# Positive Solution of Boundary Value Problem Involving Fractional Pantograph Differential Equation 

Piyachat Borisut ${ }^{1}$ and Chaiwat Auipa-arch ${ }^{2, *}$<br>${ }^{1}$ Faculty of Liberal Arts, Rajamangala University of Technology Rattanakosin, Samphanthawong, Bangkok 10100, Thailand<br>e-mail : piyachat.b@rmutr.ac.th (P. Borisut)<br>${ }^{2}$ Department of Mathematics, Faculty of Education, Valaya Alongkorn Rajabhat University under the Royal Potronage, Pathumthani 13180, Thailand<br>e-mail : chaiwat.aui@vru.ac.th (C. Auipa-arch)

Abstract In this paper, we study and integrate the positive solution of fractional pantograph differential equation with mixed conditions of the from:

$$
\begin{gathered}
R L D_{0^{+}}^{q} u(t)+f(t, u(t), u(\lambda t))=0, t \in(0,1), 0<\lambda<1, \\
u(0)=0,{ }_{R L} D_{0^{+}}^{p} u(1)=\sum_{i=1}^{n} \alpha_{i} u\left(\eta_{i}\right), 0<p \leq 1, \eta_{i} \in(0,1),
\end{gathered}
$$

where $1<q<2, \alpha_{i} \in \mathbb{R}, n \in \mathbb{N}$, and ${ }_{R L} D_{0^{+}}^{q},{ }_{R L} D_{0^{+}}^{p}$ are the Riemann-Liouville fractional derivative of order $q, p, f:[0,1] \times \mathbb{R} \times \mathbb{R} \rightarrow \mathbb{R}$ is a continuous function. By using the fixed point theorems, the main tools for finding positive solutions and uniqueness of this problem are obtained. We give one example of the main results.

MSC: 26A33; 34A34; 34B15; 47H01; 54H25
Keywords: Fractional pantograph differential equation; mixed condition; fixed point theorem.

Submission date: 27.04 .2021 / Acceptance date: 21.07.2021

## 1. Introduction

In recent decades, fractional calculus and fractional differential equations have attracted the interest of many mathematicians and researchers. The fractional differential equations have an important role in numerous fields of study carried out by mathematicians, physicists and engineers. They have used it basically to developed the mathematical modeling, many physical applications and engineering disciplines such as viscoelasticity, control, porous media, phenomena in eletromagnetics etc. (See [1-3]). The major differences between fractional order differential operator and classical calculus is it's nonlocal behavior, that is the feature future state based on the fractional differential operator depends on its current and past states. More details on the fundamental concepts of

[^0]fractional calculus, fractional differential equations and fractional integral equations can be found in books like A. A. Kilbas, H. M Srivastava and J. J. Trujillo [1], K. S Miller and B. Ross [2], and J. Banas and K. Goebel [4]. Fractional integro-differential equations involving the Caputo-Fabrizio derivative have been studied by many researchers from differential points of view. (see, for example, [5-8] and the references therein) have been published.

In the 1960s, the British Railways wanted to make the electric locomotive faster. An important construct was the pantograph, which collects current from an overhead wire. Therefore, J. R. Ockendon and A. B. Tayler studied the motion of the pantograph head on an electric locomotive in [16]. In the solution procedure of this problem, they came across a special delay differential equation of the form

$$
x^{\prime}(t)=a x(t)+b x(\lambda t), t>0
$$

where $a, b$ are real constants and $0<\lambda<1$ for $\in \mathbb{R}$. When the article was published in 1971, this kind of delay differential equation was called pantograph equation. The pantograph equation has many applications in electrodynamic and biology; see [9]. Several authors have solved the pantograph differential equations of integer-order such as, Jacobi operational method [10], Chebyshev polynomials [11], Bernoullie polynomials [12], variational iteration method [13], and so on. But there exist few methods applied to numerical solution of pantograph differential equations of fractional-order.

Boundary value problem for fractional differential equation has aroused much attention in the past few years; many professors devoted themselves to the solvability of fractional differential equations, especially to the study of the existence of solutions for boundary value problems of fractional differential equation.

Qualitative theory of differential equations have significant application, and the existence of solutions and of positive solutions of fractional differential equations, which respect the initial and boundary value, have also received considerable attention. In order to study such type of problems different kind of techniques such as fixed point theorems [14-16], fixed point index [16, 17], upper and lower solutions method [18], coincidence theory [19], etc are in vogue. For instance, in [20-23] the authors investigate the existence of positive solutions for boundary value problems.

$$
{ }_{R L} D_{0^{+}}^{q} u(t)+f(t, u(t))=0,0<t<1
$$

with one of the boundary conditions

$$
\begin{aligned}
u(0) & =u(1)=0 \\
u(0)+u^{\prime}(0) & =u(1)+u^{\prime}(1)=0
\end{aligned}
$$

where $1<q \leq 2, f:[0,1] \times[0, \infty) \rightarrow[0, \infty)$ is continuous function and ${ }_{R L} D_{0^{+}}^{q}$ is the Riemann-Liouville fractional derivative of order $q$.
In [24], the authors solve the problem:

$$
\begin{gathered}
{ }_{R L} D_{0^{+}}^{q} u(t)+\mu f(t, u(t))=0,0<t<1, \\
u(0)=0, u(1)=c
\end{gathered}
$$

