+}D_{h}^{-}\mathbf{e}^{1}\|_{h}^{2}.$$

$$(4.8)$$

Substituting (4.6), (4.7), and (4.8) into (4.5), we obtain

$$\frac{1}{\tau} \|D_h^+ \mathbf{e}^1\|_h^2 \le c_4 \|D_h^+ \mathbf{e}^1\|_h^2 + c_4 (\tau + h^2)^2$$
  
(1 - c\_4 \tau) \|D\_h^+ \mathbf{e}^1\|\_h^2 \le c\_4 \tau (\tau + h^2)^2. (4.9)

For  $c_4 \tau \leq \frac{1}{2}$ , we have

$$\|D_h^+ \mathbf{e}^1\|_h^2 \le 2c_4 \tau (\tau + h^2)^2.$$
(4.10)

From this, we get

$$\|D_h^+ \mathbf{e}^1\|_h \le \sqrt{2c_4} (\tau^{3/2} + h^2) \tag{4.11}$$

if  $\tau < 1$ . From the hypothesis of the theorem, we have

$$\|D_h^+ \mathbf{e}^1\|_h \le \frac{2}{\sqrt{L}}.$$

This shows that

$$\|\mathbf{e}^{\mathrm{I}}\|_{h,\infty} \leq 1.$$

For the time step  $t^n, n > 0$ , we use induction on n and proceed in a similar manner. Assume

$$\|D_h^+ \mathbf{e}^k\|_h \le \frac{2}{\sqrt{L}}.\tag{4.12}$$

That is,  $\|\mathbf{e}^k\|_{h,\infty} \leq 1$ , for k = 0, 1, ..., n. We shall show that (4.12) holds for k = n + 1. First, we take inner product of (4.2), where i = 1, ..., M - 1, with  $-2D_h^+ D_h^- \overline{\mathbf{e}}^n$  to get

$$\langle \mathcal{D}_{\tau}^{0} \mathbf{e}^{n}, -2D_{h}^{+} D_{h}^{-} \overline{\mathbf{e}}^{n} \rangle_{h} - \langle \eta D_{h}^{+} D_{h}^{+} D_{h}^{-} D_{h}^{0} \overline{\mathbf{e}}^{n}, -2D_{h}^{+} D_{h}^{-} \overline{\mathbf{e}}^{n} \rangle_{h}$$

$$+ \langle D_{h}^{+} D_{h}^{-} D_{h}^{0} \overline{\mathbf{e}}^{n}, -2D_{h}^{+} D_{h}^{-} \overline{\mathbf{e}}^{n} \rangle_{h} + \langle \frac{1}{2} [\Psi_{\theta} (\mathbf{v}^{n}, \overline{\mathbf{v}}^{n}) - \Psi_{\theta} (\mathbf{u}^{n}, \overline{\mathbf{u}}^{n})], -2D_{h}^{+} D_{h}^{-} \overline{\mathbf{e}}^{n} \rangle_{h}$$

$$+ \langle D_{h}^{0} \overline{\mathbf{e}}^{n}, -2D_{h}^{+} D_{h}^{-} \overline{\mathbf{e}}^{n} \rangle_{h} = \langle \gamma D_{h}^{+} D_{h}^{-} \overline{\mathbf{e}}^{n}, -2D_{h}^{+} D_{h}^{-} \overline{\mathbf{e}}^{n} \rangle_{h} + \langle \mathcal{T}^{n}, -2D_{h}^{+} D_{h}^{-} \overline{\mathbf{e}}^{n} \rangle_{h}.$$

$$(4.13)$$

Using Lemma 3.2, we get

$$\langle \mathcal{D}_{\tau}^{0} \mathbf{e}^{n}, -2D_{h}^{+} D_{h}^{-} \overline{\mathbf{e}}^{n} \rangle_{h} - \langle \gamma D_{h}^{+} D_{h}^{-} \overline{\mathbf{e}}^{n}, -2D_{h}^{+} D_{h}^{-} \overline{\mathbf{e}}^{n} \rangle_{h}$$

$$= -\langle \frac{1}{2} [\Psi_{\theta}(\mathbf{v}^{n}, \overline{\mathbf{v}}^{n}) - \Psi_{\theta}(\mathbf{u}^{n}, \overline{\mathbf{u}}^{n})], -2D_{h}^{+} D_{h}^{-} \overline{\mathbf{e}}^{n} \rangle_{h} + \langle \mathcal{T}^{n}, -2D_{h}^{+} D_{h}^{-} \overline{\mathbf{e}}^{n} \rangle_{h}.$$

$$(4.14)$$

The left-hand side of (4.14) can be simplified into

$$\frac{1}{2\tau} \Big( \|D_h^+ \mathbf{e}^{n+1}\|_h^2 - \|D_h^+ \mathbf{e}^{n-1}\|_h^2 \Big) + 2\gamma \|D_h^+ D_h^- \overline{\mathbf{e}}^n\|_h^2.$$
(4.15)

