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# Bochner-Chen Ideal Submanifolds 

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#### Abstract

In this paper, we investigate ideal invariant submanifolds, ideal anti-invariant submanifolds and ideal CR-submanifolds of Bochner Kaehler manifolds. Moreover, some characterizations related with the holomorphic sectional curvature and the anti-holomorphic sectional curvature are obtained for Bochner Kaehler manifolds.


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## 1. Introduction

In 1949, S. Bochner [1] introduced a new tensor as an analogue of the Weyl conformal curvature tensor in a complex local coordinate system in an $m$ complex dimensional Kaehlerian manifold $\widetilde{M}$ with Riemannian metric $\widetilde{g}$ as follows:

$$
\begin{align*}
B(X, Y) Z= & \widetilde{R}(X, Y) Z-\frac{1}{2(m+2)}\{\widetilde{g}(Y, Z) \widetilde{Q}(X)-\widetilde{g}(\widetilde{Q} X, Z) Y+\widetilde{g}(\widetilde{Q} Y, Z) X \\
& -\widetilde{g}(X, Z) \widetilde{Q} Y+\widetilde{g}(J Y, Z) \widetilde{Q} J X-\widetilde{g}(\widetilde{Q} J X, Z) J Y+\widetilde{g}(\widetilde{Q} J Y, Z) J X \\
& -\widetilde{g}(J X, Z) \widetilde{Q} J Y-2 \widetilde{g}(J X, \widetilde{Q} Y) J Z-2 \widetilde{g}(J X, Y) \widetilde{Q} J Z\} \\
& +\frac{\widetilde{\tau}}{4(m+1)(m+2)}\{\widetilde{g}(Y, Z) X-\widetilde{g}(X, Z) Y+\widetilde{g}(J Y, Z) J X \\
& -\widetilde{g}(J X, Z) J Y-2 \widetilde{g}(J X, Y) J Z\} \tag{1.1}
\end{align*}
$$

where $J$ is the almost complex structure, $\widetilde{R}$ is the Riemannian curvature tensor, $\widetilde{\tau}$ is the scalar curvature, $\widetilde{Q}$ denotes the Ricci operator defined by

$$
\begin{equation*}
\widetilde{g}(\widetilde{Q} X, Y)=\widetilde{\operatorname{Ric}}(X, Y) \tag{1.2}
\end{equation*}
$$

for any $X, Y, Z, W \in \Gamma(T \widetilde{M})$. Later, many mathematicians have obtained some necessary and sufficient conditions for exploring the geometric meaning of vanishing Bochner curvature tensor in some different spaces. For example, in [2], S. Tachibana studied and

[^0]obtained an interesting expression for the Bochner curvature tensor in Kaehler manifold. In [3], M. Sitaramayya and in [4], H. Mori obtained a generalized Bochner curvature tensor as a component in its curvature tensor on Kaehlerian vector spaces. In [5], F. Tricerri and L. Vanhecke generalized this notion, that is, they defined the generalized Bochner curvature tensor as a component of the element of spaces of arbitrary generalized curvature tensors on Hermitian vector space. In [6], L. Vanhecke proved that the Ricci operator is complex linear for an almost Hermitian manifold with vanishing Bochner curvature tensor if and only if the manifold is a para-Kahlerian manifold. In [7], L. Vanhecke and K. Yano showed that the Ricci operator is complex linear if and only if the Riemannian curvature tensor satisfies the following relation:
\[

$$
\begin{align*}
\widetilde{g}(\widetilde{R}(X, Y) Z, W)= & \widetilde{g}(\widetilde{R}(J X, J Y) Z, W)+\widetilde{g}(\widetilde{R}(J X, Y) J Z, W) \\
& +\widetilde{g}(\widetilde{R}(J X, Y) Z, J W) \tag{1.3}
\end{align*}
$$
\]

for all tangent vectors $X, Y, Z, W$ of the manifold. In [8], D. E. Blair stated that every totally geodesic anti-invariant submanifold of a Kaehler manifold of complex dimension $>3$ with vanishing Bochner curvature tensor is conformally flat. In [9], H. M. Abood studied the geometric meaning of vanishing the generalized Bochner curvature tensor in nearly Kaehler manifold. In [10], Y. Euh, J.H. Park, K. Sekigawa investigated the local structures of nearly Kaehler manifolds with vanishing Bochner curvature tensor. Bochner Kaehler manifolds were also discussed in [11-21] etc.

Furthermore, B.-Y. Chen and F. Dillen [22] established new simple geometric characterizations of Bochner-Kaehler and Einstein-Kaehler spaces of complex space forms. They stated that the manifold $\widetilde{M}$ is an $m$-complex dimensional Bochner Kaehler manifold if and only if the following statements satisfy for every orthonormal basis $\{X, Y\}$ of any totally real plane section:
(1) the totally real bisectional curvature $\widetilde{H}(X, Y)$ depends on the totally real plane section $\Pi=\operatorname{Span}\{X, Y\}$ and not on the choice of orthonormal basis $X, Y$;
(2) $\widetilde{H}(X)+\widetilde{H}(Y)$ depends only on the totally real plain section $\Pi=\operatorname{Span}\{X, Y\}$ and not on the choice of orthonormal basis $X, Y$;
(3) the sectional curvatures satisfy $\widetilde{K}(X, Y)=\widetilde{K}(X, J Y)$;
(4) $\widetilde{H}(X)+\widetilde{H}(Y)=8 \widetilde{K}(X, Y)$;
(5) $\widetilde{H}(X)+\widetilde{H}(Y)=4 \widetilde{H}(X, Y)$;
(6) $\widetilde{R}(X, J Y, J Y, Y)=\widetilde{R}(X, J X, J X, Y)$.

The main purpose of the present paper is to continue this work.

## 2. Riemannian Invariants and Submanifolds

In this section, we recall a number of Riemannian invariants which are the intrinsic characteristics of a Riemannian manifold and affect the behavior of the Riemannian manifold.