where $1<q \leq 2, \mu \in \mathbb{R}^{+}, c \in \mathbb{R}, f:[0,1] \times[0, \infty) \rightarrow[0, \infty)$ is continuous function and ${ }_{R L} D_{0^{+}}^{q}$ is the Riemann-Liouville fractional derivative of order $q$.
In 2010 [25], the authors obtained the existence results of positive solutions for the following non-linear fractional boundary value problem:

$$
{ }_{R L} D_{0^{+}}^{q} u(t)+f(t, u(t))=0,0<t<1,
$$

$$
u(0)=0, \beta u(\eta)=u(1)
$$

where $1<q \leq 2, \beta \in \mathbb{R} \backslash\{0\}, 0<\eta<1, f:[0,1] \times[0, \infty) \rightarrow[0, \infty)$ is continuous function and ${ }_{R L} D_{0^{+}}^{q}$ is the Riemann-Liouville fractional derivative of order $q$.
In 2013 [26], the authors study the existence and uniqueness of positive solutions for the following integral boundary value problem:

$$
\begin{gathered}
R L D_{0^{+}}^{q} u(t)+f(t, u(t))=0,0<t<1, \\
u(0)=0, u(1)=\int_{0}^{1} u(s) d s,
\end{gathered}
$$

where $1<q \leq 2, f:[0,1] \times[0, \infty) \rightarrow[0, \infty)$ is continuous function and ${ }_{R L} D_{0^{+}}^{q}$ is the Riemann-Liouville fractional derivative of order $q$.
In 2020 [27], the authors study and consider the positive solution of fractional differential equation with nonlocal multi-point conditions of the form:

$$
\left\{\begin{array}{l}
{ }_{R L} D_{0^{+}}^{q} u(t)+g(t) f(t, u(t))=0, t \in(0,1) \\
u^{(k)}(0)=0, u(1)=\sum_{i=1}^{m} \beta_{i R L} D_{0^{+}}^{p_{i}} u\left(\eta_{i}\right)
\end{array}\right.
$$

where $n-1<q<n, n \geq 2, n-1<p_{i}<n, q>p_{i} m, n \in \mathbb{N}, k=0,1, \ldots, n-2,0<$ $\eta_{1}<\eta_{2}<\cdots<\kappa, \beta_{i} \leq 0, \kappa \in(0,1]_{, R L} D_{0^{+}}^{q}, R L D_{0^{+}}^{p_{i}}$ are the Riemann-Liouville fractional derivative of order $q, p_{i}, f:[0,1] \times C([0,1], E) \rightarrow E, E$ be Banach space and $g:(0,1) \rightarrow \mathbb{R}^{+}$ are continuous functions.

There have already been lots of books and papers involving the positive solutions for boundary value problems of fractional differential equation ; however, only a few papers cover that for positive solution of boundary value problem involving fractional pantograph differential equation. Inspired by the papers in [22-27], the objective of this paper is to derive the existence solution of the fractional pantograph differential equations and mixed conditions:

$$
\left\{\begin{array}{l}
R L D_{0^{+}}^{q} u(t)+f(t, u(t), u(\lambda t))=0, t \in[0,1], 0<\lambda<1,  \tag{1.1}\\
u(0)=0,{ }_{R L} D_{0^{+}}^{p} u(1)=\sum_{i=1}^{n} \alpha_{i} u\left(\eta_{i}\right), 0<p \leq 1, \eta_{i} \in[0,1],
\end{array}\right.
$$

where $1<q<2, \alpha_{i} \in \mathbb{R}, n \in \mathbb{N}$, and ${ }_{R L} D_{0^{+}}^{q},{ }_{R L} D_{0^{+}}^{p}$ are the Riemann-Liouville fractional derivative of order $q, p, f:[0,1] \times \mathbb{R} \times \mathbb{R} \rightarrow \mathbb{R}$ is a continuous function.

The current paper is organized as follows: Section 1 contains the introduction; in Section 2, some basic definitions of fractional differential equations are introduced. In Section 3, the main results are devided into two parts; a positive solution for fractional pantograph differential equations is considered in Section 3.1; the study of existence and uniqueness result via Boyd and Wong fixed point theorem and one example of the main results are presented in Section 3.2. Finally, a conclusion is presented in Section 4.

## 2. PRELIMINARIES

Some basic definitions and properties of fractional differential equations are presented in this section, which are used in this paper.

Definition 2.1. [28] The Riemann-Liouville fractional integral of order $q>0$ with the lower limit zero for a function $f:(0, \infty) \rightarrow \mathbb{R}$ is defined by

$$
{ }_{R L} I_{0^{+}}^{q} f(t)=\frac{1}{\Gamma(q)} \int_{0}^{t}(t-s)^{q-1} f(s) d s
$$

where $\Gamma(\cdot)$ denotes the Gamma function defined by

$$
\Gamma(q)=\int_{0}^{\infty} e^{-s} s^{q-1} d s
$$

Definition 2.2. [28] The Riemann-Liouville fractional derivative of order $q>0$ of a function $f:(0, \infty) \rightarrow \mathbb{R}$, is defined by

$$
\left({ }_{R L} D_{0^{+}}^{q} f\right)(t)=\frac{1}{\Gamma(n-q)}\left(\frac{d}{d t}\right)^{n} \int_{0}^{t}(t-s)^{n-q-1} f(s) d s
$$

where $n$ is the smallest integer greater than or equal to $q$.
Lemma 2.3. [29] Let $b, q \geq 0$ and $x \in C(0, b) \cap L^{1}(0, b)$. Then

$$
{ }_{R L} I_{0^{+} R L}^{q} D_{0^{+}}^{q} x(t)=x(t)+c_{1} t^{q-1}+c_{2} t^{q-2}+\cdots+c_{n} t^{q-n}
$$