As for the first term on the right-hand side of (4.14), note that

$$\Psi_{\theta}(\mathbf{v}^{n}, \overline{\mathbf{v}}^{n}) - \Psi_{\theta}(\mathbf{u}^{n}, \overline{\mathbf{u}}^{n}) = \Psi_{\theta}(\mathbf{v}^{n}, \overline{\mathbf{e}}^{n}) + \Psi_{\theta}(\mathbf{e}^{n}, \overline{\mathbf{v}}^{n}) - \Psi_{\theta}(\mathbf{e}^{n}, \overline{\mathbf{e}}^{n})$$

Using (3.16), Lemma 3.1 and Lemma 3.3, we have

$$\begin{split} \langle \Psi_{\theta}(\mathbf{v}^{n}, \mathbf{\bar{e}}^{n}), D_{h}^{+} D_{h}^{-} \mathbf{\bar{e}}^{n} \rangle_{h} &= 2\theta h \sum_{i=1}^{M-1} v_{i}^{n} D_{h}^{0} \overline{e}_{i}^{n} (D_{h}^{+} D_{h}^{-} \overline{e}_{i}^{n}) \\ &+ (1-\theta) h \sum_{i=1}^{M-1} \left( \frac{1}{2} v_{i+1}^{n} D_{h}^{+} \overline{e}_{i}^{n} + (D_{h}^{0} v_{i}^{n}) \overline{e}_{i}^{n} + \frac{1}{2} v_{i-1}^{n} D_{h}^{+} \overline{e}_{i-1}^{n} \right) (D_{h}^{+} D_{h}^{-} \overline{e}_{i}^{n}) \\ &\leq \frac{(3\theta+1)}{2} c_{3} \| D_{h}^{+} \overline{e}^{n} \|_{h} \| D_{h}^{+} D_{h}^{-} \overline{e}^{n} \|_{h} + (1-\theta) c_{3} \| \overline{e}^{n} \|_{h} \| D_{h}^{+} D_{h}^{-} \overline{e}^{n} \|_{h} \\ &+ \frac{(1-\theta)}{2} c_{3} \| D_{h}^{+} \overline{e}^{n} \|_{h} \| D_{h}^{+} D_{h}^{-} \overline{e}^{n} \|_{h} \\ &\leq \frac{5c_{3}^{2} ((3\theta+1)^{2} + (1-\theta)^{2})}{16\gamma} \| D_{h}^{+} \overline{e}^{n} \|_{h}^{2} + \frac{5c_{3}^{2} (1-\theta)^{2}}{4\gamma} \| \overline{e}^{n} \|_{h}^{2} + \frac{3\gamma}{5} \| D_{h}^{+} D_{h}^{-} \overline{e}^{n} \|_{h}^{2}. \end{split}$$

$$\tag{4.16}$$

Similarly, we have

$$\langle \Psi_{\theta}(\mathbf{e}^{n}, \overline{\mathbf{v}}^{n}), D_{h}^{+} D_{h}^{-} \overline{\mathbf{e}}^{n} \rangle_{h} \leq 2\theta c_{3} \|\mathbf{e}^{n}\|_{h} \|D_{h}^{+} D_{h}^{-} \overline{\mathbf{e}}^{n}\|_{h} + \frac{(1-\theta)}{2} c_{3} \|\mathbf{e}^{n}\|_{h} \|D_{h}^{+} D_{h}^{-} \overline{\mathbf{e}}^{n}\|_{h}$$

$$+ (1-\theta) c_{3} \|D_{h}^{+} \mathbf{e}^{n}\|_{h} \|D_{h}^{+} D_{h}^{-} \overline{\mathbf{e}}^{n}\|_{h}$$

$$+ \frac{(1-\theta)}{2} c_{3} \|\mathbf{e}^{n}\|_{h} \|D_{h}^{+} D_{h}^{-} \overline{\mathbf{e}}^{n}\|_{h}$$