Let $\widetilde{M}$ be an $m$-dimensional Riemannian manifold equipped with a Riemannian metric $\widetilde{g}$ and inner product of the metric $\widetilde{g}$ is denoted by $\langle$,$\rangle . Let \left\{e_{1}, \ldots, e_{m}\right\}$ be an orthonormal basis for $T_{p} \widetilde{M}$. The sectional curvature, denoted $\widetilde{K}_{i j}$, of the plane section spanned by $e_{i}$ and $e_{j}$ at $p \in M$ is given by

$$
\begin{equation*}
\widetilde{K}_{i j} \equiv \widetilde{K}_{M}\left(e_{i}, e_{j}\right) \equiv \widetilde{R}\left(e_{i}, e_{j}, e_{j}, e_{i}\right) \equiv \widetilde{R}\left(e_{j}, e_{i}, e_{i}, e_{j}\right), \tag{2.1}
\end{equation*}
$$

where $\widetilde{R}$ is the Riemannian curvature tensor.
The Ricci tensor $\widetilde{\text { Ric }}$ is defined by

$$
\begin{equation*}
\widetilde{\operatorname{Ric}}(X, Y)=\sum_{j=1}^{m} \widetilde{R}\left(e_{j}, X, Y, e_{j}\right) \tag{2.2}
\end{equation*}
$$

for any $X, Y \in T_{p} \widetilde{M}$.
For a fixed $i \in\{1, \ldots, m\}$, we have

$$
\begin{aligned}
\widetilde{\operatorname{Ric}}\left(e_{i}, e_{i}\right) & =\sum_{j=1}^{m} \widetilde{R}\left(e_{j}, e_{i}, e_{i}, e_{j}\right)=\sum_{j=1}^{m} \widetilde{R}\left(e_{i}, e_{j}, e_{j}, e_{i}\right) \\
& =\sum_{j \neq i}^{m} \widetilde{R}\left(e_{i}, e_{j}, e_{j}, e_{i}\right)=\sum_{j \neq i}^{m} \widetilde{K}_{i j} .
\end{aligned}
$$

Let $u$ be a unit vector in $T_{p} \widetilde{M}$. We choose an orthonormal basis $\left\{e_{1}, \ldots, e_{m}\right\}$ of $T_{p} \widetilde{M}$ such that $e_{1}=u$. The Ricci curvature $\widetilde{\operatorname{Ric}}(u)$ of $u$ is defined by

$$
\begin{equation*}
\widetilde{\operatorname{Ric}}(u)=\widetilde{K}_{12}+\widetilde{K}_{13}+\cdots+\widetilde{K}_{1 m}=\sum_{j=2}^{m} \widetilde{K}_{1 j} . \tag{2.3}
\end{equation*}
$$

The scalar curvature $\widetilde{\tau}$ at $p$ is defined by

$$
\begin{equation*}
\widetilde{\tau}(p)=\sum_{i<j} \widetilde{K}_{i j} . \tag{2.4}
\end{equation*}
$$

The Chen invariant which is certainly an intrinsic character of a (sub)manifold [23] is given by

$$
\begin{equation*}
\delta_{\widetilde{M}}(p)=\widetilde{\tau}(p)-(\inf \widetilde{K})(p) \tag{2.5}
\end{equation*}
$$

where

$$
(\inf \tilde{K})(p)=\inf \left\{\widetilde{K}(\Pi) \mid \Pi \text { is a plane section } \subset \mathrm{T}_{\mathrm{p}} \widetilde{\mathrm{M}}\right\}
$$

We note that new optimal inequalities involving the Chen invariant have been recently proved in [24-38] etc.

Let $L^{k}$ be a $k$-plane section of $T_{p} \widetilde{M}$ and $u$ be a unit vector in $L^{k}$. We choose an orthonormal basis $\left\{e_{1}, \ldots, e_{k}\right\}$ of $L^{k}$ such that $e_{1}=u$. The Ricci curvature $\widetilde{\operatorname{Ric}}_{L^{k}}$ of $L^{k}$ at $u$ is defined by

$$
\begin{equation*}
\widetilde{\operatorname{Ric}}_{L^{k}}(u)=\widetilde{K}_{12}+\widetilde{K}_{13}+\cdots+\widetilde{K}_{1 k} \tag{2.6}
\end{equation*}
$$

Here, $\widetilde{\operatorname{Ric}}_{L^{k}}(u)$ is called a $k$-Ricci curvature [39]. Thus for each fixed $e_{i}, i \in\{1, \ldots, k\}$ we get

$$
\begin{equation*}
\widetilde{\operatorname{Ric}}_{L^{k}}\left(e_{i}\right)=\sum_{j \neq i}^{k} \widetilde{K}_{i j} . \tag{2.7}
\end{equation*}
$$

The scalar curvature $\widetilde{\tau}\left(L^{k}\right)$ of the $k$-plane section $L^{k}$ is given by

$$
\begin{equation*}
\widetilde{\tau}\left(L^{k}\right)=\sum_{1 \leq i<j \leq k} \widetilde{K}_{i j} . \tag{2.8}
\end{equation*}
$$

We note that

$$
\begin{equation*}
\widetilde{\tau}\left(L^{k}\right)=\frac{1}{2} \sum_{i=1}^{k} \sum_{j \neq i}^{k} \widetilde{K}_{i j}=\frac{1}{2} \sum_{i=1}^{n} \widetilde{\operatorname{Ric}}_{L^{k}}\left(e_{i}\right) . \tag{2.9}
\end{equation*}
$$

Let $M$ be an $n$-dimensional submanifold in a manifold $\tilde{M}$ equipped with a Riemannian metric $\widetilde{g}$. The Gauss and Weingarten formulas are given by

$$
\tilde{\nabla}_{X} Y=\nabla_{X} Y+\sigma(X, Y)
$$

and

$$
\tilde{\nabla}_{X} N=-A_{N} X+\nabla \frac{\perp}{X} N
$$

for all $X, Y \in T M$ and $N \in T^{\perp} M$, where $\tilde{\nabla}, \nabla$ and $\nabla_{\tilde{N}}^{\perp}$ are the Riemannian, the induced Riemannian and the induced normal connections in $\tilde{M}, M$ and the normal bundle $T^{\perp} M$ of $M$, respectively, and $\sigma$ is the second fundamental form related to the shape operator $A$ by

$$
\widetilde{g}(\sigma(X, Y), N)=\widetilde{g}\left(A_{N} X, Y\right)
$$

The equation of Gauss is given by

$$
\begin{align*}
\tilde{R}(X, Y, Z, W)= & R(X, Y, Z, W)-\widetilde{g}(\sigma(X, W), \sigma(Y, Z)) \\
& +\widetilde{g}(\sigma(X, Z), \sigma(Y, W)) \tag{2.10}
\end{align*}
$$

for all $X, Y, Z, W \in T M$, where $\widetilde{R}$ and $R$ are the curvature tensors of $\widetilde{M}$ and $M$, respectively.