where $c_{i} \in \mathbb{R}, i=1,2, \ldots, n, n$ is the smallest integer greater than or equal to $q$.
Proposition 2.4. [30] If $0<r<q$ then for $f \in L^{p}([a, b], \mathbb{R}),(1 \leq p \leq \infty)$, the relation ${ }_{R L} D_{a^{+}}^{r}\left({ }_{R L} I_{a^{+}}^{q} f(t)\right)={ }_{R L} I_{a^{+}}^{q-r} f(t)$ hold almost every on $[a, b]$.
Proposition 2.5. [28] If $q, \rho>0$, for $\rho>-1+q$, we have ${ }_{R L} D_{0^{+}}^{q} t^{\rho}=\frac{\Gamma(\rho+1)}{\Gamma(1+\rho-q)} t^{\rho-q}$.
Lemma 2.6. [26] Let $D$ be a subset of the cone $P$ of semi-order Banach space $E$, $T: D \rightarrow E$ be non-decreasing. If there exist $x_{0}, y_{0} \in D$ such that $x_{0} \leq y_{0},\left\langle x_{0}, y_{0}\right\rangle \subset D$ and $x_{0}, y_{0}$ are the lower and upper solution of equation $x-T(x)=0$, then the equation $x-T(x)=0$ has maximum and minimum solution $x^{*}, y^{*}$ in $\left\langle x_{0}, y_{0}\right\rangle$ such that $x^{*} \leq y^{*}$, when one of the following condition holds:
(1) $P$ is normal and $T$ is compact continuous;
(2) $P$ is regular and $T$ is continuous;
(3) $E$ is reflexive, $P$ is normal and $T$ is continuous or weak continuous.

Definition 2.7. [31] Let $E$ be a Banach space and let $A: E \rightarrow E$ be a mapping. $A$ is said to be a non-linear contraction if there exists a continuous non-decreasing function $\Psi: \mathbb{R}^{+} \rightarrow \mathbb{R}^{+}$such that $\Psi(0)=0$ and $\Psi(\epsilon)<\epsilon$ for all $\epsilon>0$ with the property:

$$
\|A x-A y\| \leq \Psi(\|x-y\|), \forall x, y \in E .
$$

## Theorem 2.8. [31] (Boyd and Wong fixed point theorem)

Let $E$ be a Banach space and let $A: E \rightarrow E$ be a nonlinear contraction. Then $A$ has a unique fixed point in $E$.

## 3. Main Results

In this section, first we establish the following Lemma to support our main results:

Lemma 3.1. Let $1<q<2$, Assume $h(t) \in C[0,1]$, then the following equation

$$
\left\{\begin{array}{l}
R L D_{0^{+}}^{q} u(t)+h(t)=0, t \in[0,1], 0<\lambda<1,  \tag{3.1}\\
u(0)=0,{ }_{R L} D_{0^{+}}^{p} u(1)=\sum_{i=1}^{n} \alpha_{i} u\left(\eta_{i}\right), 0<p \leq 1, \eta_{i} \in[0,1],
\end{array}\right.
$$

has a unique solution $u(t)=\int_{0}^{1} G(t, s) h(s) d s$, where

$$
G(t, s)= \begin{cases}\frac{1}{\Gamma(q) \sigma(0)}\left[t^{q-1}(1-s)^{q-p-1} \sigma(s)-(t-s)^{q-1} \sigma(0)\right], & 0 \leq s \leq t \leq 1  \tag{3.2}\\ \frac{1}{\Gamma(q) \sigma(0)}\left[t^{q-1}(1-s)^{q-p-1} \sigma(s)\right], & 0 \leq t \leq s \leq 1\end{cases}
$$

Proof. We may apply Lemma 2.3 to reduce equation (3.1) to an equivalent integral equation.

$$
u(t)=-{ }_{R L} I_{0^{+}}^{q} h(t)+c_{1} t^{q-1}+c_{2} t^{q-2}
$$

By $u(0)=0$, we can get $c_{2}=0$

$$
u(t)=-{ }_{R L} I_{0^{+}}^{q} h(t)+c_{1} t^{q-1}
$$

and second condition, we have

$$
\begin{aligned}
{ }_{R L} D_{0^{+}}^{p} u(1) & =-{ }_{R L} I_{0^{+}}^{q-p} h(1)+\frac{c_{1} \Gamma(q)}{\Gamma(q-p)} \\
\sum_{i=1}^{n} \alpha_{i} u\left(\eta_{i}\right) & =-\sum_{i=1}^{n} \alpha_{i R L} I_{0^{+}}^{q} h\left(\eta_{i}\right)+c_{1} \sum_{i=1}^{n} \alpha_{i} \eta_{i}^{q-1} .
\end{aligned}
$$

So,

$$
c_{1}=\frac{\Gamma(q-p)}{\Gamma(q-p) \sum_{i=1}^{n} \alpha_{i} \eta_{i}^{q-1}-\Gamma(q)}\left[-{ }_{R L} I_{0^{+}}^{q-p} h(1)+\sum_{i=1}^{n} \alpha_{i R L} I_{0^{+}}^{q} h\left(\eta_{i}\right)\right] .
$$