$$\leq \left(\frac{5c_{3}^{2}\theta^{2}}{\gamma} + \frac{5c_{3}^{2}(1-\theta)^{2}}{8\gamma}\right) \|\mathbf{e}^{n}\|_{h}^{2} + \frac{5c_{3}^{2}(1-\theta)^{2}}{4\gamma} \|D_{h}^{+} \mathbf{e}^{n}\|_{h}^{2}$$

$$+ \frac{4\gamma}{5} \|D_{h}^{+} D_{h}^{-} \overline{\mathbf{e}}^{n}\|_{h}^{2}.$$

$$(4.17)$$

We find that

$$- \langle \Psi_{\theta}(\mathbf{e}^{n}, \overline{\mathbf{e}}^{n}), D_{h}^{+} D_{h}^{-} \overline{\mathbf{e}}^{n} \rangle_{h} = -2\theta h \sum_{i=1}^{M-1} e_{i}^{n} D_{h}^{0} \overline{e}_{i}^{n} (D_{h}^{+} D_{h}^{-} \overline{e}_{i}^{n}) - (1-\theta) h \sum_{i=1}^{M-1} \left( \frac{1}{2} e_{i+1}^{n} D_{h}^{+} \overline{e}_{i}^{n} + (D_{h}^{0} e_{i}^{n}) \overline{e}_{i}^{n} + \frac{1}{2} e_{i-1}^{n} D_{h}^{+} \overline{e}_{i-1}^{n} \right) (D_{h}^{+} D_{h}^{-} \overline{e}_{i}^{n}) \leq \frac{(3+\theta)}{2} \|D_{h}^{+} \overline{\mathbf{e}}^{n}\|_{h} \|D_{h}^{+} D_{h}^{-} \overline{\mathbf{e}}^{n}\|_{h} + \frac{(1-\theta)}{2} \|D_{h}^{+} \overline{\mathbf{e}}^{n}\|_{h} \|D_{h}^{+} D_{h}^{-} \overline{\mathbf{e}}^{n}\|_{h} \leq \frac{5(\theta+3)^{2} + 5(1-\theta)^{2}}{16\gamma} \|D_{h}^{+} \overline{\mathbf{e}}^{n}\|_{h}^{2} + \frac{2\gamma}{5} \|D_{h}^{+} D_{h}^{-} \overline{\mathbf{e}}^{n}\|_{h}^{2}.$$
(4.18)

As for the last term in (4.14), we have

$$-2\langle \mathcal{T}^{n}, D_{h}^{+} D_{h}^{-} \overline{\mathbf{e}}^{n} \rangle_{h} \leq 2 \| \mathcal{T}^{n} \|_{h} \| D_{h}^{+} D_{h}^{-} \overline{\mathbf{e}}^{n} \|_{h} \\ \leq \frac{5}{\gamma} \| \mathcal{T}^{n} \|_{h}^{2} + \frac{\gamma}{5} \| D_{h}^{+} D_{h}^{-} \overline{\mathbf{e}}^{n} \|_{h}^{2}.$$
(4.19)

Substituting (4.15)-(4.19) into (4.14), we obtain

$$\|D_{h}^{+}\mathbf{e}^{n+1}\|_{h}^{2} - \|D_{h}^{+}\mathbf{e}^{n-1}\|_{h}^{2} \leq 2c_{5}\tau \left(\|D_{h}^{+}\mathbf{e}^{n+1}\|_{h}^{2} + \|D_{h}^{+}\mathbf{e}^{n-1}\|_{h}^{2} + \|D_{h}^{+}\mathbf{e}^{n}\|_{h}^{2}\right) + 2c_{5}\tau(\tau^{2}+h^{2})^{2}.$$
(4.20)

Define

$$S^{n} = \|D_{h}^{+}\mathbf{e}^{n}\|_{h}^{2} + \|D_{h}^{+}\mathbf{e}^{n+1}\|_{h}^{2}$$

One can show that (4.20) leads to

$$S^{n} - S^{n-1} \le 2c_{5}\tau(S^{n} + S^{n-1}) + 2c_{5}\tau(\tau^{2} + h^{2})^{2}$$
$$(1 - 2c_{5}\tau)S^{n} \le (1 + c_{5}\tau)S^{n-1} + 2c_{5}\tau(\tau^{2} + h^{2})^{2}.$$

For  $2c_5\tau \leq \frac{1}{2}$ , we arrive at

$$S^{n} \leq 2\left(1 + c_{5}\tau\right)S^{n-1} + 4c_{5}\tau(\tau^{2} + h^{2})^{2}.$$
(4.21)