For any orthonormal basis $\left\{e_{1}, \ldots, e_{n}\right\}$ of the tangent space $T_{p} M$, the mean curvature vector $\hbar(p)$ is given by

$$
\begin{equation*}
\hbar(p)=\frac{1}{n} \sum_{i=1}^{n} \sigma\left(e_{i}, e_{i}\right) \tag{2.11}
\end{equation*}
$$

The submanifold $M$ is called totally geodesic in $\tilde{M}$ if $\sigma=0$ and it is called minimal if $\hbar=0$. If $\sigma(X, Y)=g(X, Y) \hbar$ for all $X, Y \in T M$, then the submanifold $M$ is called totally umbilical [40].

## 3. Bochner Kaehler Manifolds

Let $\widetilde{M}$ be an almost Hermitian manifold with complex structure $J$ and Riemannian metric $\widetilde{g}$. If the almost complex structure $J$ satisfies

$$
\begin{equation*}
\left(\widetilde{\nabla}_{X} J\right) Y+\left(\widetilde{\nabla}_{Y} J\right) X=0 \tag{3.1}
\end{equation*}
$$

for any vector fields $X$ and $Y$ on $T \widetilde{M}$, then the manifold is called a nearly Kaehlerian manifold, if

$$
\begin{equation*}
\widetilde{\nabla}_{X} J=0 \tag{3.2}
\end{equation*}
$$

for all $X$ vectors on $T \widetilde{M}$, then the manifold is called a Kaehlerian manifold [41].

Let $\widetilde{M}$ be an $m$ complex dimensional Kaehlerian manifold. Then the Bochner curvature tensor, defined in [2], is given by

$$
\begin{align*}
\widetilde{B}(X, Y, Z, W)= & \widetilde{R}(X, Y, Z, W)-\langle X, W\rangle L(Y, Z)+\langle Y, W\rangle L(X, Z) \\
& -\langle Y, Z\rangle L(X, W)+\langle X, Z\rangle L(Y, W)-\langle J X, W\rangle M(Y, Z) \\
& +\langle J Y, W\rangle M(X, Z)-\langle J Y, Z\rangle M(X, W)+\langle J X, Z\rangle M(Y, W) \\
& +2\langle J Z, W\rangle M(X, Y)+2\langle J X, Y\rangle M(Z, W) \tag{3.3}
\end{align*}
$$

where

$$
\begin{gather*}
L(Y, Z)=\frac{1}{2(m+2)} \widetilde{\operatorname{Ric}}(Y, Z)-\frac{\widetilde{\tau}}{4(m+1)(m+2)}\langle Y, Z\rangle,  \tag{3.4}\\
L(Y, Z)=L(Z, Y), \quad L(J Y, J Z)=L(Y, Z), \quad L(J Y, Z)=-L(Y, J Z),  \tag{3.5}\\
M(Y, Z)=-L(Y, J Z)=-L(J Z, Y) \tag{3.6}
\end{gather*}
$$

for any $X, Y, Z, W \in T \widetilde{M}$. The manifold $\widetilde{M}$ is called a Bochner Kaehler manifold if the tensor $B$ vanishes identically.

Let $\Pi=\operatorname{Span}\{X, Y\}, X, Y \in T_{p} \widetilde{M}$, be a 2-dimensional plane section on $T_{p} \widetilde{M}$. The plane $\Pi$ is called anti-holomorphic if

$$
\begin{equation*}
\widetilde{g}(X, Y)=\widetilde{g}(J X, Y)=0, \tag{3.7}
\end{equation*}
$$

in other words, $J \Pi \subset \Pi^{\perp}$, where $\Pi^{\perp}$ is complementary space of $\Pi$ in $T \widetilde{M}$. Furthermore, the plane $\Pi$ is called holomorphic if $J \Pi \subset \Pi$. In this case, the holomorphic sectional curvature is given by

$$
\begin{equation*}
\widetilde{H}(\Pi)=\widetilde{H}(X)=\widetilde{R}(X, J X, J X, X), \tag{3.8}
\end{equation*}
$$

where $\Pi=\operatorname{Span}\{X, J X\}, X$ is a unit vector on $\Pi$.
If $\Pi$ and $\Pi^{\prime}$ are two holomorphic plane sections in $T_{p} \widetilde{M}$, then the holomorphic bisectional curvature $\widetilde{H}\left(\Pi, \Pi^{\prime}\right)$ is defined by

$$
\begin{equation*}
\widetilde{H}\left(\Pi, \Pi^{\prime}\right)=\widetilde{H}(X, Y)=\widetilde{R}(X, J X, J Y, Y), \tag{3.9}
\end{equation*}
$$

where $X$ is a unit vector on $\Pi$ and $Y$ is a unit vector on $\Pi^{\prime}$ [42].
On the other hand, if $\Pi \perp \Pi^{\prime}$, then $\widetilde{H}(X, Y)$ is called totally real bisectional curvature and

$$
\begin{equation*}
\widetilde{H}(X, Y)=\widetilde{K}(X, Y)+\widetilde{K}(X, J Y) \tag{3.10}
\end{equation*}
$$

for a totally real plane spanned by any vector pair $\{X, Y\}$ [22].
We now recall the following important facts.
Theorem 3.1. [22] Let $\widetilde{M}$ be a complex dimensional Kaehlerian manifold of complex dimension $m>1$. Then $\widetilde{M}$ is Bochner-Kaehler manifold if and only if every totally real bisectional curvature $\widetilde{H}(X, Y)$ depends only on the totally real plane section spanned by $X, Y$ but it does not depend on the choice of orthonormal basis $X, Y$.

Theorem 3.2. [12] Let $\widetilde{M}$ be a Kaehler manifold of complex dimension $m>1$. Then $\widetilde{M}$ is a Bochner-Kaehler manifold if and only if there is a Hermitian quadratic form $Q$ on $\widetilde{M}$ such that the holomorphic sectional curvature $\widetilde{H}(X)$ of the holomorphic plane spanned by $X$ and $J X$ satisfies $\widetilde{H}(X)=Q(X, X)$ for any unit tangent vector $X$. Furthermore, if such $Q$ exists, then

$$
\begin{equation*}
Q=\frac{4}{(m+2)} \widetilde{\operatorname{Ric}}-\frac{2 \tau}{(m+1)(m+2)} \widetilde{g} \tag{3.11}
\end{equation*}
$$

Let $\widetilde{M}$ be an $m$ complex dimensional Bochner Kaehler manifold and $\left\{e_{1}, \ldots, e_{n}, J e_{1}, \ldots, J e_{n}\right\}$ be an orthonormal basis of $T_{p} \widetilde{M}$ at $p \in M$. Then the scalar curvature $\widetilde{\tau}(p)$ is given by

$$
\begin{equation*}
\widetilde{\tau}(p)=\sum_{i=1}^{n} \widetilde{H}\left(e_{i}\right)+2 \sum_{i<j} \widetilde{H}\left(e_{i}, e_{j}\right) . \tag{3.12}
\end{equation*}
$$