Hence,

$$
u(t)=-{ }_{R L} I_{0^{+}}^{q} h(t)+\frac{t^{q-1} \Gamma(q-p)}{\Gamma(q-p) \sum_{i=1}^{n} \alpha_{i} \eta_{i}^{q-1}-\Gamma(q)}\left[-{ }_{R L} I_{0^{+}}^{q-p} h(1)+\sum_{i=1}^{n} \alpha_{i R L} I_{0^{+}}^{q} h\left(\eta_{i}\right)\right]
$$

From Definition 2.1

$$
\begin{aligned}
u(t)= & -\frac{1}{\Gamma(q)} \int_{0}^{t}(t-s)^{q-1} h(s) d s-\frac{t^{q-1} \Gamma(q-p)}{\Gamma(q-p) \sum_{i=1}^{n} \alpha_{i} \eta_{i}^{q-1}-\Gamma(q)} \times \\
& {\left[\frac{1}{\Gamma(q-p)} \int_{0}^{1}(1-s)^{q-p-1} h(s) d s-\sum_{i=1}^{n} \frac{\alpha_{i}}{\Gamma(q)} \int_{0}^{\eta_{i}}\left(\eta_{i}-s\right)^{q-1} h(s)\right] } \\
= & -\frac{1}{\Gamma(q)} \int_{0}^{t}(t-s)^{q-1} h(s) d s-\frac{t^{q-1} \Gamma(q-p)}{\Gamma(q-p) \sum_{i=1}^{n} \alpha_{i} \eta_{i}^{q-1}-\Gamma(q)} \times \\
& \left.-\sum_{i=1}^{n} \frac{\alpha_{i}}{\Gamma(q)} \int_{0}^{t}\left(\eta_{i}-s\right)^{q-1} h(s) d s-\sum_{i=1}^{n} \frac{\alpha_{i}}{\Gamma(q)} \int_{t}^{1}\left(\eta_{i}-s\right)^{q-1} h(s) d s\right] \\
= & \int_{0}^{t}\left[-\frac{(t-s)^{q-1}}{\Gamma(q)}-\frac{t^{q-1} \Gamma(q-p)}{\Gamma(q-p) \sum_{i=1}^{n} \alpha_{i} \eta_{i}^{q-1}-\Gamma(q)}\left(\frac{(1-s)^{q-p-1}}{\Gamma(q-p)}\right.\right. \\
& \left.\left.-\sum_{i=1}^{n} \frac{\alpha_{i}\left(\eta_{i}-s\right)^{q-1}}{\Gamma(q)}\right)\right] h(s) d s-\int_{t}^{1}\left[\frac { t ^ { q - 1 } \Gamma ( q - p ) } { \Gamma ( q - p ) \sum _ { i = 1 } ^ { n } \alpha _ { i } \eta _ { i } ^ { q - 1 } - \Gamma ( q ) } \left(\frac{(1-s)^{q-p-1}}{\Gamma(q-p)}\right.\right. \\
& \left.\left.-\sum_{i=1}^{n} \frac{\alpha_{i}\left(\eta_{i}-s\right)^{q-1}}{\Gamma(q)}\right) h(s)\right] d s \\
= & \int_{0}^{t} \frac{1}{\Gamma(q) \sigma(0)}\left[-(t-s)^{q-1}(1-s)^{q-p-1} \sigma(0)+t^{q-1} \sigma(s)\right] h(s) d s \\
& +\int_{t}^{1} \frac{t^{q-1}(1-s)^{q-p-1} \sigma(s)}{\Gamma(q) \sigma(0)} h(s) d s .
\end{aligned}
$$

Hence; $u(t)=\int_{0}^{1} G(t, s) h(s) d s$, where

$$
\begin{array}{ll}
G(t, s)= \begin{cases}\frac{1}{\Gamma(q) \sigma(0)}\left[t^{q-1}(1-s)^{q-p-1} \sigma(s)-(t-s)^{q-1} \sigma(0)\right], & 0 \leq s \leq t \leq 1 \\
\frac{1}{\Gamma(q) \sigma(0)}\left[t^{q-1}(1-s)^{q-p-1} \sigma(s)\right], & 0 \leq t \leq s \leq 1\end{cases} \\
\sigma(s)=\frac{1}{\Gamma(q-p)}-\sum_{i=1}^{n} \frac{\alpha_{i}\left(\eta_{i}-s\right)^{q-1}}{\Gamma(q)(1-s)^{q-p-1}}, \sigma(0)=\frac{1}{\Gamma(q-p)}-\sum_{i=1}^{n} \frac{\alpha_{i} \eta_{i}^{q-1}}{\Gamma(q)}
\end{array}
$$

Lemma 3.2. Suppose that $\sigma(0)>0, \alpha>0, q-p-1<0$ that function $\sigma(s)>0, s \in[0,1]$ and $\sigma$ is non-decreasing on $[0,1]$.

Lemma 3.3. The function $G(t, s)$, defined by (3.2) admits the following property $G(t, s) \geq$ 0 .

Proof. For $0 \leq s \leq t \leq 1$, noticing that $\sigma(0)>0$. By Lemma 3.2, we get

$$
\begin{aligned}
G(t, s) & \geq \frac{1}{\Gamma(q) \sigma(0)}\left[t^{q-1}(1-s)^{q-p-1} \sigma(0)-t^{q-1}\left(1-\frac{s}{t}\right)^{q-1} \sigma(0)\right] \\
& >\frac{t^{q-1}}{\Gamma(q)}\left[(1-s)^{q-1}-\left(1-\frac{s}{t}\right)^{q-1}\right] \geq 0
\end{aligned}
$$

In view of $0 \leq t \leq s \leq 1$, we get $G(t, s) \geq 0$. Obviously, $G(t, s)$ is continuous on $[0,1] \times[0,1]$.