A use of discrete Grönwall inequality shows

$$S^{n} \leq 2e^{c_{5}n\tau} \left( S^{0} + 4c_{5}n\tau(\tau^{2} + h^{2})^{2} \right)$$
  
$$\leq 2e^{c_{5}T} \left( S^{0} + 4c_{5}T(\tau^{2} + h^{2})^{2} \right).$$
(4.22)

Take the value of  $S^0$  from (4.11), we get

$$S^{n} \leq 2e^{c_{5}T} \left( 2c_{4}(\tau^{3/2} + h^{2})^{2} + 4c_{5}T(\tau^{2} + h^{2})^{2} \right)$$
  
$$\leq \frac{c_{6}^{2}}{\left(\frac{\sqrt{L}}{2}\right)^{2}} (\tau^{3/2} + h^{2})^{2}.$$
(4.23)

We have from (4.23) that

$$\|D_h^+ \mathbf{e}^{n+1}\|_h \le \frac{2c_6}{\sqrt{L}} (\tau^{3/2} + h^2).$$
(4.24)

Using Lemma 3.4, we get  $\|\mathbf{e}^{n+1}\|_{h,\infty} \leq c_6(\tau^{3/2} + h^2)$  as needed.

# 5. Numerical Results

In this section, we test the proposed scheme on various examples. We begin by extending the scheme to a more general setting.

## 5.1. AN EXTENSION TO THE NON-HOMOGENEOUS CASES

For the non-homogeneous KdV-Kawahara equation

$$u_t - \eta u_{xxxxx} + u_{xxx} + u_x + u_x - \gamma u_{xx} = f(x, t), \quad x \in [a, b], \quad t \in [0, T], \quad (5.1)$$
  
with conditions (1.5) and (1.6), we use the following difference scheme

$$\mathcal{D}_{\tau}^{+} u_{i}^{0} - \eta D_{h}^{+} D_{h}^{+} D_{h}^{-} D_{h}^{-} D_{h}^{0} u_{i}^{1/2} + D_{h}^{+} D_{h}^{-} D_{h}^{0} u_{i}^{1/2} + \frac{1}{2} \Psi_{\theta} (\mathbf{u}^{0}, \mathbf{u}^{1/2})_{i} + D_{h}^{0} u_{i}^{1/2} - \gamma D_{h}^{+} D_{h}^{-} u_{i}^{1/2} = f(x_{i}, t^{1/2}),$$
(5.2)

for  $i = 1 \dots, M - 1$  and

$$\mathcal{D}_{\tau}^{0} u_{i}^{n} - \eta D_{h}^{+} D_{h}^{+} D_{h}^{-} D_{h}^{-} D_{h}^{0} \overline{u}_{i}^{n} + D_{h}^{+} D_{h}^{-} D_{h}^{0} \overline{u}_{i}^{n} + \frac{1}{2} \Psi_{\theta} (\mathbf{u}^{n}, \overline{\mathbf{u}}^{n})_{i} + D_{h}^{0} \overline{u}_{i}^{n} - \gamma D_{h}^{+} D_{h}^{-} \overline{u}_{i}^{n} = f(x_{i}, t^{n}),$$
(5.3)

for i = 1..., M-1, for n = 1..., N-1. We can prove that difference scheme (5.2)-(5.3) has second-order of accuracy in space with respect to the uniform norm using the idea similar to Theorem 4.1.

### 5.2. Numerical Tests

Some numerical experiments were undergone to verify the correctness of our theoretical analysis. We chose three test problems, both viscous ( $\gamma \neq 0$ ) and inviscous ( $\gamma = 0$ ), to measure the performance on the proposed scheme.

In Theorem 3.7, the optimal value of  $\theta$  is 1/3. Therefor, the simulations using  $\theta = 1/3$  was conducted against other values of  $\theta$  to compare their performances. The errors were measured by the discrete Euclidean norm  $\|\cdot\|_h$  and the discrete uniform norm  $\|\cdot\|_{h,\infty}$  defined in (3.1) and (3.2), respectively.

Let r be the order of accuracy with respect to the norm  $\|\cdot\|$ . If the exact value u is **known**, order of convergence is computed using the formula

$$r = \log_2\left(\frac{\|\mathbf{e}_h\|}{\|\mathbf{e}_{h/2}\|}\right),\,$$

where  $\mathbf{e}_h$  and  $\mathbf{e}_{h/2}$  are the errors resulting from the divisions of the domain into subranges of sizes h and h/2 respectively. When u is not known, order is computed using the formula

$$r = \log_2 \left( \frac{\|\mathbf{u}_h - \mathbf{u}_{h/2}\|}{\|\mathbf{u}_{h/2} - \mathbf{u}_{h/4}\|} \right),$$

where  $\mathbf{u}_h, \mathbf{u}_{h/2}$  and  $\mathbf{u}_{h/4}$  are the estimated solutions resulting from the divisions of the domain into subranges of size h, h/2 and h/4 respectively.