If $L$ is a complex subspace of real dimension $r \geq 2$ in $T_{p} \widetilde{M}$, the $r$-scalar curvature $\widetilde{\tau}(L)$ of $L$ is defined as

$$
\begin{equation*}
\widetilde{\tau}(L)=\sum_{i=1}^{r} \widetilde{H}\left(e_{i}\right)+2 \sum_{i<j}^{r} \widetilde{H}\left(e_{i}, e_{j}\right) . \tag{3.13}
\end{equation*}
$$

From (3.3), (3.5), (3.6), (3.9) and (3.10), we get the following lemma:
Lemma 3.3. Let $\widetilde{M}$ be an $m$ complex dimensional Bochner Kaehler manifold. Then

$$
\begin{align*}
\widetilde{H}(X) & =2\langle X, X\rangle L(X, X)  \tag{3.14}\\
\widetilde{H}(X, Y) & =2(\langle Y, Y\rangle M(X, J X)-\langle X, X\rangle M(J Y, Y)) \\
& =2(\langle Y, Y\rangle L(X, X)+\langle X, X\rangle L(Y, Y)) \tag{3.15}
\end{align*}
$$

for a totally real plane spanned by any vector pair $\{X, Y\}$.
Taking into consider (3.4) equation and Lemma 3.3, we get the following proposition:
Proposition 3.4. Let $\widetilde{M}$ be an $m$ complex dimensional Bochner Kaehler manifold. Then we have

$$
\begin{gather*}
\widetilde{H}(X)=\frac{1}{(m+2)} \widetilde{\operatorname{Ric}}(X)-\frac{\widetilde{\tau}(p)}{2(m+1)(m+2)},  \tag{3.16}\\
\left.\widetilde{H}(X, Y)=\frac{1}{(m+2)} \widetilde{\operatorname{Ric}}(X)+\widetilde{\operatorname{Ric}}(Y)\right]-\frac{\widetilde{\tau}(p)}{2(m+1)(m+2)} \tag{3.17}
\end{gather*}
$$

for a totally real plane spanned by any vector pair $\{X, Y\}$.

## 4. Submanifolds of a Bochner Kaehler Manifold

Let $M$ be an $n$-dimensional submanifold of an almost Hermitian manifold $(\widetilde{M}, J, \widetilde{g})$. For any $X \in T_{p} M$, we decompose $J X$ into tangential and normal parts given by

$$
\begin{equation*}
J X=P X+F X, \quad P X \in T_{p} M, F X \in T_{p}^{\perp} M \tag{4.1}
\end{equation*}
$$

thus $P X$ is the tangential part of $J X$ while $F X$ is the normal part of $J X$. The squared norm of $P$ at $p \in M$ is defined to be

$$
\begin{equation*}
\|P\|^{2}=\sum_{i, j=1}^{n}\left\langle P e_{i}, e_{j}\right\rangle^{2} \tag{4.2}
\end{equation*}
$$

where $\left\{e_{1}, \ldots, e_{n}\right\}$ is any orthonormal basis of the tangent space $T_{p} M$.
In an almost Hermitian manifold, its almost complex structure $J$ transforms a vector into a vector perpendicular to it. According to the behavior of the tangent bundle of a submanifold under the action of the almost complex structure $J$ of the ambient manifold, there are two well-known classes of submanifolds, namely, invariant submanifolds and anti-invariant submanifolds.

Let $M$ be a submanifold of an almost Hermitian manifold $(\widetilde{M}, J, \widetilde{g})$. The tangent space of the submanifold remains invariant under the action of the almost complex structure $J$ where as in the second case it is mapped into the normal space. Thus, $M$ is invariant if $F=0$, and it is anti-invariant if $P=0$ [41].

In 1978, A. Bejancu [43] generalized the concept of invariant and anti-invariant submanifolds in to a $C R$-submanifold as follows.

A submanifold $M$ of an almost Hermitian manifold is called a $C R$-submanifold if the tangent bundle $T M$ of $M$ can be decomposed as the direct sum of a holomorphic (invariant) distribution and a totally real (anti-invariant) distribution, that is,

$$
T M=D \oplus D^{\perp}
$$

where $J(D)=D$ and $J\left(D^{\perp}\right) \subset T M^{\perp}$. In fact, we have $D=\operatorname{ker}(F)$ and $D^{\perp}=\operatorname{ker}(P)$. Invariant and anti-invariant submanifolds are $C R$-submanifolds with $D=\{0\}$ and $D^{\perp}=$ $\{0\}$, respectively.

Let $M$ be an $n$-dimensional CR-submanifold of an $m$ complex dimensional Bochner Kaehler manifold and $\left\{e_{1}, \ldots, e_{s}, e_{s+1}, \ldots, e_{n}\right\}$ be an orthonormal basis of $T_{p} M$ such that the invariant distribution of $T_{p} M$ is spanned by the vectors $e_{1}, \ldots, e_{s}$ and the antiinvariant distribution of $T_{p} M$ is spanned by the vectors $e_{s+1}, \ldots, e_{n}$. Let us define

$$
\begin{equation*}
\hbar_{D}(p)=\frac{1}{s} \sum_{i=1}^{s} \sigma\left(e_{i}, e_{i}\right) \text { and } \hbar_{D^{\perp}}(p)=\frac{1}{n-s} \sum_{j=s+1}^{n} \sigma\left(e_{j}, e_{j}\right) . \tag{4.3}
\end{equation*}
$$

The submanifold $M$ is called $D$-minimal if $\hbar_{D}=0$, called $D^{\perp}$-minimal if $\hbar_{D^{\perp}}=0$ for all point of $M$ [16].

Theorem 4.1. Let $(M, g)$ be an n-dimensional invariant submanifold of an $m$ complex dimensional Bochner Kaehler manifold ( $\widetilde{M}, \widetilde{g}$ ). For all mutually orthogonal unit vectors $X, Y \in T M$, we have

$$
\begin{align*}
K(X, Y)= & \frac{3}{(m+2)} \widetilde{\operatorname{Ric}}(J X, Y)-\frac{3 \widetilde{\tau}(p)}{2(m+1)(m+2)}-\|\sigma(X, Y)\|^{2} \\
& +g(\sigma(X, X), \sigma(Y, Y))+\frac{1}{2}(\widetilde{H}(X)+\widetilde{H}(Y)) \tag{4.4}
\end{align*}
$$

where $\sigma$ is the second fundamental form is given in the Gauss and Weingarten formulas.