Let $E=C[0,1]$ be the Banach space endowed with the sup-norm and define the cone $P \subset E . P=\{u \in E: u(t) \geq 0,0 \leq t \leq 1\}$. Define the operator $T: P \rightarrow P$ as follows

$$
T u(t):=\int_{0}^{1} G(t, s) f(s, u(s), u(\lambda s)) d s
$$

then the equation (1.1) has a solution if and only if the operator $T$ has a fixed point.

### 3.1. A POSITIVE SOLUTION FOR FRACTIONAL PANTOGRAPH DIFFERENTIAL EQUATIONS

The definition of lower and upper solution of the operator $T$ are given below.
Definition 3.4. [26] Let $v(t), w(t) \in E$, we say that $v(t)$ is called a lower solution of operator $T$ if $v(t) \leq T v(t)$, and $w(t)$ is called an upper solution of operator $T$ if $w(t) \geq T w(t)$.

Theorem 3.5. Assume that
(H1) $f:[0,1] \times[0,+\infty) \times[0,+\infty) \rightarrow[0,+\infty)$ is continuous $f(t, \cdot)$ is non-decreasing for each $t \in[0,1]$ and there exists a positive constant a such that $f(t, \cdot)$ is strictly increasing on $[0, a]$ for each $t \in[0,1]$;
$(H 2) 0<\lim _{u \rightarrow+\infty} f(t, u(t), u(\lambda t))<+\infty$ for each $t \in[0,1]$.
Then the equation (1.1) has a positive solution.
Proof. We will prove the theorem through four steps.
Step 1. $T: P \rightarrow P$ is completely continuous. The operator $T: P \rightarrow P$ is continuous in view of non-negativeness and continuity of $G(t, s)$ and $f(t, u(t), u(\lambda t)), 0<\lambda<1$. Let $\Omega \subset P$ be bounded, which is to say there exists a positive constant $M>0$ such that $\|u\| \leq M, \forall u \in \Omega$. Let $L=\max _{0 \leq t \leq 1,0 \leq u \leq 1}|f(t, u(t), u(\lambda t))|+1$. Then $\forall u \in \Omega$, we have

$$
\begin{aligned}
|T u(t)| & \leq \int_{0}^{1} G(t, s) f(s, u(s), u(\lambda s)) d s \\
& \leq L \int_{0}^{1} G(t, s) d s
\end{aligned}
$$

Hence $T(\Omega)$ is bounded. For each $u \in \Omega, \forall \tau_{1}, \tau_{2} \in[0,1]$ satisfy $\tau_{1}<\tau_{2}$, we have

$$
\begin{aligned}
\left|T u\left(\tau_{2}\right)-T u\left(\tau_{1}\right)\right|= & \left|\int_{0}^{1} G\left(\tau_{2}, s\right) f(s, u(s), u(\lambda s)) d s-\int_{0}^{1} G\left(\tau_{1}, s\right) f(s, u(s), u(\lambda s)) d s\right| \\
\leq & \int_{0}^{\tau_{1}}\left|G\left(\tau_{2}, s\right)-G\left(\tau_{1}, s\right)\right| f(s, u(s), u(\lambda s)) d s \\
& +\int_{\tau_{1}}^{\tau_{2}}\left|G\left(\tau_{2}, s\right)-G\left(\tau_{1}, s\right)\right| f(s, u(s), u(\lambda s)) d s \\
& +\int_{\tau_{2}}^{1}\left|G\left(\tau_{2}, s\right)-G\left(\tau_{1}, s\right)\right| f(s, u(s), u(\lambda s)) d s \\
\left|T u\left(\tau_{2}\right)-T u\left(\tau_{1}\right)\right|= & \frac{1}{\Gamma(q) \sigma(0)} \int_{0}^{\tau_{1}}\left[\left(\tau_{2}^{q-1}-\tau_{1}^{q-1}\right)(1-s)^{q-p-1} \sigma(s)\right. \\
& \left.-\left\{\left(\tau_{2}-s\right)^{q-1}-\left(\tau_{1}-s\right)^{q-1}\right\} \sigma(0)\right] f(s, u(s), u(\lambda s)) d s \\
& +\frac{1}{\Gamma(q) \sigma(0)} \int_{\tau_{1}}^{\tau_{2}}\left[\left(\tau_{2}^{q-1}-\tau_{1}^{q-1}\right)(1-s)^{q-p-1} \sigma(s)\right. \\
& \left.-\left\{\left(\tau_{2}-s\right)^{q-1}-\left(\tau_{1}-s\right)^{q-1}\right\} \sigma(0)\right] f(s, u(s), u(\lambda s)) d s \\
& +\frac{1}{\Gamma(q) \sigma(0)} \int_{\tau_{2}}^{1}\left[\left(\tau_{2}^{q-1}-\tau_{1}^{q-1}\right)(1-s)^{q-p-1} \sigma(s)\right. \\
& \left.-\left\{\left(\tau_{2}-s\right)^{q-1}-\left(\tau_{1}-s\right)^{q-1}\right\} \sigma(0)\right] f(s, u(s), u(\lambda s)) d s .
\end{aligned}
$$

Since $\sigma(s)$ is non-decreasing on $[0,1]$ then $\sigma(s)<\sigma(1)$.