#### Example 1. Accuracy Test for the Homogeneous Viscous case.

We used the homogeneous example with no exact solution. The initial data is given by

$$u(x,0) = \frac{105}{169}\operatorname{sech}^4(\frac{x}{2\sqrt{13}}).$$

M	$\theta = 0$		$\theta = 1/3$		$\theta = 2/3$		$\theta = 1$	
	$  u_h - u_{h/2}  _h$	order						
80	1.7203e-03	1.98	1.6846e-03	1.97	1.7097e-03	1.99	1.7354e-03	1.99
160	4.3573e-04	2.00	4.3075e-04	1.99	4.3063e-04	1.99	4.3597e-04	2.00
320	1.0904e-04	2.00	1.0806e-04	2.00	1.0808e-04	2.00	1.0910e-04	2.00
640	2.7265e-05		2.7039e-05		2.7054 e-05		2.7280e-05	
1280								

The simulation was conducted on the domain [-40, 40] with parameters T = 1,  $\eta = 1$ ,  $\gamma = 1$  and  $\tau = h$ . Orders showing optimal convergence rates are given in Table 1.

TABLE 1. Orders showing optimal convergence rates for the viscous homogeneous problem (Example 1) with  $\theta = 0, 1/3, 2/3, 1$ .

## Example 2. Accuracy Test for the Non-Homogeneous Viscous case.

We used the non-homogeneous example with exact solution

$$u(x,t) = e^{-(x-t)^2}.$$

The simulation was conducted on the domain [-20, 40] with parameters T = 1,  $\eta = 1$ ,  $\gamma = 1$  and  $\tau = h$ . The errors and orders of accuracy are given in Tables 2 and 3. The comparison between exact and approximate solutions is represented in Figure 1 for T = 0, 5, 15, 20.

		= 0	$\theta = 1/3$					
M	$\ \mathbf{u}-\mathbf{u}_h\ _h$		$\ \mathbf{u}-\mathbf{u}_h\ _{h,\infty}$		$\ \mathbf{u}-\mathbf{u}_h\ _h$		$\ \mathbf{u}-\mathbf{u}_h\ _{h,\infty}$	
	error	order	error	order	error	order	error	order
160	8.8058e-02		9.9948e-02		8.7100e-02		9.8985e-02	
320	1.9590e-02	2.17	2.1627e-02	2.21	1.9405e-02	2.17	2.1447e-02	2.21
640	4.7898e-03	2.03	5.2382e-03	2.05	4.7462e-03	2.03	5.1961e-03	2.05
1280	1.1911e-03	2.01	1.3028e-03	2.01	1.1803e-03	2.01	1.2916e-03	2.01
2560	2.9738e-04	2.00	3.2533e-04	2.00	2.9471e-04	2.00	3.2265e-04	2.00

TABLE 2. Errors and orders showing optimal convergence rates for the viscous non-homogeneous problem (Example 2) with  $\theta = 0, 1/3$ .

		2/3	$\theta = 1$					
M	$\ \mathbf{u}-\mathbf{u}_h\ _h$		$\ \mathbf{u}-\mathbf{u}_h\ _{h,\infty}$		$\ \mathbf{u}-\mathbf{u}_h\ _h$		$\ \mathbf{u}-\mathbf{u}_h\ _{h,\infty}$	
	error	order	error	order	error	order	error	order
160	8.6311e-02		9.8029e-02		8.5692e-02		9.7082e-02	
320	1.9249e-02	2.16	2.1268e-02	2.20	1.9124e-02	2.16	2.1089e-02	2.20
640	4.7095e-03	2.03	5.1539e-03	2.04	4.6798e-03	2.03	5.1119e-03	2.04
1280	1.1713e-03	2.01	1.2804e-03	2.01	1.1639e-03	2.01	1.2695e-03	2.01
2560	2.9245e-04	2.00	3.1996e-04	2.00	2.9062e-04	2.00	3.1728e-04	2.00

TABLE 3. Errors and orders showing optimal convergence rates for the viscous non-homogeneous problem (Example 2) with  $\theta = 2/3, 1$ .



FIGURE 1. Comparison between the exact and approximate solutions for the viscous non-homogeneous problem (Example 2) at T = 0, 5, 15, 20.