Proof. Let $\left\{e_{1}, \ldots, e_{m}, J e_{1}, \ldots, J e_{m}\right\}$ be an orthonormal basis of $T_{p} \widetilde{M}$. By doing straightforward computation in (3.3), we get

$$
\begin{equation*}
\widetilde{K}\left(e_{i}, e_{j}\right)=L\left(e_{i}, e_{i}\right)+L\left(e_{j}, e_{j}\right)+6\left\langle J e_{i}, e_{j}\right\rangle L\left(J e_{i}, e_{j}\right) \tag{4.5}
\end{equation*}
$$

If we put (3.14) in (4.5), we have

$$
\begin{equation*}
\widetilde{K}\left(e_{i}, e_{j}\right)=\frac{1}{2}\left(\widetilde{H}\left(e_{i}\right)+\widetilde{H}\left(e_{j}\right)\right)+6\left\langle J e_{i}, e_{j}\right\rangle L\left(J e_{i}, e_{j}\right), \tag{4.6}
\end{equation*}
$$

for $i \neq j \in\{1, \ldots, m\}$. Using (2.10), (3.4) and (4.6) equalities, we get

$$
\begin{align*}
K\left(e_{i}, e_{j}\right)= & \frac{3}{(m+2)} \widetilde{\operatorname{Ric}}\left(J e_{i}, e_{j}\right)-\frac{3 \widetilde{\tau}(p)}{2(m+1)(m+2)}+\widetilde{g}\left(\sigma\left(e_{i}, e_{i}\right), \sigma\left(e_{j}, e_{j}\right)\right) \\
& -\left\|\sigma\left(e_{i}, e_{j}\right)\right\|^{2} \tag{4.7}
\end{align*}
$$

Finally, putting $e_{i}=X$ and $e_{j}=Y$, we have (4.4).

We recall now the following theorem of B.-Y. Chen in [44] for future uses.
Theorem 4.2. Let $M$ be an $n$-dimensional $(n \geq 3)$ submanifold in a real space form $R(c)$ of constant sectional curvature $c$. Then, for each point $p \in M$ we have

$$
\begin{equation*}
\delta(2) \leq \frac{n^{2}(n-2)}{2(n-1)}\|\hbar(p)\|^{2}+\frac{1}{2}(n+1)(n-2) c . \tag{4.8}
\end{equation*}
$$

The equality in (4.8) holds at $p \in M$ if and only if there exist an orthonormal basis $\left\{e_{1}, \ldots, e_{n}\right\}$ of $T_{p} M$ and an orthonormal basis $\left\{e_{n+1}, \ldots, e_{m}\right\}$ of $T_{p}^{\perp} M$ such that (a) $\Pi=\operatorname{Span}\left\{e_{1}, e_{2}\right\}$ and (b) the forms of shape operators $A_{e_{r}}, r=n+1, \ldots, m$, become

$$
\begin{align*}
& A_{e_{n+1}}=\left(\begin{array}{ccc}
a & 0 & 0 \\
0 & b & 0 \\
0 & 0 & \mu I_{n-2}
\end{array}\right), \quad \mu=a+b,  \tag{4.9}\\
& A_{e_{r}}=\left(\begin{array}{ccc}
c_{r} & d_{r} & 0 \\
d_{r} & -c_{r} & 0 \\
0 & 0 & 0_{n-2}
\end{array}\right), \quad r \in\{n+2, \ldots, m\} . \tag{4.10}
\end{align*}
$$

Next, we give a generalization of Theorem 4.2 in terms of the Chen's invariant in submanifolds of any Riemannian manifold. We note that the following theorem is a special case of Theorem 3.1 in [45] of B.-Y. Chen:

Theorem 4.3. Let $M$ be an n-dimensional $(n \geq 3)$ submanifold in an m-dimensional Riemannian manifold $\widetilde{M}$. Then, for each point $p \in M$ and each plane section $\Pi \subset T_{p} M$, we have

$$
\begin{equation*}
\delta(2) \leq \frac{n^{2}(n-2)}{2(n-1)}\|\hbar(p)\|^{2}+\widetilde{\tau}\left(T_{p} M\right)-\widetilde{K}\left(\Pi_{2}\right) . \tag{4.11}
\end{equation*}
$$

The equality in (4.11) holds at $p \in M$ if and only if there exist an orthonormal basis $\left\{e_{1}, \ldots, e_{n}\right\}$ of $T_{p} M$ and an orthonormal basis $\left\{e_{n+1}, \ldots, e_{m}\right\}$ of $T_{p}^{\perp} M$ such that the forms of shape operators $A_{e_{r}}, r=n+1, \ldots, m$, become as (4.9) and (4.10).

Using Theorem 4.1 and Theorem 4.3, we have the following theorem:

Theorem 4.4. Let $(M, g)$ be an invariant submanifold of a Bochner Kaehler manifold $(\widetilde{M}, \widetilde{g})$ and $\Pi=\operatorname{Span}\left\{e_{1}, e_{2}\right\}$ is a 2-dimensional plane section $T_{p} M$. Then we have

$$
\begin{align*}
\tau(p) & \leq \frac{3}{(m+2)} \widetilde{\operatorname{Ric}}(J X, Y)-\frac{3 \widetilde{\tau}(p)}{2(m+1)(m+2)}+\frac{n^{2}(n-2)}{2(n-1)}\|\hbar(p)\|^{2} \\
& +\widetilde{\tau}_{T_{p} M}(p)-\widetilde{K}(\Pi)+4\left\|\left.\hbar\right|_{\Pi}(p)\right\|^{2}+\frac{1}{2}\left(\widetilde{H}\left(e_{1}\right)+\widetilde{H}\left(e_{2}\right)\right) \tag{4.12}
\end{align*}
$$

where

$$
\begin{equation*}
\left\|\left.\hbar\right|_{\Pi}(p)\right\|^{2}=\frac{\widetilde{g}\left(\sigma\left(e_{1}, e_{1}\right), \sigma\left(e_{2}, e_{2}\right)\right)}{4} \tag{4.13}
\end{equation*}
$$

The equality in (4.12) holds at $p \in M$ if and only if the shape operators take the following forms:

$$
\begin{align*}
& A_{e_{n+1}}=\left(\begin{array}{ccc}
a & 0 & 0 \\
0 & b & 0 \\
0 & 0 & \mu I_{n-2}
\end{array}\right), \quad \mu=a+b,  \tag{4.14}\\
& A_{e_{r}}=\left(\begin{array}{ccc}
c_{r} & 0 & 0 \\
0 & -c_{r} & 0 \\
0 & 0 & 0_{n-2}
\end{array}\right), \quad r \in\{n+2, \ldots, m\} . \tag{4.15}
\end{align*}
$$

Now we state the following definition:
Definition 4.5. Let $(M, g)$ be an invariant submanifold of a Bochner Kaehler manifold $(\widetilde{M}, \widetilde{g})$. We call the manifold $M$ as a Bochner-Chen ideal invariant submanifold if the shape operators take the form as (4.14) and (4.15).