$$
\begin{aligned}
\left|T u\left(\tau_{2}\right)-T u\left(\tau_{1}\right)\right| \leq & \frac{L}{\Gamma(q) \sigma(0)}\left[\left(\tau_{2}^{q-1}-\tau_{1}^{q-1}\right) \sigma(1) \frac{\left[1-\left(1-\tau_{1}\right)^{q-1}\right]}{q-p}\right. \\
& \left.-\sigma(0)\left(\frac{\tau_{2}^{q}-\tau_{1}^{q}}{q}-\frac{\left(\tau_{2}-\tau_{1}\right)^{q}}{q}\right)\right] \\
& +\frac{L}{\Gamma(q) \sigma(0)}\left[\left(\tau_{2}^{q-1}-\tau_{1}^{q-1}\right) \sigma(1) \frac{\left[\left(1-\tau_{1}\right)^{q-p}-\left(1-\tau_{2}\right)^{q-p}\right]}{q-p}\right. \\
& \left.-\sigma(0) \frac{\left(\tau_{2}-\tau_{1}\right)^{q}}{q}\right]+\frac{L}{\Gamma(q) \sigma(0)}\left(\tau_{2}^{q-1}-\tau_{1}^{q-1}\right) \sigma(1) \frac{\left[1-\left(1-\tau_{2}\right)^{q-1}\right]}{q-p}
\end{aligned}
$$

As $\tau_{2} \rightarrow \tau_{1}$, the right hand side tends to zero. The Arzela-Ascoli Theorem implies that $\overline{T(\Omega)}$ is compact. That is $T: P \rightarrow P$ is completely continuous.
Step 2. $T$ is an increasing operator. In fact, by $(H 1)$, let $u_{1} \leq u_{2}$, we have

$$
\begin{aligned}
T u_{1}(t) & =\int_{0}^{1} G(t, s) f\left(s, u_{1}(s), u_{1}(s)\right) d s \\
& \leq \int_{0}^{1} G(t, s) f\left(s, u_{2}(s), u_{2}(s)\right) d s \leq T u_{2}(t)
\end{aligned}
$$

So; $T$ is an increasing operator.
Step 3. By (H2), $\exists M_{1}>0, N>0$, such that $u \geq N_{1}$, it holds $f:[0,1] \times\left[0, N_{1}\right] \times\left[0, N_{2}\right]$,
where $N_{1}>N_{2}$, is continuous $\exists M_{2}>0$ such that $u \leq N_{1}$, it hold $f(t, u(t), u(\lambda t)) \leq$ $M, \forall u \geq 0$. Now we consider the following equation

$$
\left\{\begin{array}{l}
{ }_{R L} D_{0^{+}}^{q} w(t)+M=0, t \in[0,1], 1<q \leq 2  \tag{3.3}\\
w(0)=0,{ }_{R L} D_{0^{+}}^{p} w(1)=\sum_{i=1}^{n} \alpha_{i} w\left(\eta_{i}\right), 0<p \leq 1, \eta_{i} \in[0,1] .
\end{array}\right.
$$

From Theorem 3.1, we have solution of (3.3) is an upper solution of the oprator $T$. On the other hand, its obvious that $v(t) \equiv 0$ is a lower solution of the operator $T$, and we have $v(t) \leq w(t)$.
Step 4. Since $P$ is a normal cone. Lemma 2.6 implies that $T$ has a fixed point $u \in$ $\langle 0, w(t)\rangle$. Therefore, the equation (1.1) has a positive solution.

### 3.2. Existence and Uniqueness Result Via Boyd and Wong Fixed Point Theorem.

Theorem 3.6. Let $f:[0,1] \times\left[0, N_{1}\right] \times\left[0, N_{2}\right] \rightarrow \mathbb{R}$ be a continuous function satisfying the assumption:

$$
|f(t, u(t), u(\lambda t))-f(t, v(t), v(\lambda t))| \leq \frac{\beta(t)|u-v|}{B+|u-v|}, \text { for } t \in[a, b], u, v \geq 0
$$

where $\beta(t):[a, b] \rightarrow \mathbb{R}^{+}$is continuous and $B$ is the constant defined by

$$
B:=\int_{0}^{1} G(s, t) \beta(s) d s<1 .
$$

Then the problem (1.1) has a unique solution on $[0,1]$.
Proof. Consider a continuous non-decreasing function $\Psi: \mathbb{R}^{+} \rightarrow \mathbb{R}^{+}$by

$$
\Psi(\epsilon)=\frac{B \epsilon}{B+\epsilon}
$$

for all $\epsilon>0$, such that $\Psi(0)=0$ and $\Psi(\epsilon)<\epsilon$ for all $\epsilon>0$. For any $u, v \in C[0,1]$ and for each $t \in[0,1]$, yields.

$$
\begin{aligned}
|T u(t)-T v(t)| & \leq\left|\int_{0}^{1} G(t, s) f(s, u(s), u(\lambda s)) d s-\int_{0}^{1} G(t, s) f(s, v(s), v(\lambda s)) d s\right| \\
& \leq \int_{0}^{1} G(t, s)|f(s, u(s), u(\lambda s)) d s-f(s, v(s), v(\lambda s))| d s \\
& \leq \int_{0}^{1} G(s, t) \frac{\beta(s)|u-v|}{B+|u-v|} d s \\
& \leq \frac{\Psi(\|u-v\|)}{B}\left[\int_{0}^{1} G(s, t) \beta(s) d s\right] \\
& \leq \Psi(\|u-v\|) .
\end{aligned}
$$

This implies that $\|T u-T v\| \leq \Psi(\|u-v\|)$. There for $A$ is a non-linear contraction. Hence, by theorem (Boyd and Wong). The operator $T$ has a unique fixed point, which is the unique solution of the problem (1.1).