### Example 3. The Homogeneous Inviscous case.

For the case where  $\gamma = 0$ , we used the homogeneous example from [28]. The exact solution is given by

$$u(x,t) = \frac{105}{169}\operatorname{sech}^4\left(\frac{1}{2\sqrt{13}}(x - \frac{205t}{169} - x_0)\right)$$

where  $x_0$  is an arbitrary constant.

## Accuracy Test.

To test the convergence, the simulation was conducted on the domain [-80, 80] with parameters T = 1,  $x_0 = 2$ ,  $\eta = 1$  and  $\tau = h$ . The errors and orders of accuracy are given in Tables 4 and 5. The comparison between exact and approximate solutions is represented in Figure 2 for T = 0, 5, 15, 20. The performances for each value of  $\theta$  are shown in Figure 3 where we see that all the errors are vanishing for any value of  $\theta$ . However, we will show later that the energy is stable only when  $\theta = 1/3$ .

Invariant-Preserving 3-level linear FDM for KDV-Kawahara

		= 0	$\theta = 1/3$					
M	$\ u-u_h\ _h$		$\ u-u_h\ _{h,\infty}$		$\ u-u_h\ _h$		$\ u-u_h\ _{h,\infty}$	
	error	order	error	order	error	order	error	order
80	1.7942e-02		1.1498e-02		1.7212e-02		1.0702e-02	
160	4.4815e-03	2.00	2.8070e-03	2.03	4.3222e-03	1.99	2.7338e-03	1.97
320	1.1199e-03	2.00	7.0555e-04	1.99	1.0821e-03	2.00	6.8581e-04	2.00
640	2.7993e-04	2.00	1.7657e-04	2.00	2.7062e-04	2.00	1.7247e-04	1.99

TABLE 4. Errors and orders showing optimal convergence rates for the inviscous homogeneous problem (Example 3) with  $\theta = 0, 1/3$ .

		$\theta =$	2/3		$\theta = 1$				
M	$I \qquad \ u-u_h\ _h$		$\ u-u_h\ _{h,\infty}$		$\ u-u_h\ _h$		$\ u-u_h\ _{h,\infty}$		
	error	order	error	order	error	order	error	order	
80	1.6648e-02		1.0303e-02		1.6266e-02		1.0054e-02		
160	4.2149e-03	1.98	2.6610e-03	1.95	4.1635e-03	1.97	2.6287e-03	1.94	
320	1.0579e-03	1.99	6.8078e-04	1.97	1.0480e-03	1.99	6.8277e-04	1.94	
640	2.6472e-04	2.00	1.7049e-04	2.00	2.6246e-04	2.00	1.7087e-04	2.00	

TABLE 5. Errors and orders showing optimal convergence rates for the inviscous homogeneous problem (Example 3) with  $\theta = 2/3, 1$ .



FIGURE 2. Comparison between the exact and approximate solutions for the inviscous homogeneous problem (Example 3) at T = 0, 5, 15, 20.



FIGURE 3. Comparison of the uniform errors at t = 1 when using different values of  $\theta$  for the inviscous homogeneous problem (Example 3).

### **Invariant-Preserving Test**

To see how well the scheme performs on a long-time simulation, we compare the performances for each value of  $\theta$  in Figures 4 and 5. We see that the quantity  $||u^n||_h$  is stable only when  $\theta = 1/3$ .

We also compare the percentage of the quantity  $||u^n||_h$  with respect to its original value at the initial time. The simulation was done using M = 1000 on the domain [-30, 150]with  $\tau = 0.046$ , as shown in Table 6. We see that the quantity  $||\mathbf{u}^n||_h$  is stable only when  $\theta = 1/3$ , but when we used  $\theta = 0, 2/3, 1$ , the numerical solution becomes unstable as time increases. This shows that the invariant-preserving method performs better in the long run.



FIGURE 4. Values of  $\|\mathbf{u}^n\|_h$  at t = 0, 1, ..., 100 when using the scheme with different choices of  $\theta$  with M = 160 for the inviscous homogeneous problem Example 3.



FIGURE 5. Values of  $\|\mathbf{u}^n\|_h$  at  $t = 80, \ldots, 100$  when using the scheme with different choices of  $\theta$  with M = 160 for the inviscous homogeneous problem Example 3.