Let $(M, g)$ be a Bochner-Chen ideal invariant submanifold of a Bochner Kaehler manifold $(\widetilde{M}, \widetilde{g})$ and $\Pi=\operatorname{Span}\left\{e_{1}, e_{2}\right\}$. Then, from (4.14) and (4.15), we get

$$
\begin{gather*}
K\left(e_{1}, e_{2}\right)=\widetilde{K}\left(e_{1}, e_{2}\right)+a b-\sum_{r=n+2}^{m}\left(c_{r}\right)^{2},  \tag{4.16}\\
K\left(e_{1}, e_{j}\right)=\widetilde{K}\left(e_{1}, e_{j}\right)+a \mu,  \tag{4.17}\\
K\left(e_{2}, e_{j}\right)=\widetilde{K}\left(e_{2}, e_{j}\right)+b \mu,  \tag{4.18}\\
K\left(e_{i}, e_{j}\right)=\widetilde{K}\left(e_{i}, e_{j}\right)+\mu^{2},  \tag{4.19}\\
\operatorname{Ric}\left(e_{1}\right)=\widetilde{\operatorname{Ric}}_{T_{p} M}\left(e_{1}\right)+a b-\sum_{r=n+2}^{m}\left(c_{r}\right)^{2}+(n-2) a \mu^{2},  \tag{4.20}\\
\operatorname{Ric}\left(e_{2}\right)=\widetilde{\operatorname{Ric}}_{T_{p} M}\left(e_{2}\right)+a b-\sum_{r=n+2}^{m}\left(c_{r}\right)^{2}+(n-2) b \mu^{2},  \tag{4.21}\\
\operatorname{Ric}\left(e_{i}\right)=\widetilde{\operatorname{Ric}_{T_{p} M}}\left(e_{i}\right)+(n-2) \mu^{2}, \tag{4.22}
\end{gather*}
$$

where $i, j>2$ and $\widetilde{\operatorname{Ric}}_{T_{p} M}$ is $n$-plane Ricci curvature given in (2.7).
Taking trace in (4.5), we have the following lemma:

Lemma 4.6. Let $(M, g)$ be an n-dimensional submanifold of a Bochner Kaehler manifold $(\widetilde{M}, \widetilde{g})$ and $\left\{e_{1}, \ldots, e_{n}\right\}$ be an orthonormal basis of $T_{p} M$. Then we have

$$
\begin{equation*}
\widetilde{\operatorname{Ric}}_{T_{p} M}\left(e_{j}\right)=\operatorname{trace}\left(\left.L\right|_{M}\right)+(n-2) L\left(e_{j}, e_{j}\right)+6 \sum_{i=1}^{n}\left\langle J e_{i}, e_{j}\right\rangle L\left(e_{i}, e_{j}\right) . \tag{4.23}
\end{equation*}
$$

Taking into consideration (4.20), (4.21) equalities and Lemma 4.6, we get the following theorem:

Theorem 4.7. Let $(M, g)$ be an n-dimensional Bochner-Chen ideal invariant submanifold of Bochner Kaehler manifold $(\widetilde{M}, \widetilde{g})$. If the submanifold $(M, g)$ is Einstein, then there exist a plane section spanned by unit vectors $X, Y$ such that

$$
\begin{equation*}
L(X, X)-L(Y, Y)=b^{2}-a^{2} \tag{4.24}
\end{equation*}
$$

where $a, b$ given in (4.14).
Proof. Let $\Pi=\operatorname{Span}\left\{e_{1}, e_{2}\right\}$ and the submanifold $(M, g)$ be Einstein. Then

$$
\begin{equation*}
\widetilde{\operatorname{Ric}}_{T_{p} M}\left(e_{1}\right)-\widetilde{\operatorname{Ric}}_{T_{p} M}\left(e_{2}\right)=(n-2)\left(b^{2}-a^{2}\right) \tag{4.25}
\end{equation*}
$$

Furthermore, from Lemma 4.6, we have

$$
\begin{equation*}
\widetilde{\operatorname{Ric}}_{T_{p} M}\left(e_{1}\right)-\widetilde{\operatorname{Ric}}_{T_{p} M}\left(e_{2}\right)=(n-2)\left(L\left(e_{1}, e_{1}\right)-L\left(e_{2}, e_{2}\right)\right) . \tag{4.26}
\end{equation*}
$$

Puting $e_{1}=X$ and $e_{2}=Y$, we obtain (4.24).
Lemma 4.8. Let $(M, g)$ be an n-dimensional anti-invariant submanifold of a Bochner Kaehler manifold $(\widetilde{M}, \widetilde{g})$. Then we have

$$
\begin{equation*}
\widetilde{H}(X, Y)=2 \widetilde{K}(X, Y) \tag{4.27}
\end{equation*}
$$

where $X, Y$ are vector fields on $M$ such that $\operatorname{Span}\{X, Y\}$ is an anti-holomorphic plane section.

Theorem 4.9. Let $(M, g)$ be an n-dimensional anti-invariant submanifold of a Bochner Kaehler manifold $(\widetilde{M}, \widetilde{g})$. Then, for each point $p \in M$ and each plane section $\Pi=$ $\operatorname{Span}\left\{e_{1}, e_{2}\right\}$, we have

$$
\begin{equation*}
\tau(p)-K(\Pi) \leq \frac{n^{2}(n-2)}{2(n-1)}\|\hbar(p)\|^{2}+\widetilde{\tau}\left(T_{p} M\right)-\frac{1}{2} \widetilde{H}\left(e_{1}, e_{2}\right) . \tag{4.28}
\end{equation*}
$$

The equality in (4.28) holds at $p \in M$ if and only if there exist an orthonormal basis $\left\{e_{1}, \ldots, e_{n}\right\}$ of $T_{p} M$ and an orthonormal basis $\left\{e_{n+1}, \ldots, e_{m}\right\}$ of $T_{p}^{\perp} M$ such that the forms of shape operators $A_{e_{r}}, r=n+1, \ldots, m$, become

$$
\begin{align*}
& A_{e_{n+1}}=\left(\begin{array}{ccc}
a & 0 & 0 \\
0 & b & 0 \\
0 & 0 & (a+b) I_{n-2}
\end{array}\right),  \tag{4.29}\\
& A_{e_{r}}=\left(\begin{array}{ccc}
c_{r} & d_{r} & 0 \\
d_{r} & -c_{r} & 0 \\
0 & 0 & 0_{n-2}
\end{array}\right), \quad r \in\{n+2, \ldots, m\} . \tag{4.30}
\end{align*}
$$

Definition 4.10. Let $(M, g)$ be an anti invariant submanifold of a Bochner Kaehler manifold $(\widetilde{M}, \widetilde{g})$. We call the submanifold $(M, g)$ as a Bochner-Chen ideal anti invariant submanifold if the shape operators take the form as (4.29) and (4.30).