Example 3.7. Consider the following fractional boundary value problems

$$
\left\{\begin{array}{l}
{ }_{R L} D_{0^{+}}^{\frac{5}{4}} u(t)+\frac{(\sqrt{t}+3)}{7}\left(1-\frac{1}{2|1+u(t)|}-\frac{1}{3\left|1+u\left(\frac{2 t}{3}\right)\right|}\right)=0, t \in(0,1),  \tag{3.4}\\
u(0)=0,{ }_{R L} D_{0^{+}}^{\frac{1}{2}} u(1)=\frac{1}{3} u\left(\frac{1}{3}\right)+\frac{1}{4} u\left(\frac{1}{4}\right)+\frac{1}{5} u\left(\frac{1}{5}\right) .
\end{array}\right.
$$

By comparing problem (3.1) and (3.4), we obtain the following parameters: $q=5 / 4, p=$ $1 / 2, \alpha_{1}=1 / 3, \alpha_{2}=1 / 4, \alpha_{3}=1 / 5, \eta_{1}=1 / 3, \eta_{2}=1 / 4, \eta_{3}=1 / 5, f(t, u(t), u(\lambda t))=$ $\frac{(\sqrt{t}+3)}{7}\left(1-\frac{1}{2|1+u(t)|}-\frac{1}{3\left|1+u\left(\frac{2 t}{3}\right)\right|}\right)$. Note that $-\frac{1}{2|1+u(t)|} \leq 0,-\frac{1}{3\left|1+u\left(\frac{2 t}{3}\right)\right|} \leq 0$. We now obtain

$$
\begin{aligned}
\lim _{u \rightarrow+\infty} f(t, u(t), u(\lambda t)) & =\lim _{u \rightarrow+\infty} \frac{(\sqrt{t}+3)}{7}\left(1-\frac{1}{2|1+u(t)|}-\frac{1}{3\left|1+u\left(\frac{2 t}{3}\right)\right|}\right) \\
& \leq \frac{(\sqrt{t}+3)}{7}<+\infty
\end{aligned}
$$

Then, the condition $(H 1)$ and $(H 2)$ hold. If fact, the solution of (3.4) is equivalent to a fixed point of the operator $T$, here

$$
\begin{aligned}
T u(t) & =\int_{0}^{1} G(t, s) f(s, u(s), u(\lambda s)) d s \\
& =\int_{0}^{1} G(t, s) \frac{(\sqrt{s}+3)}{7}\left(1-\frac{1}{2|1+u(s)|}-\frac{1}{3\left|1+u\left(\frac{2 s}{3}\right)\right|}\right) d s
\end{aligned}
$$

Setting $w(t)=\int_{0}^{1} G(t, s) \frac{(\sqrt{s}+3)}{7} d s$, and $v(t) \equiv 0$, then

$$
w(t) \geq \int_{0}^{1} G(t, s) f(s, w(s), w(\lambda s)) d s=T w(t)
$$

which implies $w(t)$ is an upper solution of the operator $T$. It is obvious that $v(t) \equiv 0$ is a lower solution of the operator $T$. Thus, by Theorem 3.5, we can get that the problem (3.7) has a positive solution. By choosing $\beta(t)=5 / 6$ we then have $B=\int_{0}^{1} G(s, t) \beta(s) d s \approx$ 0.4906. Consider

$$
\begin{aligned}
\left|f\left(t, u_{1}(t), u_{1}(\lambda t)\right)-f\left(t, u_{2}(t), u_{2}(\lambda t)\right)\right|= & \left\lvert\,-\frac{1}{2\left|1+u_{1}(t)\right|}+\frac{1}{2\left|1+u_{2}(t)\right|}\right. \\
& \left.-\frac{1}{3\left|1+u_{1}\left(\frac{2 t}{3}\right)\right|}+\frac{1}{3\left|1+u_{2}\left(\frac{2 t}{3}\right)\right|} \right\rvert\, \\
\leq & \left|-\frac{5}{6\left|1+u_{1}(t)\right|}+\frac{5}{6\left|1+u_{2}(t)\right|}\right| \\
\leq & \frac{\frac{5}{6}\left|u_{1}-u_{2}\right|}{1+\left|u_{1}-u_{2}\right|} \\
\leq & \frac{\frac{5}{6}\left|u_{1}-u_{2}\right|}{0.4906+\left|u_{1}-u_{2}\right|}
\end{aligned}
$$

Hence, by Theorem 3.6, problem (3.4) has a unique solution on $(0,1)$.

## 4. CONCLUSION

In conclusion, a positive solution for fractional pantograph differential equations is obtained and existence and uniqueness result via Boyd and Wong fixed point theorem is presented. Also we give example as an application to illustrate the results obtained.

## Acknowledgements

We would like to thank Valaya Alongkorn Rajabhat University under the Royal Potronage, Pathumthani and Rajamangala University of Technology Rattanakosin for giving us the opportunity to do research. Also, the authors are grateful to the referees for many useful comments and suggestions which have improved the presentation of this paper.