Thai J. Math. Special Issue AMM 2022 / K. Phollama and N. Ploymaklam

T	$\theta = 0$		$\theta = 1/3$		$\theta = 2/3$		$\theta = 1$	
	$\ \mathbf{u}^n\ _h$	$\frac{\ \mathbf{u}^n\ _h}{\ \mathbf{u}^0\ _h}$	$\ \mathbf{u}^n\ _h$	$\frac{\ \mathbf{u}^n\ _h}{\ \mathbf{u}^0\ _h}$	$\ \mathbf{u}^n\ _h$	$\frac{\ \mathbf{u}^n\ _h}{\ \mathbf{u}^0\ _h}$	$\ \mathbf{u}^n\ _h$	$\frac{\ \mathbf{u}^n\ _h}{\ \mathbf{u}^0\ _h}$
0	3.7602		3.7602		3.7602		3.7602	
15	3.7602	100.00	3.7602	100.00	3.7602	100.00	3.7602	100.00
30	3.7602	100.00	3.7602	100.00	3.7602	100.00	3.7602	100.00
45	3.7602	100.00	3.7602	100.00	3.7602	100.00	3.7603	100.00
60	3.7602	100.00	3.7602	100.00	3.7602	100.00	3.7612	100.02
75	3.7602	100.00	3.7602	100.00	3.7603	100.00	3.7671	100.16
90	3.7602	100.00	3.7602	100.00	3.7605	100.01	3.8022	100.93
105	3.7602	100.00	3.7602	100.00	3.7610	100.02	4.0015	105.24
120	3.7600	99.99	3.7602	100.00	3.7628	100.05	5.0621	126.51

TABLE 6. Comparison of the performance of the invariant-preserving scheme ( $\theta = 1/3$ ) and other schemes ( $\theta = 0, 2/3, 1$ ) for Example 3.

## 6. DISCUSSION

Results from numerical examples verified that the approximated solutions are consistent with the result of the previously proven theorems; that is, the numerical solutions converge to the exact solutions with second order of accuracy with respect to the spatial variable. The convergence can be inferred from the error plot in Figure 3 while the rate of convergence can be inferred from the numerical evidence in Tables 1-5. Note that second-order convergence occurs at any value of  $\theta$ . However, Figures 4 and 5 show that the invariant is preserved only when  $\theta = 1/3$ . This behavior agrees with the results we proved in Section 4. The comparisons in Example 3 (Invariant-Preserving Test) confirmed that the invariant-preserving scheme performs better in the long run. This hints that the invariant-preserving property, if any, should be taken into account when one wants to design a numerical method.

## 7. CONCLUSION

In this work, we proposed a family of three-level linearized finite difference  $\theta$ -schemes to solve the Korteweg-de Vries – Kawahara equation with added viscosity term. When  $\theta = 1/3$ , we showed that the resulting scheme has a discrete invariant-preserving property. We also proved that the numerical solution converges uniformly and has second order of accuracy in space. Finally, the proposed numerical method was verified using various numerical examples. The numerical results are consistent with the theoretical results.

#### ACKNOWLEDGEMENTS

We would like to thank the referees and editor for their helpful suggestions which significantly improve the paper's quality. This work was supported by Chiang Mai University.

#### References

 M. Ablowitz and P. Clarkson, "Solitons, nonlinear evolution equations and inverse scattering," *Cambridge Univ. Press, Cambridge*, vol. 3, pp. 2301–2305, 1991.