Let $M$ be an $n$-dimensional CR-submanifold of an $m$-dimensional Bochner Kaehler manifold and $\left\{e_{1}, \ldots, e_{s}, e_{s+1}, \ldots, e_{n}\right\}$ be an orthonormal basis of $T_{p} M$ such that the invariant distribution of $T_{p} M$ is spanned by the vectors $e_{1}, \ldots, e_{s}$ and the anti-invariant distribution of $T_{p} M$ is spanned by the vectors $e_{s+1}, \ldots, e_{n}$. Let $P_{i}: T M \rightarrow D_{i}, i \in\{1,2\}$ be be orthogonal projections. For any mutually orthogonal unit vector fields $X, Y \in T M$, it can be written that

$$
\begin{equation*}
X=P_{1} X+P_{2} X, \quad \text { and } \quad Y=P_{1} Y+P_{2} Y \tag{4.31}
\end{equation*}
$$

Then we have

$$
\begin{aligned}
\widetilde{R}(X, Y, Y, X)= & \widetilde{R}\left(P_{1} X+P_{2} X, P_{1} Y+P_{2} Y, P_{1} Y+P_{2} Y, P_{1} X+P_{2} X\right) \\
= & \widetilde{R}\left(P_{1} X, P_{1} Y, P_{1} Y, P_{1} X\right)+\widetilde{R}\left(P_{1} X, P_{2} Y, P_{1} Y, P_{1} X\right) \\
& +\widetilde{R}\left(P_{1} X, P_{1} Y, P_{2} Y, P_{1} X\right)+\widetilde{R}\left(P_{1} X, P_{2} Y, P_{1} Y, P_{2} X\right) \\
& +\widetilde{R}\left(P_{1} X, P_{1} Y, P_{1} Y, P_{2} X\right)+\widetilde{R}\left(P_{1} X, P_{2} Y, P_{2} Y, P_{1} X\right) \\
& +\widetilde{R}\left(P_{1} X, P_{1} Y, P_{2} Y, P_{2} X\right)+\widetilde{R}\left(P_{1} X, P_{2} Y, P_{2} Y, P_{2} X\right) \\
& +\widetilde{R}\left(P_{2} X, P_{1} Y, P_{1} Y, P_{1} X\right)+\widetilde{R}\left(P_{2} X, P_{1} Y, P_{1} Y, P_{2} X\right) \\
& +\widetilde{R}\left(P_{2} X, P_{1} Y, P_{2} Y, P_{1} X\right)+\widetilde{R}\left(P_{2} X, P_{1} Y, P_{2} Y, P_{2} X\right) \\
& +\widetilde{R}\left(P_{2} X, P_{2} Y, P_{1} Y, P_{1} X\right)+\widetilde{R}\left(P_{2} X, P_{2} Y, P_{1} Y, P_{2} X\right) \\
& +\widetilde{R}\left(P_{2} X, P_{2} Y, P_{2} Y, P_{1} X\right)+\widetilde{R}\left(P_{2} X, P_{2} Y, P_{2} Y, P_{2} X\right) .
\end{aligned}
$$

From (3.3), we obtain the followings:

$$
\begin{aligned}
& \widetilde{R}\left(P_{1} X, P_{1} Y, P_{1} Y, P_{1} X\right)=\left\langle P_{1} X, P_{1} X\right\rangle L\left(P_{1} Y, P_{1} Y\right)+\left\langle P_{1} Y, P_{1} Y\right\rangle L\left(P_{1} X, P_{1} X\right) \\
& +6\left\langle J P_{1} X, P_{1} Y\right\rangle L\left(P_{1} X, P_{1} Y\right), \\
& \widetilde{R}\left(P_{1} X, P_{1} Y, P_{2} Y, P_{1} X\right)=\left\langle P_{1} X, P_{1} X\right\rangle L\left(P_{1} Y, P_{2} Y\right)+3\left\langle J P_{1} X, P_{1} Y\right\rangle L\left(J P_{1} X, P_{2} Y\right), \\
& \widetilde{R}\left(P_{1} X, P_{2} Y, P_{1} Y, P_{2} X\right)=\left\langle J P_{1} X, P_{1} Y\right\rangle L\left(J P_{2} X, P_{2} Y\right), \\
& \widetilde{R}\left(P_{1} X, P_{1} Y, P_{1} Y, P_{2} X\right)=\left\langle P_{1} Y, P_{1} Y\right\rangle L\left(P_{1} X, P_{2} X\right)+3\left\langle J P_{1} X, P_{1} Y\right\rangle L\left(J P_{2} X, P_{1} Y\right), \\
& \widetilde{R}\left(P_{1} X, P_{2} Y, P_{2} Y, P_{1} X\right)=\left\langle P_{1} X, P_{1} X\right\rangle L\left(P_{2} Y, P_{2} Y\right)+\left\langle P_{2} Y, P_{2} Y\right\rangle L\left(P_{1} X, P_{1} X\right), \\
& \widetilde{R}\left(P_{1} X, P_{1} Y, P_{2} Y, P_{2} X\right)=2\left\langle J P_{1} X, P_{1} Y\right\rangle L\left(J P_{2} X, P_{2} Y\right), \\
& \widetilde{R}\left(P_{1} X, P_{2} Y, P_{2} Y, P_{2} X\right)=\left\langle P_{2} Y, P_{2} Y\right\rangle L\left(P_{1} X, P_{2} X\right), \\
& \widetilde{R}\left(P_{2} X, P_{1} Y, P_{1} Y, P_{2} X\right)=\left\langle P_{2} X, P_{2} X\right\rangle L\left(P_{1} Y, P_{1} Y\right)+\left\langle P_{1} Y, P_{1} Y\right\rangle L\left(P_{2} X, P_{2} X\right), \\
& \widetilde{R}\left(P_{2} X, P_{1} Y, P_{2} Y, P_{2} X\right)=\left\langle P_{2} X, P_{2} X\right\rangle L\left(P_{1} Y, P_{2} Y\right), \\
& \widetilde{R}\left(P_{2} X, P_{2} Y, P_{2} Y, P_{2} X\right)=\left\langle P_{2} X, P_{2} X\right\rangle L\left(P_{2} Y, P_{2} Y\right)+\left\langle P_{2} Y, P_{2} Y\right\rangle L\left(P_{2} X, P_{2} X\right) .
\end{aligned}
$$