## References

[1] I. Podlubny, Fractional differential equations. Academic Press, New york, 1999.
[2] K. S. Miller, B. Ross, An introduction to the fractional calculus and fractional differential equations. Wiley, New York, 1993.
[3] A.A. Kilbas, H.M. Srivastava, J.J. Trujillo, Theory and applications of fractional differential equations, North-Holland Mathematics Studies 204 (2006) 7-10.
[4] J. Banas, K.Goebel, Measures of Noncompactness in Banach Spaces, Lecture Notes in Pure and Applied Mathematics 60, Macel Dekker, New York, 1980.
[5] Sh. Rezapour, V. Hedayati, On a Caputo fractional differential inclusion with integral boundary condition for convex-compact and nonconvex-compact valued multifunctions, Kragujevac Journal of Mathematics 41 (1) (2017) 143-158.
[6] Sh. Rezapour, M. Shabibi, A singular fractional differential equation with RiemannLiouville integral boundary condition, Journal of Advanced Mathematical Studies 8 (1) (2015) 80-88.
[7] D. Baleanu, S. Rezapour, Z. Saberpour, On fractional integro-differential inclusions via the extended fractional Caputo-Fabrizio derivation, Journal of Advanced Mathematical Studies, 2019.
[8] D. Baleanu, A. Mousalou, S. Rezapour, A new method for investigating approximate solutions of some fractional integro-differential equations involving the CaputoFabrizio derivative, Advances in Difference Equations, 2017.
[9] R.L. Magin, Fractional calculus models of complex dynamics in biological tissues, Comput. Math. Appl. 59 (2010) 1586-1593.
[10] A. Borhanifar, K. Sadri, A new operational approach for numerical solution of generalized functional integro-differential equations, J. Comput. Appl. Math. 279 (2015) 80-96.
[11] S. Sedaghat, Y. Ordokhani, M. Dehghan, Numerical solution of the delay differential equations of pantograph type via Chebyshev polynomials, Commun. Nonlinear Sci. Numer. Simul. 17 (2012) 4815-4830.
[12] E. Tohidi, A.H. Bhrawy, K.A. Erfani, Collocation method based on Bernoulli operational matrix for numerical solution of generalized panto- graph equation, Appl. Math. Model. 37 (2012) 4283-4294.
[13] Z.H. Yu, Variational iteration method for solving the multipantograph delay equation, Phys. Lett. A. 372 (2008) 6475-6479.
[14] Z. Han, H. Lu, C. Zhang, Positive solutions for eigenvalue problems of fractional differential equations with generalized P-Laplacian, Appl. Math. Comp. 257 (2014) 526-536.
[15] H.R. Marasi, H. Afshari, C.B. Zhai, Some existence and uniqueness results for nonlinear fractional partial differential equations, Rocky Mountain J. Math.
[16] X. Zhang, L. Wang, Qian Sun, Existence of positive solutions for a class of nonlinear fractional differential equations with integral boundary conditions and a parameter, Appl. Math. Comp. 226 (2014) 708-718.
[17] Y. Sun, Positive solutions of Sturm-Liouville boundary value problems for singular nonlinear second-order impulsive integro-differential equation in Banach spaces, Boundary Value Problems 86 (2012).
[18] S. Liang, J. Zhang, Positive solutions for boundary value problems of nonlinear fractional differential equations, Nonlinear Anal. 71 (2009) 5545-5550.
[19] T. Chen, W. Liu, Z. Hu, A boundary value problem for fractional differential equation with P-Laplacian operator at resonance, Nonlinear Anal. 75 (2012) 3210-3217.
[20] N. Kosmatov, Integral equations and initial value problems for nonlinear differential equations of fractional order, Nonlinear Anal. 70 (2009) 2521-2529.
[21] J. Deng, L. Ma, Existence and uniqueness of solutions of initial value problems for nonlinear fractional differential equations, Appl. Math. Lett. 23 (2010) 676-680.
[22] Z. Bai, H.S. Lu, Positive solutions of boundary value problems of nonlinear fractional differential equation, Journal of Applied Mathematics 311 (2005) 495-505.
[23] S.Q. Zhang, Positive solutions for boundary for boundary value problems of nonlinear fractional differential equations, Electronic Journal of Differential Equations 36 (2006) 1-12.
[24] H. Jafari, V.D. Gejji, Positive solutions of nonlinear fractional boundary value problems using adomian decomposition method, Applied Mathematics and Computation, (108) 2016, 700 -706.
[25] Z. Bai, On positive solutions of a nonlocal fractional boundary value problem, Journal of Applied Mathematics, (72) 2013, 916-924.
[26] G. Wang, S. Liu, R.P. Agawal, L. Zhang, Positive solutions of integral boundary value problem involving Riemann-Liouville fractional derivative, Journal of Fractional Calculus and Applications 2 (2013) 312-321.
[27] P. Borisut, P. Kumam, I. Ahmed, K. Sitthithakerngkiet, Positive Solution for nonlinear fractional differential equation with nonlocal multi-point condition, Fixed Point Theory 21 (2020) 427-440.
[28] A.A. Kibas, H.M. Srivastava, J.J. Trujillo, Theory and Applications of Fractional Differential Equations, North Holland athematics Studies 204 (2006) 123-145.
[29] K. Sathiyanathan, V. Krishnaveni, Nonlinear Implicit Caputo Fractional Differential Equations with Integral Boundary Conditions in Banach Space, Global Journal of Pure and Applied Mathematics 13 (2017) 3895-3907.
[30] Y. Zhou, J. Wang, L. Zhang, Basic Theory of Fractional Differential Equations, World Scientific (2013) 18-20.
[31] B. Ahmad, A. Alsacdi, S.K. Ntouyas, J. Tariboon, Hadamard-Type Fractional Differential Equations Inclusions and Inequalities, Springer International Publishing (2017), 3-11.


[^0]:    *Corresponding author.