- [2] R. Mohanty and V. Gopal, "High accuracy cubic spline finite difference approximation for the solution of one-space dimensional non-linear wave equations," *Applied Mathematics and Computation*, vol. 218, no. 8, pp. 4234–4244, 2011.
- [3] O. Nikan, A. Golbabai, and T. Nikazad, "Solitary wave solution of the nonlinear KdV-Benjamin-Bona-Mahony-Burgers model via two meshless methods," *The European Physical Journal Plus*, vol. 134, no. 7, pp. 1–14, 2019.
- [4] K. Raslan and T. S. EL-Danaf, "Solitary waves solutions of the MRLW equation using quintic B-splines," *Journal of King Saud University-Science*, vol. 22, no. 3, pp. 161–166, 2010.
- [5] S. Sharifi and J. Rashidinia, "Collocation method for convection-reaction-diffusion equation," *Journal of King Saud University-Science*, vol. 31, no. 4, pp. 1115–1121, 2019.
- [6] A. Korkmaz and I. Dağ, "Crank-Nicolson-differential quadrature algorithms for the Kawahara equation," Chaos, Solitons & Fractals, vol. 42, no. 1, pp. 65–73, 2009.
- [7] N. Sirendaoreji, "New exact travelling wave solutions for the Kawahara and modified Kawahara equations," *Chaos Solitons & Fractals*, vol. 19, no. 1, pp. 147–150, 2004.
- [8] E. D. Jager, "On the origin of the Korteweg-de Vries equation," arXiv preprint math/0602661, 2006.
- D. Kaya, "An explicit and numerical solutions of some fifth-order KdV equation by decomposition method," *Applied Mathematics and Computation*, vol. 144, no. 2-3, pp. 353–363, 2003.
- [10] J. C. Ceballos, M. Sepulveda, and O. P. V. Villagran, "The Korteweg–de Vries– Kawahara equation in a bounded domain and some numerical results," *Applied Mathematics and Computation*, vol. 190, no. 1, pp. 912–936, 2007.
- [11] F. Natali, "A note on the stability for Kawahara-KdV type equations," Applied mathematics letters, vol. 23, no. 5, pp. 591–596, 2010.
- [12] J. P. Albert, "Positivity properties and stability of solitary-wave solutions of model equations for long waves," *Communications in partial differential equations*, vol. 17, no. 1-2, pp. 1–22, 1992.
- [13] A. H. Badali, M. S. Hashemi, and M. Ghahremani, "Lie symmetry analysis for Kawahara-KdV equations," *Computational Methods for Differential Equations*, vol. 1, no. 2, pp. 135–145, 2013.
- [14] G. M. Coclite and L. d. Ruvo, "Well-posedness of the classical solutions for a Kawahara–Korteweg–de Vries-type equation," *Journal of Evolution Equations*, vol. 21, no. 1, pp. 625–651, 2021.
- [15] P. Y. Kuo and J. Sanz-Serna, "Convergence of methods for the numerical solution of the Korteweg-de Vries equation.," *IMA Journal of Numerical Analysis*, vol. 1, no. 2, pp. 215–221, 1981.
- [16] L. Zhang, "A finite difference scheme for generalized regularized long-wave equation," *Applied Mathematics and Computation*, vol. 168, no. 2, pp. 962–972, 2005.
- [17] J. M. Zuo, Y. M. Zhang, T. D. Zhang, and F. Chang, "A new conservative difference scheme for the general Rosenau-RLW equation," *Boundary Value Problems*, vol. 2010, pp. 1–13, 2010.
- [18] X. Pan and L. Zhang, "On the convergence of a conservative numerical scheme for the usual Rosenau-RLW equation," *Applied Mathematical Modelling*, vol. 36, no. 8, pp. 3371–3378, 2012.

- [19] X. Wang and Z. Z. Sun, "A second order convergent difference scheme for the initialboundary value problem of Korteweg-de Vires equation," *Numerical Methods for Partial Differential Equations*, vol. 37, no. 5, pp. 2873–2894, 2021.
- [20] Q. Zhang, Y. Qin, X. Wang, and Z. Z. Sun, "The study of exact and numerical solutions of the generalized viscous Burgers' equation," *Applied Mathematics Letters*, vol. 112, p. 106719, 2021.
- [21] X. Pan and L. Zhang, "Numerical simulation for general Rosenau-RLW equation: an average linearized conservative scheme," *Mathematical Problems in Engineering*, vol. 2012, 2012.
- [22] B. Wongsaijai and K. Poochinapan, "A three-level average implicit finite difference scheme to solve equation obtained by coupling the Rosenau-KdV equation and the Rosenau-RLW equation," *Applied Mathematics and Computation*, vol. 245, pp. 289– 304, 2014.
- [23] Q. Zhang, X. Wang, and Z. Z. Sun, "The pointwise estimates of a conservative difference scheme for Burgers' equation," *Numerical Methods for Partial Differential Equations*, vol. 36, no. 6, pp. 1611–1628, 2020.
- [24] C. Darayon, M. Khebchareon, and N. Ploymaklam, "An invariant-preserving scheme for the viscous Burgers-poisson system," *Computation*, vol. 9, no. 11, p. 115, 2021.
- [25] Z. Z. Sun, "Numerical methods of partial differential equations 2nd version," Chinese, Science Press, Beijing, 2012.
- [26] A. Samarskii and V. Andreev, "Difference methods for elliptic equations(Russian book)," Moscow, Izdatel'stvo Nauka, 1976. 352, 1976.
- [27] Y. Zhou, Applications of discrete functional analysis to the finite difference method. Pergamon Press, 1991.
- [28] E. Parkes and B. Duffy, "An automated tanh-function method for finding solitary wave solutions to non-linear evolution equations," *Computer physics communications*, vol. 98, no. 3, pp. 288–300, 1996.