Let us choose $P_{1} X=\frac{1}{\sqrt{2}} e_{\alpha}, P_{1} Y=\frac{1}{\sqrt{2}} e_{\beta}, P_{2} X=\frac{1}{\sqrt{2}} e_{\gamma}, P_{2} Y=\frac{1}{\sqrt{2}} e_{\omega}$ for any $\alpha, \beta \in\{1, \ldots, s\}$ and $\gamma, \omega \in\{s+1, \ldots, n\}$. Then we have

$$
\begin{align*}
\widetilde{R}(X, Y, Y, X)= & \frac{1}{2}\left[L\left(e_{\alpha}, e_{\alpha}\right)+L\left(e_{\beta}, e_{\beta}\right) L\left(e_{\gamma}, e_{\gamma}\right)+L\left(e_{\omega}, e_{\omega}\right)\right. \\
& \left.+2 L\left(e_{\alpha}, e_{\gamma}\right)+2 L\left(e_{\beta}, e_{\omega}\right)\right]+6\left\langle J e_{\alpha}, e_{\beta}\right\rangle\left(L\left(J e_{\alpha}, e_{\beta}\right)\right. \\
& \left.+L\left(J e_{\alpha}, e_{\omega}\right)+L\left(J e_{\gamma}, e_{\omega}\right)+L\left(J e_{\gamma}, e_{\beta}\right)\right) . \tag{4.32}
\end{align*}
$$

Using the equation of Gauss, (3.4) and (4.32), we state the following lemma:
Lemma 4.11. Let $M$ be an n-dimensional CR-submanifold of an $m$ complex dimensional Bochner Kaehler manifold. For any mutually orthogonal unit vectors $X, Y \in T_{p} M$ and $\Pi=\operatorname{Span}\{X, Y\}$, we have

$$
\begin{align*}
\widetilde{K}(\Pi)= & \frac{1}{(m+2)}\left[\widetilde{\operatorname{Ric}}\left(P_{1} X\right)+\widetilde{\operatorname{Ric}}\left(P_{2} X\right)+\widetilde{\operatorname{Ric}}\left(P_{1} Y\right)+\widetilde{\operatorname{Ric}}\left(P_{2} Y\right)\right. \\
& \left.2 \widetilde{\operatorname{Ric}}\left(P_{1} X, P_{2} X\right)+2 \widetilde{\operatorname{Ric}}\left(P_{1} Y, P_{2} Y\right)\right]+\frac{3}{(m+2)}\left\langle J P_{1} X, P_{1} Y\right\rangle \\
& \left(\widetilde{\operatorname{Ric}}\left(J P_{1} X, P_{1} Y\right)+\widetilde{\operatorname{Ric}}\left(J P_{1} X, P_{2} Y\right)+\widetilde{\operatorname{Ric}}\left(J P_{2} X, P_{1} Y\right)\right. \\
& \left.+\widetilde{\operatorname{Ric}}\left(J P_{2} X, P_{2} Y\right)\right)-\frac{2 \widetilde{\tau}(p)}{(m+1)(m+2)} . \tag{4.33}
\end{align*}
$$

From Lemma 4.11, we get the following theorems:
Theorem 4.12. Let $M$ be an $n$-dimensional $C R$-submanifold of an $m$ complex dimensional Bochner Kaehler manifold.
i) If $\Pi=\operatorname{Span}\{X, Y\}$ is a plane section in $\Gamma(D)$, then

$$
\begin{equation*}
\widetilde{K}(\Pi)=\frac{1}{(m+2)}\left[\widetilde{\operatorname{Ric}}(X)+\widetilde{\operatorname{Ric}}(Y)+3\langle J X, Y\rangle \widetilde{\operatorname{Ric}}(X, Y)-\frac{\widetilde{\tau}(p)}{2(m+1)}\right] . \tag{4.34}
\end{equation*}
$$

ii) If $\Pi=\operatorname{Span}\{X, Y\}$ is a plane section in $\Gamma\left(D^{\perp}\right)$, then

$$
\begin{equation*}
\widetilde{K}(\Pi)=\frac{1}{(m+2)}\left[\widetilde{\operatorname{Ric}}(X)+\widetilde{\operatorname{Ric}}(Y)-\frac{\widetilde{\tau}(p)}{2(m+1)(m+2)}\right] . \tag{4.35}
\end{equation*}
$$

Theorem 4.13. Let $M$ be an n-dimensional CR-submanifold of an $m$ complex dimensional Bochner Kaehler manifold. Then, for each point $p \in M$ and each plane section $\Pi=\operatorname{Span}\{X, Y\}$ of $T M$, we have

$$
\begin{align*}
\tau(p)-K(\Pi) \leq & \frac{n^{2}(n-2)}{2(n-1)}\|\hbar(p)\|^{2}+\left(1+\frac{1}{(m+1)(m+2)}\right) \widetilde{\tau}(p) \\
& -\frac{1}{(m+2)}\left[\widetilde{\operatorname{Ric}}\left(P_{1} X\right)+\widetilde{\operatorname{Ric}}\left(P_{2} X\right)+\widetilde{\operatorname{Ric}}\left(P_{1} Y\right)+\widetilde{\operatorname{Ric}}\left(P_{2} Y\right)\right. \\
& \left.+2 \widetilde{\operatorname{Ric}}\left(P_{1} X, P_{2} X\right)+2 \widetilde{\operatorname{Ric}}\left(P_{1} Y, P_{2} Y\right)\right]-\frac{3}{(m+2)}\left\langle J P_{1} X, P_{1} Y\right\rangle \\
& \left(\widetilde{\operatorname{Ric}}\left(J P_{1} X, P_{1} Y\right)+\widetilde{\operatorname{Ric}}\left(J P_{1} X, P_{2} Y\right)+\widetilde{\operatorname{Ric}}\left(J P_{2} X, P_{1} Y\right)\right. \\
& \left.+\widetilde{\operatorname{Ric}}\left(J P_{2} X, P_{2} Y\right)\right) . \tag{4.36}
\end{align*}
$$

The equality in (4.36) holds at $p \in M$ if and only if the forms of shape operators $A_{e_{r}}$, $r=n+1, \ldots, m$, become as (4.9) and (4.10).

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